Fuji Electric

Innovating Energy Technology

High Performance Multifunctional Inverters

FRENIC-MEGA (G2) Series

New Standard

FRENIC-MEGA

With the flexibility and functionality to support a wide range of applications on all types of mechanical equipment, the FRENIC-MEGA takes core capability, responsiveness, environmental awareness, and easy maintenance to the next level.

CE c UL us LISTED

24A1-E-0166b

The Industry's Best Just Got Better

Inherits the excellent performance specifications and functionality of the G1 Series while providing a more stylish design.
Unrelenting pursuit of performance and functionality to further enhance adaptability.
It is time to experience the fullness of the MEGA Series world.

High basic performance

Supports vector control, sensorless vector control, dynamic torque vector control, and V/f control.

Various applications

Comes with feature-rich functionality and enhances compatibility with system networks.

FRENIC-MEGA

G2

SERIES

Easy maintenance

Enhances work efficiency through simplified wiring and configuration and ensures safety and security through standard features such as preventive and predictive maintenance functions.

Environmentally resistant

Globally compliant lineup compatible with adverse atmospheres and various safety standards.

CONTENTS

Features

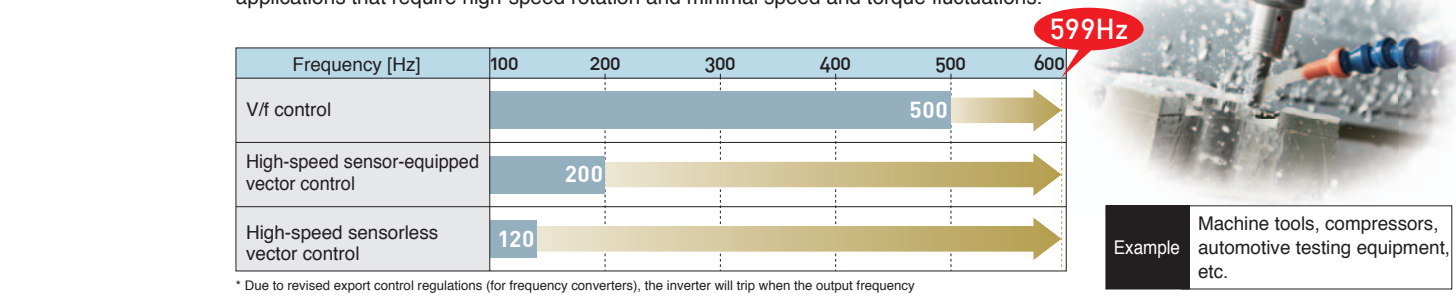
High basic performance

Supports vector control, sensorless vector control, dynamic torque vector control, and V/f control.

01 Faster operating speeds Expanded range

HIGH BASIC PERFORMANCE

Increases the maximum output frequency of all control systems to 599 Hz and supports applications that require high-speed rotation and minimal speed and torque fluctuations.



* Due to revised export control regulations (for frequency converters), the inverter will trip when the output frequency exceeds the upper limit of 599 Hz.

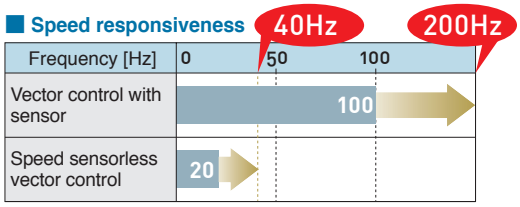
Example: Machine tools, compressors, automotive testing equipment, etc.

02 Enhanced response Improved speed and current

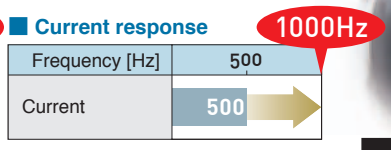
HIGH BASIC PERFORMANCE

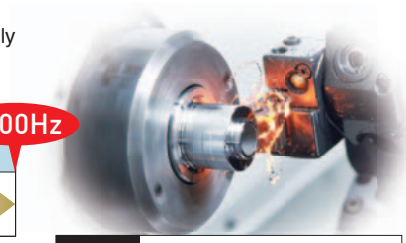
Improves speed and current responsiveness and stabilizes product quality by substantially reducing torque ripple and rotation irregularities.

■ Speed responsiveness



■ Current response





Example: Wire drawing machines, metal processing machines, printing machines, etc.

03 Enhanced torque Improves the speed control range

HIGH BASIC PERFORMANCE

Stabilizes torque at low speeds and increases the accuracy of machine operations through its improved speed control range.

■ Speed control range

Induction motor	During sensor-equipped V/f control	Minimum speed	1:20	Base speed
		Constant torque region	1:2	Constant output region
	During sensor-equipped Dynamic torque vector control	Minimum speed	1:200	Base speed
		Constant torque region	1:2	Constant output region
	During sensorless vector control	Minimum speed	1:200	Base speed
		Constant torque region	1:2	Constant output region
	During sensor-equipped vector control	Minimum speed	1:1500	Base speed
		Constant torque region	1:16	Constant output region
Synchronous motors	During sensorless vector control	Minimum speed	1:10	Base speed
	During sensor-equipped vector control	Minimum speed	1:1500	Base speed

Example: Conveyance machinery, press machines, etc.

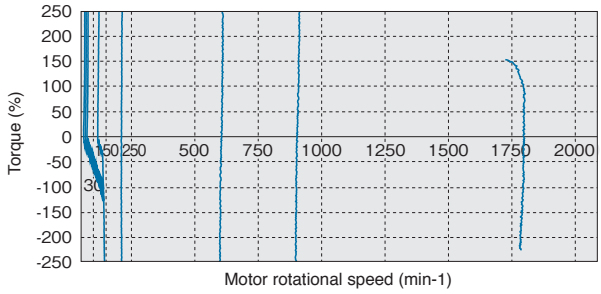
04 Advanced dynamic torque vector control

HIGH BASIC PERFORMANCE

Enhances our proprietary dynamic torque vector control with new motor constant tuning (that takes into account the voltage of the main circuit) and newly designed magnetic flux observer.

Low-speed frequency 0.3 Hz → starting torque 200%

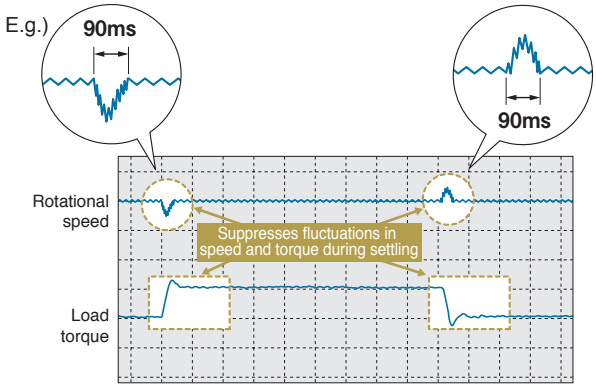
Example of torque characteristics (typical unit: 22 kW)



05 Strengthens ability to handle impact loads

HIGH BASIC PERFORMANCE

Achieves its class's highest level of torque responsiveness to sudden load changes.
Minimizes fluctuations in motor rotational speed and suppresses vibration via magnetic flux control.

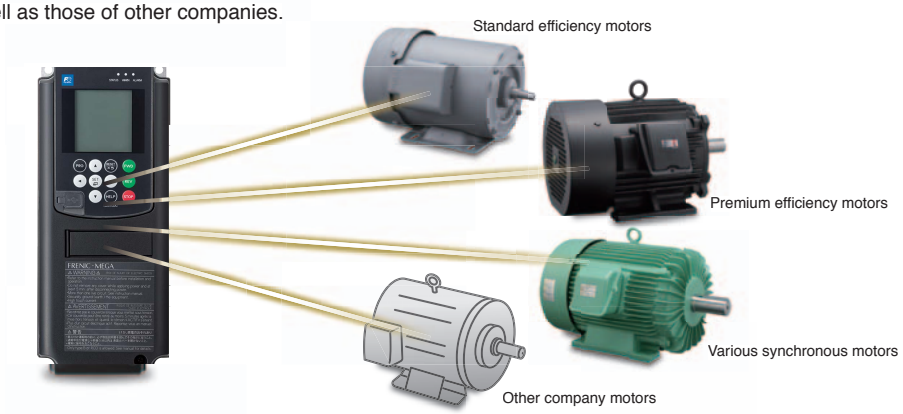


06 Can be used with any motor

HIGH BASIC PERFORMANCE

Comes with new auto-tuning features that enable multi-drive operation using our induction and synchronous motors as well as those of other companies.

* The G2 Series can replace conventional FRENIC-MEGA_GX1S Series products (synchronous motor drive types only).



07 Expansion of standard applied motor capacity for the HND specification Expansion

HIGH BASIC PERFORMANCE

We expanded the rated current and standard applied motor capacity (HND specification) for general loads, making it an easy replacement for our FRENIC-Eco Series (for fans and pumps).

[400 V Series]

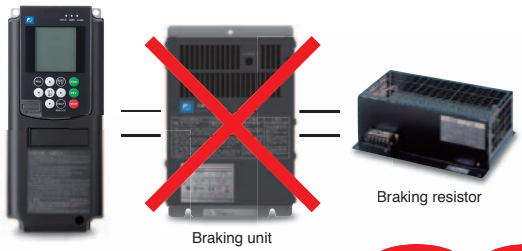
Type (FRN□□□G2S/E-4J)		75	90	110	132	160	200	220
New HND specification	Standard applied motor capacity [kW]	110	132	160	200	220	280	315
	Rated current [A]	217	261	290	361	415	547	610

Old HND specification	Standard applied motor capacity [kW]	90	110	132	160	200	220	280
	Rated current [A]	180	216	260	325	377	432	520

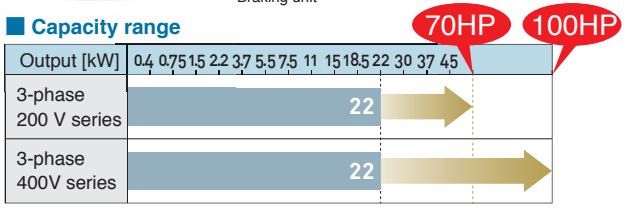
08 Expands the capacity of the built-in braking transistor type Enhancement

HIGH BASIC PERFORMANCE

Comes standard with a larger capacity range and contributes to control panel space and cost savings.



Capacity range



Features

Various applications

Comes with feature-rich functionality and enhances compatibility with system networks.

01 Positioning

VARIOUS APPLICATIONS

Contributes to shortening machine tact time through high-precision positioning control for pulse string input and feedback output instructions.

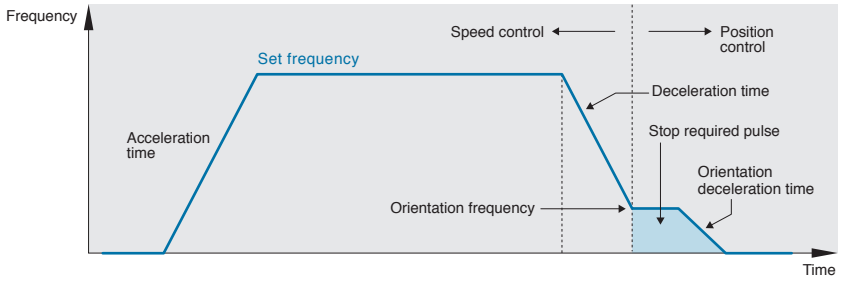
Main features

- Eight positioning data points
- Pulse train instruction
- Origin return function
- Overtravel detection function
- Position preset function

02 Orientation

VARIOUS APPLICATIONS

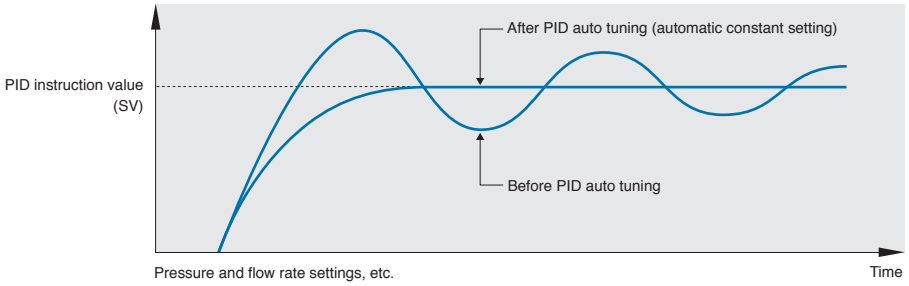
Capable of rotator positioning, enabling machinery to be held in place via servo locking after stoppage.



03 PID auto tuning

VARIOUS APPLICATIONS

Simplifies optimization via automatic adjustment of proportional and integral gains, resulting in shorter system start-up times.



04 Load limiter

VARIOUS APPLICATIONS

Improves system reliability by stopping when excessive torque is detected and by allowing operation only in the direction opposite to that in which the excessive load was detected.

05 Load adaptive control

VARIOUS APPLICATIONS

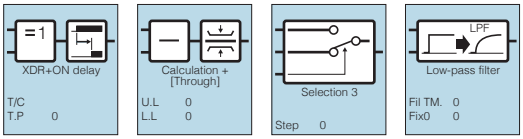
When the actual load level is lower than the configured load level, the system can be operated at a ratio-multiplied frequency, resulting in significantly better efficiency.

06 Customizable logic functions Enhancement

VARIOUS APPLICATIONS

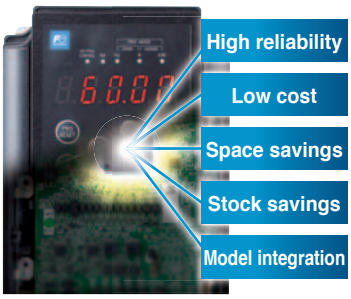
Customizable inverter functions to meet your own specific needs.
Requires no PLC or external control equipment (relays, timers, etc.) circuits, and can be configured simply by setting and combining various parameters inside the inverter.

Comes with a wide variety of logic symbols and programming steps

Item	FRENIC-MEGA
Logic symbol type (Logical operations, counters, timers, arithmetic operations, comparators, limiters, selectors, holders, etc.)	Total of 58 digital & analog types  Digital operations / Analog operations / Selector / Filter
Number of programming steps	260 steps

* The programming tool software can be downloaded for free from our website.

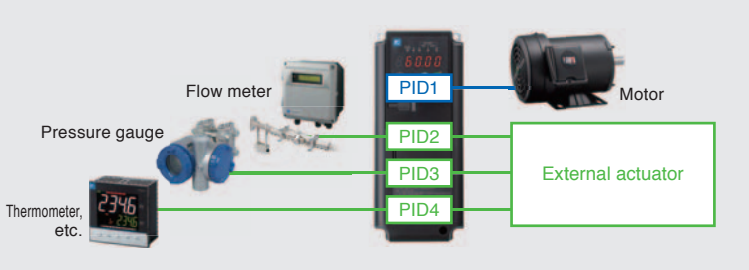
Advantages



07 PID Control (with 4 PIDs) NEW

VARIOUS APPLICATIONS

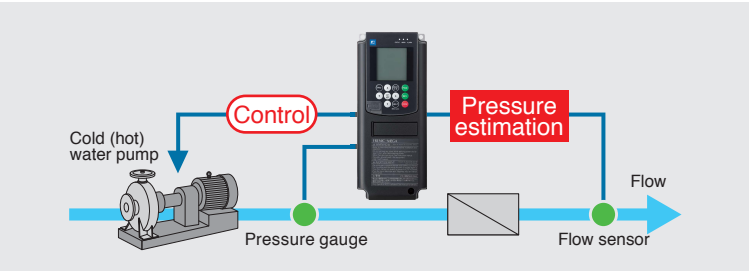
Allows switching between two types of process commands and feedback values. PID control function that is easy to adjust using an anti-reset windup function to prevent overshoot of PID control and PID output limiter and integral hold/reset signal.
In addition, up to three external actuators can be controlled simultaneously with motor PID control, eliminating the need for a PLC and contributing to system cost reductions.



08 Linearize

VARIOUS APPLICATIONS

By controlling the pumping pressure at an appropriate value based on the flow rate and target end pressure, it maintains the discharge pressure and reduces wasteful power consumption, contributing to energy-saving effects.



09 Cascade operation NEW

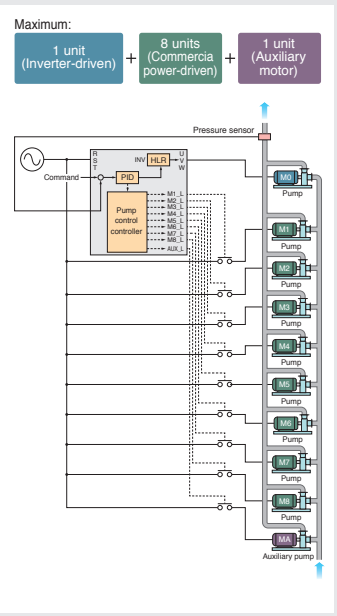
VARIOUS APPLICATIONS

Function to control multiple pumps with one inverter. Control by combining inverter-driven and commercial power-driven operation. The flow and pressure sensor signals are controlled by the PID controller built-in the inverter, and each pump is driven by commercial power or the inverter using switching signals from the inverter.
As a result, when the discharge flow rate is low, only inverter-driven operation is used, and when the discharge flow rate is high, commercial power-driven operation is used in addition to inverter-driven operation to ensure the necessary total discharge flow rate.

Inverter-driven motor fixed system

FIXED

It consists of a combination of a inverter-driven motor (M0), commercial power-driven motors (M1 to M8), and an auxiliary motor (MA). The inverter-driven motor is fixed to motor M0. When the desired discharge flow rate is not achieved with only motor M0, control is performed by sequentially adding commercial power-driven motors.

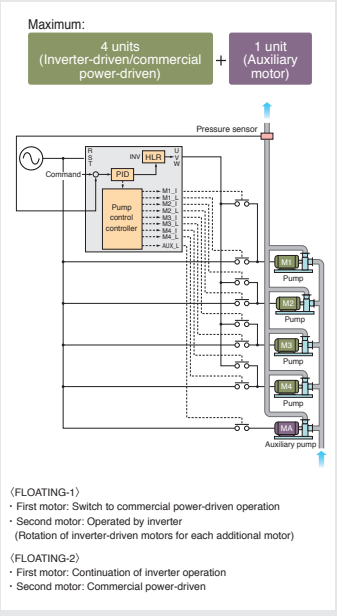


*When using the optional relay output card (OPC-RY2)

Inverter-driven motor circulation system

FLOATING

It consists of a combination of motors (M1 to M4) that can switch between inverter-driven and commercial power-driven operation, and an auxiliary motor (MA) that is driven by commercial power. Variable speed control using inverter-driven operation at startup. If the desired discharge flow rate is not achieved with only the first motor, the operation of FLOATING-1 or FLOATING-2 can be selected.

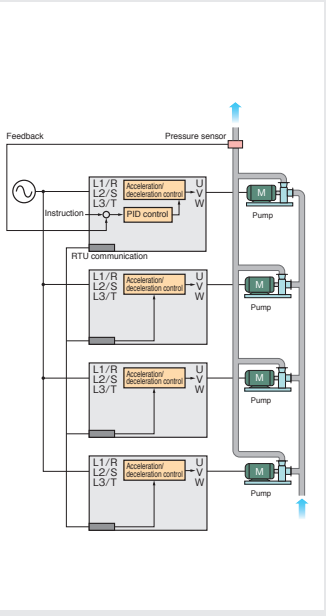


〈FLOATING-1〉
・First motor: Switch to commercial power-driven operation
・Second motor: Operated by inverter
(Rotation of inverter-driven motors for each additional motor)

〈FLOATING-2〉
・First motor: Continuation of inverter operation
・Second motor: Commercial power-driven

Communication link method: Rotary operation

Each inverter is connected via a communication link, eliminating the need for a controller when building systems. In addition, the communication link reduces wiring without requiring any additional options.

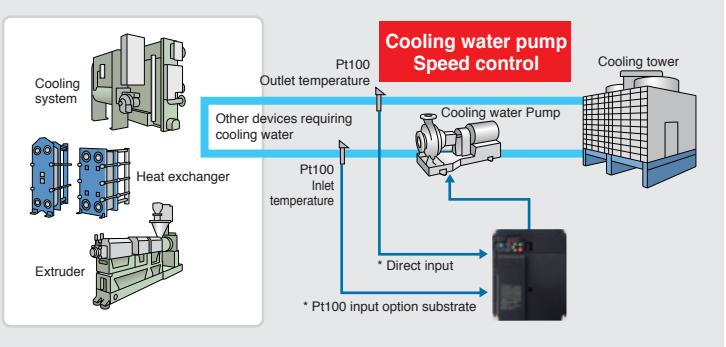


10 Constant control of temperature and pressure differences

VARIOUS APPLICATIONS

Reduces wasteful power consumption by lowering fan output when it is difficult to lower internal temperatures due to environmental factors such as the outdoor air temperature being higher than that of the cooling water. Temperature can be detected directly with the resistance temperature sensor by using an OPC-PT option card.

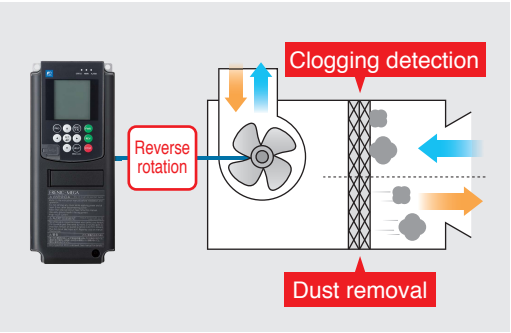
Note) The resistance temperature sensor needs to be purchased separately.



11 Clogged Air Filter Remediation NEW

VARIOUS APPLICATIONS

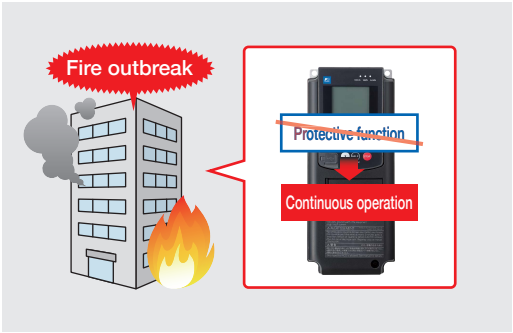
MEGA G2 detects filter clogging due to dust, etc., based on output current and pressure sensor values, and removes the dust through reverse rotation. In addition, an alarm is used to indicate that mainte-nance is required.



12 Fire Mode

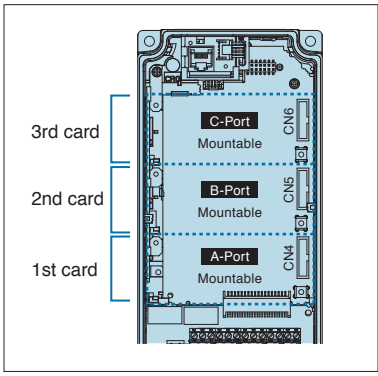
VARIOUS APPLICATIONS

In the event of a fire or other emergency, the inverter's protective function (output shutoff) is partially ignored and operation is continued. This prevents the building from being filled with smoke and secures an evacuation passage.



13 Supports a variety of networks Option cards

VARIOUS APPLICATIONS



Insert the option card into the connector inside the main unit.
Up to three cards can be inserted.

Optional communication card types

1. DeviceNet
2. CC-Link
3. T-Link
4. PROFIBUS-DP
5. CANopen
6. SX bus
7. Ethernet (EtherNet/IP, PROFINET RT)

Coming soon
(Modbus-TCP, BACnet/IP, and EtherCAT)

Note) There are some limitations to how option cards can be combined. Please contact us for details.

* For other types of option cards, please refer to page 70.

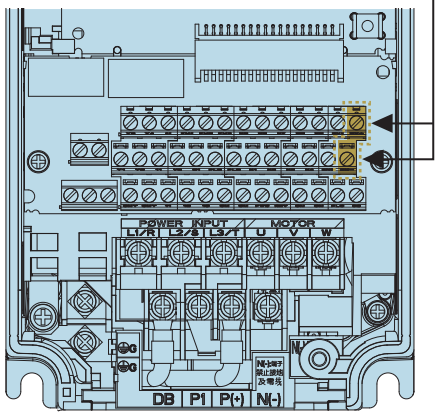
14 Enhanced network functions

VARIOUS APPLICATIONS

Compatible with RS-485 communication (terminal block)

Comes standard with an RS-485 terminal in addition to a port (RJ-45 connector) that is shared with the keypad.
Simplifies multi-drop connections via terminal connection.

Supports RS-485 terminal multi-drop connection



15 Bluetooth

VARIOUS APPLICATIONS

Our upgraded FRENIC Mobile Loader now includes Bluetooth support built into the FRENIC-MEGA. This provides an easy connection from a mobile device, real-time tracing, configuration according to usage, editing functional codes, real-time operation monitoring, and remote testing.

Features

Easy maintenance

Enhances work efficiency through simplified wiring and configuration and ensures safety and security through standard features such as preventive and predictive maintenance functions.

05 Load adaptive control

When the actual load level is lower than the configured load level, the system can be operated at a ratio-multiplied frequency, resulting in significantly better efficiency.

01 Same mounting dimensions

MAINTAINABILITY

The appearance and mounting dimensions of the inverter are fully compatible.
The 3D position and size of the main circuit screw terminals are also the same.

* Can be installed as a replacement for conventional FRENIC-MEGA_G1 series products.

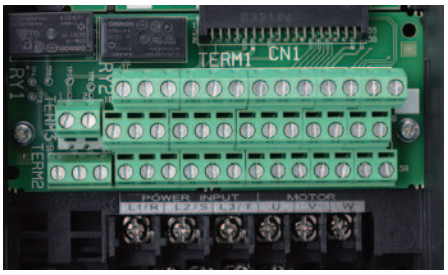
02 Simple wiring

MAINTAINABILITY

The control terminal block uses an industry-standard rod-shaped block (44-pole, ⊖ screw) and improves workability of wiring.

Supports replacement or mounting of conventional FRENIC-MEGA_G1 Series' round terminal blocks (35-pole ⊕ screw).

Rod-shaped terminal block 44 poles



03 Easy parameter migration

MAINTAINABILITY

Compatibility mode allows parameters read from the previous model to be written directly to the G2 Series.

* The previous models include FRENIC-MEGA_G1 and FRENIC-MEGA_GX1 FRENIC-Eco series products.
* Data can be read from a touch panel (TP-E1U/TP-G1-J1) or PC loader from a conventional FRENIC-MEGA_G1 Series product and copied to the G2 Series. Please be assured that the function codes newly added in the G2 Series will not be changed.

04 Designed with new operation keypad

MAINTAINABILITY

Comes standard with a Multifunction LCD display whose large screen is very intuitive and enhances maintainability via improved key button operability and cursor digit control.

ulti-fun ti **Standard**

G2
TP-A2SW

G1
TP-G1-J1

iti l atures

Character display

・Equipped with a highly visible LCD.
・Supports a total of 20 languages, including Japanese hiragana, katakana and kanji.

0:Japanese	1:English	2:German	3:French	4:Spanish
5:Italian	6:Chinese	7:Korean*	8:Russian	9:Greek
10:Turkish	11:Polish	12:Czech	13:Swedish	14:Portuguese
15:Dutch	16:Malay	17:Vietnamese	18:Thai	19:Indonesian

* Compatible with the software version, main product ROM0500 or later and the multifunctional keypad ROM5020 or later.

USB port

・Mounts to both standard keypad and multifunctional keypad.
・Can be directly connected to a PC with a commercially available USB cable (mini B).

Clock function

・Time data can be added to the alarm history.
* Battery (CR2032 type) not included.

SD card slot

・Can store traceback data on micro SD card.
* SD card not included.

Water resistant

・The front surface and sides are IP55 protected. * The back side is IP20 protected.

Built-in Bluetooth

・Parameter changes and maintenance can be performed remotely using a mobile device.
* Radio law certified countries: Japan, Europe, North America, China, Thailand

05 Enhancement of alarm history/traceback function

MAINTAINABILITY

・Capable of displaying and saving data for the past 4 alarms, such as output voltage and output frequency at times of alarms.
* When using the multifunctional keypad, you can also obtain data on the time of occurrence. However, batteries are required.

・When an alarm occurs, previous waveform data can be acquired and saved.

■Number of saved items

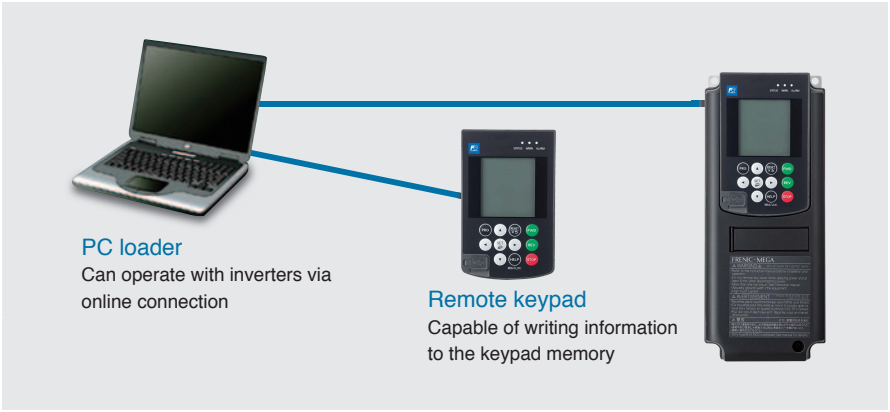
	Number of alarms
Keypad (TP-E2)	1
Multifunctional keypad (TP-A2SW)	100 *SD card

*The above is the number of saved tracebacks.

06 Enhanced PC loader functions

MAINTAINABILITY

- The PC loader can be used by directly connecting the keypad to a PC using a commercially available USB cable (mini B).
- It makes it easy to store or check various types of information at the office, or send information and check abnormalities at

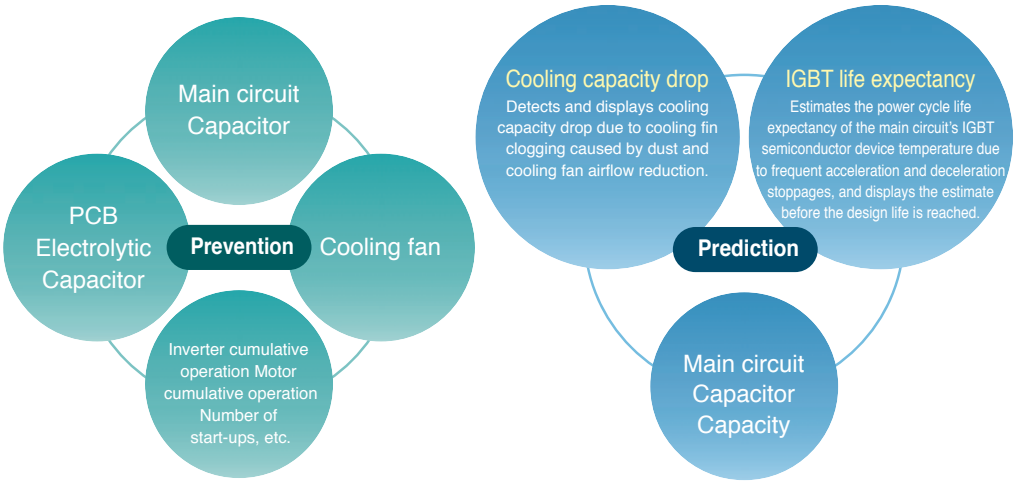


Usage examples

07 Life expectancy diagnosis and maintenance functions Enhancement

MAINTAINABILITY

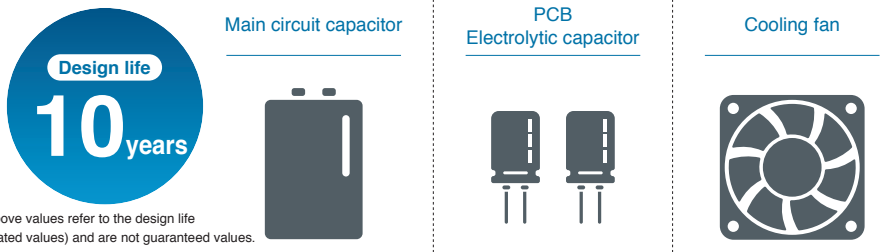
The keypad and PC loader make it easy to check the status of equipment and detect problems before they occur, helping to reduce production equipment maintenance time and downtime.



08 Long life expectancy (main components)

MAINTAINABILITY

Many of the serviceable parts inside the inverter have been designed to meet



* The above values refer to the design life (calculated values) and are not guaranteed values.

Life expectancy conditions	Ambient temperature 40°C, load factor 100% (HHD specification), 80% (HND specification)

Features

Environmentally resistant

Globally compliant lineup compatible with adverse atmospheres and various safety standards.

01 Improves environmental resistance Enhancement

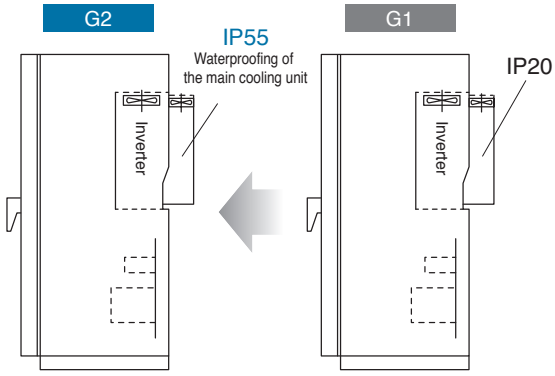
ENVIRONMENTAL RESISTANCE

(1) Uses copper bars with nickel and tin plating
(2) Ambient operating temperature up to +55°C
* Derating is required when used at 50°C or higher.

(3) Further strengthens PCB coating
(JIS C 60721-3-3/IEC 60721-3-3 Class 3C2)
* Products also available with enhanced salt-resistance and made-to-order specifications.

(4) IP55 protection for the inverter's main cooling unit contributes to enhanced cooling outside the panel, lower costs, and downsizing.

Note) If you are using or considering using the product under the following conditions, please contact our sales department.
a. Environments containing sulfurized gas (e.g., some applications in the tire manufacturing, paper manufacturing, sewage treatment, textile industries, etc.)
b. Environments containing conductive dust and foreign objects (e.g., metal processing machines, extruders, printing machines, waste disposal machinery, etc.)
c. When using the product in non-standard environments



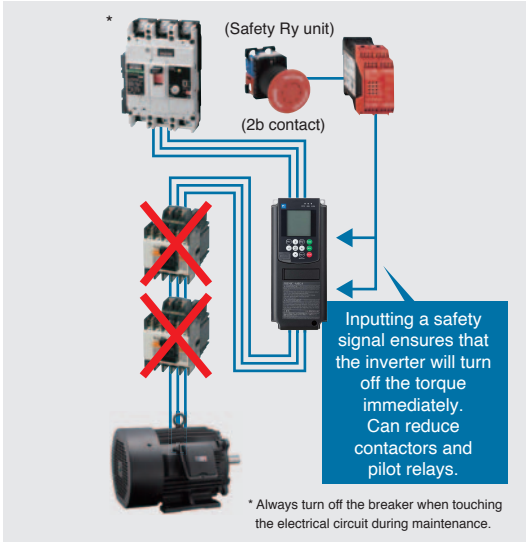
* Supports only 30 kW to 630 kW

02 Accepts Safety Interlocking

ENVIRONMENTAL RESISTANCE

- Compliant with European safety standards.
(EN ISO 13849-1:2015, Cat3/PL:e IEC/EN61800-5-2:2016 SIL3 (STO))
*The zero-phase reactor built-in type does not comply with the EC Directive (CE marking).

- The inverter comes with a function that enables it to adapt to machine safety. This facilitates the design of main circuit switching devices for ensuring safe stoppages.



* Always turn off the breaker when touching the electrical circuit during maintenance.

03 Compliant with the revised European RoHS Directive

ENVIRONMENTAL RESISTANCE

Ten environmental impact substances

RoHS 2019

Lead, mercury, cadmium, and hexavalent chromium
Polybrominated biphenyl (PBB)
Polybrominated diphenyl ether (PBDE)
Di-2-ethylhexyl phthalate (DEHP)
Butyl benzyl phthalate (BBP)
Di-n-butyl phthalate (DBP)
Diisobutyl phthalate (DIBP)

04 Globally compliant

ENVIRONMENTAL RESISTANCE

Compliant with overseas safety standards.

European regions	United States/ Canada
EC directive (CE marking)	UL standard/cUL standard
CE	c UL us LISTED

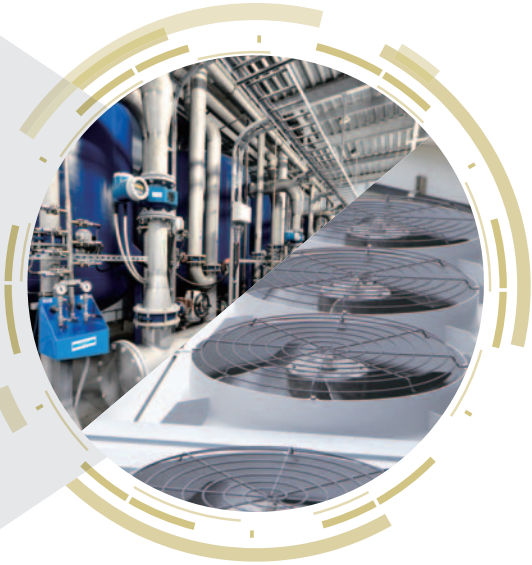
*The zero-phase reactor built-in type does not comply with the EC Directive (CE marking).

Main application examples

Expansion of Mega Series app

Fans and pumps

Others Blowers, turbo chillers, etc.



»PID control
Auto tuning function

Ensures smooth equipment startup and optimal operation adjustment through automatic PID parameter adjustment.

»Automatic energy-saving operation mode

Minimizes inverter and motor loss through automatic operation, helping to achieve equipment energy savings.

»Multi drive
New auto tuning function

Enables multi-drive operation with a single inverter through induction and synchronous motor tuning.

Compressors

Others Machine tools, gear pumps, etc.

»Sensorless vector control
Synchronous motors

Capable of driving synchronous motors up to 599 Hz, helping to achieve equipment downsizing and energy savings.

Machine tools

Others Compressors, automobile testing instruments, etc.

»Position control
Orientation functions

Enables operation and rotator stopping angle specification using tool changer positioning, allowing stopped machinery to be held in place via servo locking.

»Speed responsiveness
Vector control

Reduces the effects of rotation irregularities and interference on machines through improved responsiveness (with sensor: 200 Hz; without sensor: 40 Hz).

»High-speed operation

Expands the output frequency range to 599 Hz for all control methods and shortens machining times through high-speed rotation.

lications

Supports a wide variety of applications and is useful in various situations.

Press machines

Others Forging press machines, hoisting and transporting, etc.

»High-speed responsiveness

Speed and current response | Vector control

Stabilizes quality by ensuring a constant rotational speed during load fluctuations through improved speed and current responsiveness.

»Regeneration avoidance function

Stabilizes operations by suppressing load fluctuation overvoltage alarms even in regenerative mode.

»Built-in braking transistor

Saves space and reduces cost of electric panels by expanding the capacity range (200 V series: 0.4 to 70HP, 400 V series: 0.4 to 100HP).

Winding machines

Others Printing machines, wrapping machines, etc.

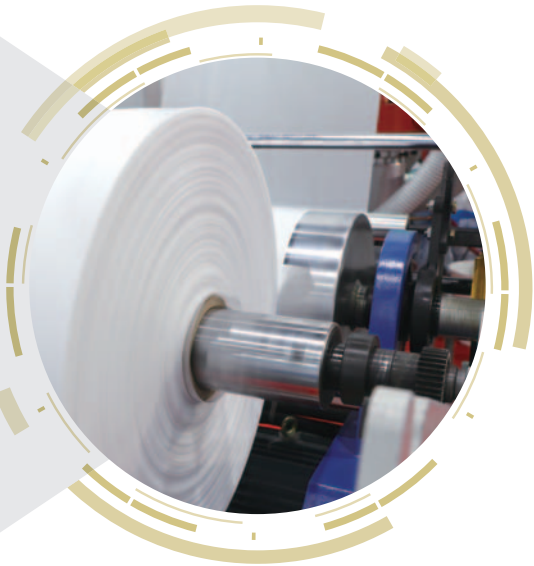
»High-speed responsiveness

Speed and current response | Vector control

Stabilizes quality by ensuring a constant rotational speed during load fluctuations through improved speed and current responsiveness.

»Stability at low speeds

Can control product quality variations even when the motor is running at low speed.



Hoists

Others Cranes and multistory warehouses, etc.

»Load adaptive control

Load adaptive control

When the actual load level is lower than the configured load level, the system can be operated at a ratio-multiplied speed (in terms of the configured frequency), resulting in significantly better efficiency.

»Load limiter

Load limiter

Maintains safety and rescuability of suspended loads by stopping when excessive torque is detected and by allowing operation only in the direction opposite to that in which the excessive load was detected.

»Vector control

Torque biasing function

Automatically incorporates the load portion into torque instructions to enable smooth start-up compensation during lifting and lowering.

Main application examples

Stacker cranes

Others Elevators, escalators, etc.

» Position control function

Enables high-precision positioning control and tact time reduction through use of pulse train instructions and operations, origin return, and position preset overtravel detection.

» Brake release signals

Outputs braking signals based on inverter operating conditions to prevent cargo bed rollback and overrunning.

» Motor constant switching

Enables multi-motor switchover operation for driving, lifting, and forking applications, and reduces costs by decreasing the number of inverters in use.

Multistory parking lots

Others Cranes, hoists, etc.

» Built-in braking transistor

Saves space and reduces cost of electric panels by expanding the capacity range (200 V series: 0.4 to 55 kW, 400 V series: 0.4 to 75 kW).

» Dynamic torque vector control

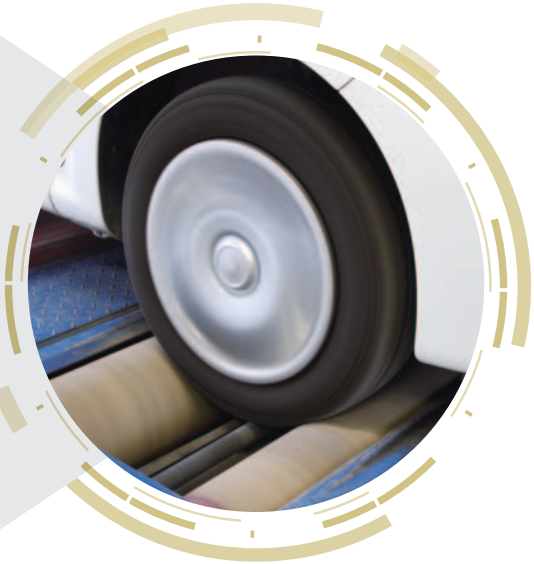
Enables smooth startup by outputting powerful torque even at low speeds.

» Brake release signals

Outputs braking signals based on inverter operating conditions to prevent vehicle rollback and overrunning.

Automotive testing equipment

Others Machine tools, press machines, etc.



» Torque control Sensor-equipped vector control

Supports configuration of test equipment for simulating loads using torque control.

» High-speed responsiveness Speed and current response Vector control

Enables quantification of testing by ensuring a constant rotational speed during load fluctuations through improved speed and current responsiveness.

» Speed control range Sensor-equipped vector control

Enables high-speed motor driving rotation testing through expansion of the constant output range (1:16).

Crushing machines

» Dynamic torque vector control

Enables powerful operation even during sudden load changes and low-speed rotation.

» Life expectancy forecasting

Monitors inverter current and temperature rise to predict and detect inverter tripping and failure. Prevents equipment stoppages and reduces downtime.

» Customizable logic functions

Enables creation of customized programs (such as a program for recovering from stoppages due to jamming) by combining a wide variety of digital and analog operation blocks.

Plant related

1 Rolling mills

» High-speed responsiveness Speed and current response Vector control

Enables high-precision roller operation by ensuring a constant rotational speed during load fluctuations through improved speed and current responsiveness.

» Load inertia estimation

Estimates the theoretical acceleration and deceleration time based on the load inertia, enabling users to make optimal settings.

2 Kilns

» Multi-pole motor operation

Can operate motors with up to 128 poles and supports rated frequencies as low as 5 Hz.

» Life expectancy forecasting

Monitors inverter current and temperature rise to predict and detect inverter tripping and failure. Prevents device and equipment stoppages and reduces downtime.

Model Variations

Model list

Standard applied motor [kW (HP)]	Basic type			
	3-phase 460 V series		3-phase 230 V series	
	HND spec	HHD spec	HND spec	HHD spec
2/5(1/2)	FRN0002G2S-4GU	FRN0002G2S-4GU	FRN0003G2S-2GU	FRN0003G2S-2GU
1(1)	FRN0003G2S-4GU	FRN0003G2S-4GU	FRN0005G2S-2GU	FRN0005G2S-2GU
2(2)	FRN0004G2S-4GU	FRN0004G2S-4GU	FRN0008G2S-2GU	FRN0008G2S-2GU
2(3)	FRN0006G2S-4GU	FRN0006G2S-4GU	FRN0011G2S-2GU	FRN0011G2S-2GU
4(5)	FRN0009G2S-4GU	FRN0009G2S-4GU	FRN0018G2S-2GU	FRN0018G2S-2GU
6(7.5)		FRN0018G2S-4GU		FRN0032G2S-2GU
8(10)	FRN0018G2S-4GU	FRN0023G2S-4GU	FRN0032G2S-2GU	FRN0046G2S-2GU
11(15)	FRN0023G2S-4GU	FRN0035G2S-4GU	FRN0046G2S-2GU	FRN0059G2S-2GU
15(20)	FRN0035G2S-4GU	FRN0041G2S-4GU	FRN0059G2S-2GU	FRN0075G2S-2GU
18(25)	FRN0041G2S-4GU	FRN0045G2S-4GU	FRN0075G2S-2GU	FRN0088G2S-2GU
22(30)	FRN0045G2S-4GU	FRN0060G2S-4GU	FRN0088G2S-2GU	FRN0115G2S-2GU
30(40)	FRN0060G2S-4GU	FRN0085G2S-4GU	FRN0115G2S-2GU	FRN0146G2S-2GU
37(50)	FRN0085G2S-4GU	FRN0105G2S-4GU	FRN0146G2S-2GU	FRN0180G2S-2GU
45(60)	FRN0105G2S-4GU	FRN0139G2S-4GU	FRN0180G2S-2GU	FRN0215G2S-2GU
55(75)	FRN0139G2S-4GU	FRN0179G2W-4GU‡§	FRN0215G2S-2GU	FRN0288G2W-2GU‡§
75(100)	FRN0179G2W-4GU‡§	FRN0217G2W-4GU‡§	FRN0288G2W-2GU‡§	FRN0346G2W-2GU‡§
90(125)		FRN0261G2W-4GU‡§	FRN0346G2W-2GU‡§	FRN0432G2W-2GU‡§
110(150)	FRN0217G2W-4GU‡§		FRN0432G2W-2GU‡§	
132(200)	FRN0261G2W-4GU‡§	FRN0376G2W-4GU‡§		
160(250)		FRN0431G2W-4GU‡§		
200(300)	FRN0376G2W-4GU‡§	FRN0547G2W-4GU‡§		
220(350)	FRN0431G2W-4GU‡§	FRN0610G2W-4GU‡§		
315(450)	FRN0547G2W-4GU‡§	FRN0840G2W-4GU‡§		
355(500)	FRN0610G2W-4GU‡§	FRN1039G2W-4GU‡§		
400(600)	FRN0840G2W-4GU‡§	FRN1169G2W-4GU‡§		
500(800)	FRN1039G2W-4GU‡§			
560(900)	FRN1169G2W-4GU‡§	FRN1480G2W-4GU‡§		
710(1200)	FRN1480G2W-4GU‡§			

HND = High Normal Duty Mode -> 120% Overload for 1 min.
HHD = High Heavy Duty Mode -> 150% Overload for 1 min, and 200% for 3.0 Sec
‡ = Includes separately mounted and wired open DC Link Reactor
§ = Includes a UL Type 12 kit for the heat sink when installed inside the enclosure and heat sink through the back

How to interpret the inverter model number

FRN 0000 G 2 S - 4 GU

Code	Series name
FRN	FRENIC series

Code	Applicable motor rating
ND	Output current (A)

Code	Applicable range
G	High performance, multifunctional type

Code	Destination
GU	Global

Code	Input power source
4	3-phase 400V
2	3-phase 200V

Code	Enclosure
S	Standard (basic type)
	EMC filter built-in type
W	Includes a separately mounted and wired open DC Link Reactor and a UL Type 12 kit for the heat sink, used when the VFD installed inside the enclosure and heat sinkextends through the enclosure rear panel.

Code	Order of development
2	Series

Standard Specifications

Basic type

Three-phase 200V series

Item				Specifications															
Type (FRN□□□□G2S-2G)				0003	0005	0008	0011	0018	0032	0046	0059	0075	0088	0115	0146	0180	0215	0288	0346	0432
Standard applicable motor (*1)		kW	HHD	0.4	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75	90
			HND	-					7.5	11	15	18.5	22	30	37	45	55	75	90	110
		HP	HHD	1/2	1	2	3	5	7.5	10	15	20	25	30	40	50	60	75	100	125
			HND	-					10	15	20	25	30	40	50	60	75	100	125	150
Output ratings	Rated capacity [kVA] (*2)		HHD	1.1	1.9	3.0	4.1	6.8	10	14	18	24	28	34	45	55	68	81	109	131
			HND	-					12	17	22	28	33	43	55	68	81	109	131	164
	Rated current [A] (at Ta=50°C(122°F))		HHD	3	5	8	11	18	27	37	49	63	76	90	119	146	180	215	288	346
			HND	-					31.8	46.2	59.4	74.8	88	115	146	180	215	288	346	432
	Rated voltage [V] (*3)			Three-phase 200 to 240 V (with AVR function)											Three-phase 200 to 230 V (with AVR function)					
	Overload current rating [A] (permissible overload time)		HHD	150% for 1 minute, 200% for 3 seconds																
			HND	120% for 1 minute																
	Ambient temperature		HHD	-10 to +55 °C [14 to 131 °F] (current derating necessary in +50 to +55 °C [122 to 131 °F] range)																
			HND	-10 to +55 °C [14 to 131 °F] (current derating necessary in +50 to +55 °C [122 to 131 °F] range)																
	Rated frequency [Hz]			50/60 Hz																
Input ratings	Voltage, frequency			Three-phase 200 to 240 V, 50/60 Hz											Three-phase 200 to 230 V, 50/60 Hz					
	Voltage, frequency fluctuation			Voltage: +10 to -15% (interphase unbalance ratio: 2% or less) (*5), Frequency: +5 to -5 %																
	Rated current [A] (*6)	With DCR	HHD	1.6	3.2	6.1	8.9	15.0	21.1	28.8	42.2	57.6	71.0	84.4	114	138	167	203	282	334
			HND	-					28.8	42.2	57.6	71	84.4	114	138	167	203	282	334	410
		Without DCR	HHD	3.1	5.3	9.5	13.2	22.2	31.5	42.7	60.7	80.1	97.0	112	151	185	225	270	-	-
			HND	-					42.7	60.7	80.1	97	112	151	185	225	270	-	-	-
	Required power supply capacity (with DCR) [kVA] (*7)		HHD	0.6	1.2	2.2	3.1	5.2	7.4	10	15	20	25	30	40	48	58	71	98	116
			HND	-					10	15	20	25	30	40	48	58	71	98	116	143
	Auxiliary control power supply voltage			-		Single-phase 200 to 240 V, 50/60 Hz 100VA									Single-phase 200 to 230 V, 50/60 Hz 100VA					
Braking	Torque [%] (*8)		HHD	150		100					20				10 to 15					
			HND	-					70		15				7 to 12					
	Braking transistor			Built-in															Option	
	Minimum connectable resistance value [Ω]			100		40		24	16	12	8	6	4		2.5	2.25	2	1.6	-	
	Built-in braking resistor [Ω]			100		40			20		Option									
		Time [s]	HHD	5							-									
			HND	-					3.7	3.4	-									
		%ED	HHD	5	3	5	3	2	3	2	-									
			HND	-					2.2	1.4	-									
DC reactor (DCR)			HHD	Option															Option (*9)	
			HND	Option														Option (*9)		
Protective construction (IEC 60529)				IP20 enclosed type, UL open type											IP00 open type, UL open type IP55 at external side when external cooling installed					
Cooling system				Natural cooling			Fan cooling													
Weight [kg(lbs)]				1.7 (3.6)	1.9 (4.2)	2.6 (5.7)	2.9 (6.3)	2.9 (6.4)	5.8 (13)	6.2 (14)	5.7 (13)	11 (23)	11 (24)	12 (25)	23 (51)	31 (68)	40 (88)	42 (93)	60 (132)	97 (214)

(*1) Standard applicable motor indicates Fuji Electric 4-pole standard motors. Select a motor not only based on inverter output (kW), but also so that the output rated current is greater than the motor rated current.
(*2) The rated capacity indicates 220 V for the 200 V series, and 440 V for the 400 V series.
(*3) It is not possible to output a voltage higher than the power supply voltage.
(*5) Interphase unbalance ratio [%] = (Max. voltage [V] - min. voltage [V]/Three-phase average voltage [V] x 67 (see IEC/EN 61800-3).
If using the motor with an unbalance ratio of 2 to 3%, use an AC reactor (ACR: option).
(*6) This indicates the estimated value if the power supply capacity is 500 kVA (10 times inverter capacity if inverter capacity exceeds 50 kVA), and the motor is connected to a power supply of %X = 5%.
(*7) This indicates the capacity when the motor is equipped with a DC reactor (DCR).
(*8) This is the average braking torque when performing individual operation. (This will vary based on the motor efficiency.)
(*9) When applying a motor of 75kW or more, be sure to use a DC reactor (option).

Three-phase 400V series

Item				Specification													
Type (FRN□□□□G2S-4G)				0002	0003	0004	0006	0009	0018	0023	0035	0041	0045	0060	0085	0105	0139
Standard applicable motor (*1)		kW	HHD	0.4	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45
			HND	-					7.5	11	15	18.5	22	30	37	45	55
			HD	-											37	45	55
			ND	-											45	55	75
		HP	HHD	1/2	1	2	3	5	7.5	10	15	20	25	30	40	50	60
			HND	-	-	-	-	-	10	15	20	25	30	40	50	60	75
			HD	-											50	60	75
			ND	-											60	75	100
Output ratings	Rated capacity [kVA] (*2)		HHD	1.1	1.9	3.2	4.5	6.8	10	14	18	24	29	34	45	57	69
			HND	-					13	17	26	31	34	45	57	69	85
			HD	-											57	69	85
			ND	-											64	80	105
	Rated current [A] (at Ta=50°C(122°F))		HHD	1.5	2.5	4.2	6.0	9.0	13.5	18.5	24.5	32	39	45	60	75	91
			HND	-					17.5	23	35	41	45	60	75	91	112
	Rated current [A] (at Ta=40°C(104°F))		HD	-											75	91	112
			ND	-											85	105	139
	Rated voltage [V] (*3)			Three-phase 380 to 480 V (with AVR function)													
	Overload current rating [A] (permissible overload time)		HHD	150% for 1 minute, 200% for 3 seconds													
			HND	120% for 1 minute													
			HD	150% for 1 minute													
			ND	120% for 1 minute													
	Ambient temperature		HHD	-10 to +55 °C [14 to 131 °F] (current derating necessary in +50 to +55 °C [122 to 131 °F] range)													
			HND	-					-10 to +55 °C [14 to 131 °F] (current derating necessary in +50 to +55 °C [122 to 131 °F] range)								
			HD	-											-10 to +55°C [14 to 131°F] (current derating necessary in +40 to +55°C [104 to 131°F] range)		
			ND	-													
	Rated frequency [Hz]			50/60 Hz													
Input ratings	Voltage, frequency			Three-phase 380 to 480 V, 50/60 Hz													
	Voltage, frequency fluctuation			Voltage: +10 to -15% (interphase unbalance ratio: within 2%)(*5), Frequency: +5 to -5 %													
	Rated current [A] (*6)	With DCR	HHD	0.85	1.6	3.0	4.5	7.5	10.6	14.4	21.1	28.8	35.5	42.2	57.0	68.5	83.2
			HND	-					14.4	21.1	28.8	35.5	42.2	57	68.5	83.2	102
			HD	-											68.5	83.2	102
			ND	-											83.2	102	138
		Without DCR	HHD	1.7	3.1	5.9	8.2	13	17.3	23.2	33	43.8	52.3	60.6	77.9	94.3	114
			HND	-					23.2	33	43.8	52.3	60.6	77.9	94.3	114	140
			HD	-											94.3	114	140
			ND	-											114	140	-
	Required power supply capacity (with DCR) [kVA] (*7)		HHD	0.6	1.2	2.1	3.2	5.2	7.4	10	15	20	25	30	40	48	58
			HND	-					10	15	20	25	30	40	48	58	71
			HD	-											48	58	71
			ND	-											58	71	96
	Auxiliary control power supply voltage			-	Single-phase 380 to 480 V, 50/60 Hz 100 VA												
Braking	Torque [%] (*8)		HHD	150	100						20				10 to 15		
			HND	-					70		15				7 to 12		
			HD ND	-											7 to 12		
	Braking transistor			Built-in as standard													
	Minimum connectable resistance value [Ω]			200		160		96	64	48	32	24	16		10	9.0	8.0
	Built-in braking resistor [Ω]			720	470	160			80		Option						
		Time [s]	HHD	5							-						
			HND	-					3.7	3.4	-						
			HD ND	-													
		%ED	HHD	5	3	5	3	2	3	2	-						
			HND	-					2.2	1.4	-						
			HD ND	-							-						

(*1) Standard applicable motor indicates Fuji Electric 4-pole standard motors. Select a motor not only based on inverter output (kW), but also so that the output rated current is greater than the motor rated current.
(*2) The rated capacity indicates 220 V for the 200 V series, and 440 V for the 400 V series.
(*3) It is not possible to output a voltage higher than the power supply voltage.
(*5) Interphase unbalance ratio [%] = (Max. voltage [V] - min. voltage [V]/Three-phase average voltage [V] x 67 (see IEC/EN 61800-3).
If using the motor with an unbalance ratio of 2 to 3%, use an AC reactor (ACR: option).
(*6) This indicates the estimated value if the power supply capacity is 500 kVA (10 times inverter capacity if inverter capacity exceeds 50 kVA), and the motor is connected to a power supply of %X = 5%.
(*7) This indicates the capacity when the motor is equipped with a DC reactor (DCR).
(*8) This is the average braking torque when performing individual operation. (This will vary based on the motor efficiency.)

Basic type

Three-phase 400V series

Item		Specification												
Type (FRN□□□□G2S-4G)		0002	0003	0004	0006	0009	0018	0023	0035	0041	0045	0060	0085	0105	0139
DC reactor (DCR)	HHD	Option													
	HND	Option													
	HD	-											Option		
	ND	-											Option		Option (*9)
Protective construction (IEC 60529)		IP20 enclosed type, UL open type											IP00 open type, UL open type IP55 at external side when external cooling installed		
Cooling system		Natural cooling			Fan cooling										
Weight [kg(lbs)]		1.7 (3.7)	2.0 (4.3)	2.6 (5.8)	2.9 (6.4)	3.0 (6.6)	5.9 (13)	6.0 (13)	5.7 (13)	10 (23)	11 (23)	11 (23)	23 (51)	23 (51)	28 (62)

(*1) Standard applicable motor indicates Fuji Electric 4-pole standard motors. Select a motor not only based on inverter output (kW), but also so that the output rated current is greater than the motor rated current.
(*2) The rated capacity indicates 220 V for the 200 V series, and 440 V for the 400 V series.
(*3) It is not possible to output a voltage higher than the power supply voltage.
(*5) Interphase unbalance ratio [%] = (Max. voltage [V] - min. voltage [V]/Three-phase average voltage [V] x 67 (see IEC/EN 61800-3).
If using the motor with an unbalance ratio of 2 to 3%, use an AC reactor (ACR: option).
(*6) This indicates the estimated value if the power supply capacity is 500 kVA (10 times inverter capacity if inverter capacity exceeds 50 kVA), and the motor is connected to a power supply of %X = 5%.
(*7) This indicates the capacity when the motor is equipped with a DC reactor (DCR).
(*8) This is the average braking torque when performing individual operation. (This will vary based on the motor efficiency.)
(*9) When applying a motor of 75kW or more, be sure to use a DC reactor (option).

Basic type

Three-phase 400V series

Item				Specification													
Type (FRN □□□□ G2S-4G)				0179	0217	0261	0290	0376	0431	0547	0610	0739	0840	1039	1169	1385	1480
Standard applicable motor (*1)		kW	HHD	55	75	90	110	132	160	200	220	280	315	355	400	500	630
			HND	75	110	132	160	200	220	280	315	355	400	500	560	630	710
			HD	75	90	110	132	160	200	220	250	315	355	400	450	560	710
			ND	90	110	132	160	200	220	280	315	400	450	560	630	710	800
		HP	HHD	75	100	125	150	200	250	300	350	400	450	500	600	800	900
			HND	100	150	200	200	300	350	450	500	500	600	800	900	900	1200
			HD	100	150	150	200	250	300	350	400	450	500	600	700	900	1200
			ND	125	150	200	200	300	350	450	500	600	700	900	900	1200	1300
Output ratings	Rated capacity [kVA] (*2)		HHD	85	114	137	164	198	247	287	329	396	445	495	563	731	891
			HND	114	165	198	221	275	316	416	464	495	563	731	792	891	1056
			HD	114	137	165	198	247	287	329	363	445	495	563	640	792	1056
			ND	136	165	198	221	286	328	416	464	563	640	791	890	1055	1127
	Rated current [A] (at Ta=50°C(122°F))		HHD	112	150	180	216	260	325	377	432	520	585	650	740	960	1170
			HND	150	217	261	290	361	415	547	610	650	740	960	1040	1170	1386
	Rated current [A] (at Ta=40°C(104°F))		HD	150	180	217	261	325	377	432	477	585	650	740	840	1040	1386
			ND	179	217	261	290	376	431	547	610	739	840	1039	1169	1385	1480
	Rated voltage [V] (*3)			Three-phase 380 to 480 V (with AVR function)													
	Overload current rating[A] (permAissible overload time)		HHD	150% for 1 minute, 200% for 3 seconds													
			HND	120% for 1 minute													
			HD	150% for 1 minute													
			ND	120% for 1 minute													
	Ambient temperature		HHD	-10 to +55 °C [14 to 131 °F] (current derating necessary in +50 to +55 °C [122 to 131 °F] range)													
			HND	-10 to +55 °C [14 to 131 °F] (current derating necessary in +50 to +55 °C [122 to 131 °F] range)													
			HD	-10 to +55 °C [14 to 131 °F] (current derating necessary in +40 to +55 °C [104 to 131 °F] range)													
			ND	-10 to +55 °C [14 to 131 °F] (current derating necessary in +40 to +55 °C [104 to 131 °F] range)													
	Rated frequency [Hz]			50/60 Hz													
Input ratings	Voltage, frequency			Three-phase 380 to 480 V, 50/60 Hz 100VA													
	Voltage, frequencyfluctuation			Voltage: +10 to -15% (interphase unbalance ratio: within 2%)(*5), Frequency: +5 to -5 %													
	Rated current [A](*6)	With DCR	HHD	102	138	164	201	238	286	357	390	500	559	628	705	881	1115
			HND	138	201	238	286	357	390	500	559	628	705	881	990	1115	1256
			HD	138	164	201	238	286	357	390	443	559	628	705	789	990	1256
			ND	164	201	238	286	357	390	500	559	705	789	990	1115	1256	1415
		Without DCR	HHD	140	-	-	-	-	-	-	-	-	-	-	-	-	-
			HND	-	-	-	-	-	-	-	-	-	-	-	-	-	-
			HD	-	-	-	-	-	-	-	-	-	-	-	-	-	-
			ND	-	-	-	-	-	-	-	-	-	-	-	-	-	-
	Required power supply capacity (with DCR) [kVA] (*7)		HHD	71	96	114	140	165	199	248	271	347	388	436	489	611	773
			HND	96	140	165	199	248	271	347	388	436	489	611	686	773	871
			HD	96	114	140	165	199	248	271	307	388	436	489	547	686	871
			ND	114	140	165	199	248	271	347	388	489	547	686	773	871	981
	Auxiliary control power supply voltage			Single-phase 380 to 480 V, 50/60 Hz													
Braking	Torque [%] (*8)		HHD	10 to 15													
			HND HD ND	7 to 12													
	Braking transistor			Built-in		Option											
	Minimum connectable resistance value [Ω]			6.5	4.7	-											
	Built-in braking resistor [Ω]			Option													
		Time [s]		-													
		%ED		-													
DC reactor (DCR)			HHD	Option	Option(*9)												
			HND	Option(*9)													
			HD ND	Option(*9)													
Protective construction (IEC 60529)				IP00 open type, UL open type IP55 at external side when external cooling installed													
Cooling system				Fan cooling													
Weight [kg(lbs)]				31 (68)	38 (84)	60 (132)	60 (132)	89 (196)	89 (196)	116 (256)	124 (273)	221 (487)	221 (487)	291 (642)	295 (650)	450 (992)	450 (992)

(*1) Standard applicable motor indicates Fuji Electric 4-pole standard motors. Select a motor not only based on inverter output (kW), but also so that the output rated current is greater than the motor rated current.
(*2) The rated capacity indicates 220 V for the 200 V series, and 440 V for the 400 V series.
(*3) It is not possible to output a voltage higher than the power supply voltage.
(*5) Interphase unbalance ratio [%] = (Max. voltage [V] - min. voltage [V]/Three-phase average voltage [V] x 67 (see IEC/EN 61800-3).
If using the motor with an unbalance ratio of 2 to 3%, use an AC reactor (ACR: option).
(*6) This indicates the estimated value if the power supply capacity is 500 kVA (10 times inverter capacity if inverter capacity exceeds 50 kVA), and the motor is connected to a power supply of %X = 5%.
(*7) This indicates the capacity with a DC reactor (DCR).
(*8) This is the average braking torque during standalone operation. (This will vary based on the motor efficiency.)
(*9) When applying a motor of 75kW or more, be sure to use a DC reactor (option).

Common Specifications

Item			Explanation		Remarks
Output	Adjustment	Maximum output frequency	5 to 599 Hz variable setting		
		Base frequency	5 to 599 Hz variable setting (in conjunction with maximum output frequency)		
		Number of motor poles setting	2 to 128 poles		
		Starting frequency	0.1 to 60.0 Hz variable setting (0.0 Hz when performing speed sensorless vector control/vector control with speed sensor)		
		Carrier frequency	• 0.75 to 16 kHz variable setting HHD specification: 0.4 to 55 kW (type: 0003 to 0288 (200 V), type: 0002 to 0179 (400 V)) HND specification: 5.5 to 18.5 kW (type: 0032 to 0088 (200 V), type: 0018 to 0045 (400 V)) • 0.75 to 10 kHz variable setting HHD specification: 75 to 630 kW (type: 0346 to 0432 (200 V), type: 0217 to 1480 (400 V)) HND specification: 22 to 55 kW (type: 0115 to 0288 (200 V), type: 0060 to 0179 (400 V)) HD specification: 30 to 55 kW (type: 0085 to 0179 (400 V)) • 0.75 to 6 kHz variable setting HND specification: 75 to 630 kW (type: 0346 to 0432 (200 V), type: 0217 to 1480 (400 V)) HD specification: 75 to 630 kW (type: 0217 to 1480 (400 V)) ND specification: 30 to 630 kW (type: 0085 to 1480 (400 V)) Note) The carrier frequency may automatically lower depending upon the ambient temperature or the output current to protect the inverter. (The automatic lowering function can be disabled.)		
	Output frequency accuracy		• Analog setting : ±0.2% of maximum output frequency (at 25 ±10 °C) (77 ±18 °F) • Keypad setting : ±0.01% of maximum output frequency (at 10 to +50 °C) (14 ±22 °F)		
	Frequency setting resolution		• Analog setting : 1/3000 of maximum output frequency • Keypad setting : 0.01 Hz • Link setting : 1/20000 of maximum output frequency or 0.01 Hz (fixed)		
	Synchronous motors	When performing V/f control with sensor*1 When performing dynamic torque vector control with sensor*2	Speed control Range	• 1:20*1, 1:200*2 (Minimum speed: Nominal speed) • 1:2 (fixed torque area : fixed output area)	
			Speed control accuracy	• Analog setting: ±0.2% of maximum output frequency or below (at 25 ±10 °C) • Digital setting: ±0.01% of maximum output frequency or below (at 10 to +50 °C)	
		When performing sensorless vector control	Speed control Range	• 1:200 (Minimum speed: Nominal speed) • 1:2 (fixed torque area : fixed output area)	
			Speed control accuracy	• Analog setting: ±0.5% of maximum output frequency or below (at 25 ±10 °C) • Digital setting: ±0.5% of maximum output frequency or below (at 10 to +50 °C)	
		When performing vector control with sensor	Speed control Range	• 1:1500 (Minimum speed: Nominal speed) • 1:16 (fixed torque area : fixed output area)	
			Speed control accuracy	• Analog setting: ±0.2% of maximum output frequency or below (at 25 ±10 °C) • Digital setting: ±0.01% of maximum output frequency or below (at 10 to +50 °C)	
		When performing sensorless vector control	Speed control Range	• 1:10 (Minimum speed: Nominal speed) • 1:2 (Limited by maximum output voltage)	
			Speed control accuracy	• Analog setting: ±0.5% of nominal speed or below (at 25 ±10 °C) • Digital setting: ±0.5% of nominal speed or below (at 10 ±+50 °C°C)	
		When performing vector control with sensor	Speed control Range	• 1:1500 (Minimum speed: Nominal speed) • 1:2 (Limited by maximum output voltage)	
			Speed control accuracy	• Analog setting: ±0.2% of maximum output frequency (at 25 ±10 °C) • Digital setting: ±0.01% of maximum output frequency (at 10 to +50 °C)	
Control	Control method		• V/f control • Dynamic torque vector control • V/f control with sensor, dynamic torque vector control with sensor • Sensorless vector control • Vector control with sensor • Sensorless vector control (synchronous motors) • Vector control with sensor (synchronous motors)		
	Voltage/frequency characteristics		200V series	• The base frequency and maximum output frequency are common, and the voltage can be set between 80 and 240 V. • AVR control can be turned ON or OFF. • Non linear V/f setting (3 points): The desired voltage (0 to 240 V) and frequency (0 to 599 Hz) can be set.	
			400V series	• The base frequency and maximum output frequency are common, and the voltage can be set between 160 and 500 V. • AVR control can be turned ON or OFF. • Non linear V/f setting (3 points): The desired voltage (0 to 500 V) and frequency (0 to 599 Hz) can be set.	
	Torque boost		• Auto torque boost (for constant torque load) • Manual torque boost: The desired torque boost value (0.0 to 20.0%) can be set. • The applicable load can be selected (for constant torque load, quadratic-torque load)		
	Starting torque (HHD specification)		• FRN0115G2S-2G/FRN0060G2■-4G or below 200% or higher, • FRN0146G2S-2G/FRN0085G2■-4G or above 180% or higher set frequency: 0.3 Hz, when performing V/f control (base frequency: 50 Hz, slip compensation/auto torque boost)		
	Running·operation		Key operation:	Start and stop with RUN and STOP keys (LED keypad) Start and stop with FWD, REV, and STOP keys (optional multi-function keypad)	
			External signals: Forward (reverse) rotation, start/stop commands [2-wire/3-wire operable], (digital input) coast to stop command, external alarm, alarm reset, etc.		
			Link operation: Operation through RS-485, field bus communication (option)		
			Run command switching : Remote/local switching, link switching		
			[RUN] key memory : Memorizes the state of the RUN key in the event of a power failure during operation using the keypad, and resumes operation after power is restored.		
	Frequency setting		Keypad operation : Using ▲ and ▼ keys		
			External potentiometer: Using external frequency command potentiometer (external resistor of 1 to 5 kΩ, 1/2 W)		
			Analog input :	Voltage input (terminal [12], [V2], [C1] (V3 function)) 0 to ±10 VDC (±5 VDC)/0 to ±100% 0 to +10 VDC (+5 VDC)/0 to +100% (+1 to +5 VDC can also be adjusted with bias, analog input gain) Voltage input (terminal [C1] (C1 function)) 4 to 20 mA DC/0 to 100%, 0 to 20 mA DC/0 to 100% 4 to 20 mA DC/-100 to +100%, 0 to 20 mA DC/-100 to +100%	

* For details, refer to the FRENIC-MEGA (G2) User's Manual.

	Item		Explanation	Remarks
Control	Frequency setting		UP/DOWN operation: Frequency can be increased or decreased while the digital input signal is ON. The frequency recorded with digital input “STZ” can be cleared.	
			Multistep frequency selection: Selectable from 16 different frequencies (step 0 to 15)	
			Pattern operation: The inverter runs automatically according to the previously specified run time, rotation direction, acceleration/deceleration time and reference frequency. Up to 7 stages can be specified.	
			Link operation: Setting through RS-485, field bus communication (option) (built in as standard)	
			Frequency setting switching: Two types of frequency settings can be switched with an external signal (digital input). Remote/local switching, link switching	
			Auxiliary frequency setting: Can be selected by adding and entering the respective terminal [12], [C1], or [V2] inputs.	
			Operation at a specified ratio: The ratio can be set with an analog input signal..	
			Inverse operation: Can be switched from “0 to +10 VDC/0 to 100%” to 10 to 0 VDC/0 to 100%” from an external source. Can be switched from “4 to 20 mA DC/0 to 100%” to “20 to 4 mA DC/0 to 100%” from an external source. Can be switched from “0 to 20 mA DC/0 to 100%” to “20 to 0 mA DC/0 to 100%” from an external source.	
			Pulse train input: (standard) Pulse input = terminal [X6], [X7], forward/reverse pulse, pulse + rotation direction Complementary output: Max. 100 kHz Open collector output: Max. 30 kHz	
			Pulse train input: (option) PG interface option, forward/reverse pulse, pulse + rotation direction Complementary output: Max. 100 kHz Open collector output: Max. 30 kHz	
	Acceleration/ deceleration time		Setting range: Setting range from 0.00 to 6000 s	
			Switching: The four types of acceleration/deceleration time can be set or selected individually (switchable during operation).	
			Acceleration/deceleration pattern: Linear acceleration/Deceleration, S curve acceleration/deceleration (week, random (weak)), curve line acceleration/deceleration (max. acceleration/deceleration at rated output)	
			Deceleration mode (coast to stop): Shutoff of the run command lets the motor coast to a stop.	
			Forcible stop deceleration time: Deceleration stop in exclusive deceleration time by forced stop (STOP). • Dedicated acceleration/deceleration time for jogging: • It is possible to switch between acceleration/deceleration time = 0 with acceleration/deceleration operation cancel “BPS”.	
	Frequency limiter (upper limit and lower limit frequencies)		• Specifies the upper and lower frequencies in Hz. • Processing can be selected when the reference frequency is less than the lower limit (F16). (The output frequency will be maintained at the lower limit/motor decelerates and stops.) • Setting is possible with analog input (terminal [12], [C1], [V2], [V3]).	
	Frequency/PID command bias		• Frequency: Set between 0 and ±200% • PID command: Set between 0 to ±100%	
	Analog input		• Gain: Setting range from 0 to 400% • Offset: Setting range from 5.0 to +5.0% • Filter: Setting range from 0.00 to 5.00s	
	Jump frequency		Six operation points and their common jump width (0 to 30.0 Hz) can be set.	
	Ready for jogging		Operation with RUN key (LED keypad), FWD or REV keys (Multi function keypad), or digital contact inputs “FWD” or “REV” (Exclusive acceleration/deceleration time setting, exclusive frequency setting)	
	Restart mode after momentary power failure		• Trip immediately: Trip immediately at the time of power failure. • Trip after recovery from power failure: Coast to a stop at the time of power failure and trip when the power is recovered. • Trip after decelerate to stop: Deceleration stop at power failure, and trip after stoppage • Continue to run: Operation is continued using the load inertia energy. • Start at the frequency selected before momentary power failure: Free run at power failure and start after power recovery at the frequency selected before momentary stop. • Start at starting frequency: Free run at power failure and start at the starting frequency after power recovery. • Start at frequency of power recovery: Free run at power failure, and start after power recovery by searching for the speed.	
	Current limiting	Hardware current limiter	Current is limited with hardware to prevent overcurrent trip due to high-speed load fluctuations or momentary power failure which cannot be handled with software current limiting. (This limiter can be canceled.)	
		Software current limiter	Automatically reduces the frequency so that the output current becomes lower than the preset operation level. (This limiter can be canceled.) The operation can be selected (operation at constant speed only, operation when accelerating and at constant speed).	
	Operation by commercial power supply		• With commercial power selection commands (“SW50”, “SW60”), the inverter outputs 50/60 Hz. • Commercial switching sequence built in	
	Slip compensation		Compensates for decrease in speed according to the load.	
	Droop control		Decreases the speed according to the load torque.	
	Torque limit control		• Switchable between 1st and 2nd torque limit values. • Torque limiting/torque current limiting/power limiting for each quadrant • Analog torque limit input	
	PID control		• PID processor for process control/dancer control • Switch normal/inverse operation • Command: Keypad, analog input (terminals 12, C1, V2, V3), multi-stage setting (selectable from 3 options), RS-485 communication, fieldbus communication (optional) • Feedback value: Analog input (terminals 12, C1, V2, V3) • Alarm output (absolute value alarm, deviation alarm) • PID feedback error detection • Sensor input scaling function • Sensor input conversion/calculation function • Low liquid level stop function (pressurized operation possible before low liquid level stop) • Automatic frequency update function for stoppage due to small water quantity • Anti reset wind up function • Output limiter • Integration reset/hold • PID constant auto tuning function for process control PID controlle • Built-in external PID controller: 3 sets	
	Retry		• Automatically releases the trip state and resumes operation up to the set number of times without outputting a batch alarm even if the protective function to be retried is activated. • Can be set up to 20 times (configurable by function code). • Can set the wait time before resetting. • Can set the alarm to be retried	

* For details, refer to the FRENIC-MEGA (G2) User’s Manual.

Common Specifications

	Item	Explanation	Remarks
Control	Auto search	The motor speed is estimated before startup, and the motor is started without ever stopping the motor while it is idling. (Motor constants must be tuned. Auto tuning (offline))	
	Anti regenerative control (Automatic deceleration)	• If the intermediate DC voltage/torque calculation value reach or exceed the anti regenerative control level when the motor is decelerating, the deceleration time is automatically extended to avoid an overvoltage trip. (Forced deceleration can be set at three or more times the deceleration time.) • If the torque calculation value reaches or exceeds the anti regenerative control level during constant speed operation, overvoltage tripping is avoided by performing control to raise the frequency.	
	Deceleration characteristics (Improvement of braking performance)	• The motor loss is increased during deceleration to reduce the regenerative energy in the inverter to avoid overvoltage trip. • Can be set for use with AVR cancellation	
	Auto energy saving operation	Controls the output voltage to minimize the total sum of the motor loss and inverter loss. (Auto energy saving control can be turned ON and OFF from an external source with a digital input signal.)	
	Overload prevention control	If the surrounding temperature or IGBT junction temperature increases due to overload, the inverter lowers the output frequency to avoid overload.	
	Offline tuning	Tunes the motor while the motor is stopped or running, for setting up motor parameters.	
	Offline tuning	This corrects changes in motor constants caused by temperature rise.	
	Cooling fan ON OFF control	• Detects inverter internal temperature and stops cooling fan when the temperature is low. • Possible to output a fan control signal to an external device.	
	Motor 1 to 4 settings	• Switching is possible between 4 motors. • It is possible to switch between four types of specific function code data (switching is possible while the motor is running.) The following data can be set for motors 1 to 4: base frequency, rated current, torque boost, electronic thermal slip compensation.	
	Universal DI	Transfers the status of an external digital signal connected with the general purpose digital input terminal to the host controller.	
	Universal DO	Outputs a digital command signal sent from the host controller to the general purpose digital output terminal.	
	Universal AO	Outputs an analog command signal sent from the host controller to the analog output terminal.	
	Speed control	• Selectable among the four set of the auto speed regulator (ASR) parameters. • Notch filter for vibration control	
	Line speed control	Regulates the motor speed to keep the peripheral speed constant even if the roll winding diameter changes on machines such as winders and unwinders. Tension can be controlled when used in combination with PID control. (A PG option card is required.)	
	Master follower operation	Two motors can be run synchronously using a pulse generator (PG). (A PG option card is required.)	
	Pre excitation	Excitation is carried out to create the motor flux before starting the motor.	
	Zero speed control	Performs speed control by forcibly setting the speed command to zero.	
	Servo lock	Stops the motor and holds the motor in the stopped position.	
	DC braking	• Applies DC current to the motor at the operation start time or at the time of inverter stop to generate braking torque.	
	Mechanical brake control	• It is possible to output mechanical brake control signals with the brake ON/OFF timing adjusted by the output current, torque commands, output frequency and timer. • The output timing of control signals can be adjusted individually when performing • Errors can be detected with mechanical brake operation check input signals.	
	Torque control	• Analog torque command input • Speed limit function is provided to prevent the motor from becoming out of control. • Torque bias (with analog setting, digital setting) possible	
	Rotation direction limitation	Select either of reverse or forward rotation prevention.	
	Motor condensation prevention	Current flows automatically when the motor is stopped, and the motor temperature is raised to prevent condensation.	
	Customizable logic	It is possible to select or connect digital logic circuits or analog operation circuits with digital/analog I/O signals, configure a simple relay sequence, and operate it freely. (The maximum number of steps is 260)	
	Battery operation	Inverters at which an undervoltage has occurred are run with the battery power. 1.5 to 37 kW (type: 0008 to 0180) (200 V class), 1.5 to 55 kW (type: 0004 to 0179) (400 V class)	
	Overload stop function	When used for hoisting applications, the motor stops if the inverter detects excessive torque during ascent. After the overload is detected, operation is possible only in the descend direction.	
	Load adaptive control function	If the load is lighter than the preset load level, operation can be performed at a frequency that is the set frequency multiplied by a specified ratio / the maximum allowable frequency depending on the load (e.g., vertical transportation machines, conveyors).	
	Position control	•Absolute/relative positioning is possible using a pulse encoder •The stop target position can be set by the user's preferred unit system (using electronic gears) via function code (8 point) communication. •Home return, Preset, Clear function, Teaching function •Position regulator (APR), Position feed forward function •Movable range is settable by overtravel detection and stop function	
	Orientation function	This function makes it possible for rotors such as machine tool spindles and turntables to be positioned. Stop target position can be set by a function code (8 points)	
	Pump control	• Cascade operation (drive motor fixed type: 1+8 units, drive motor circulation type: 4 units (when OPC-RY2 is used)) • Operation time equalization function • Boost function • Bite prevention function • Drought detection function • Auxiliary motor control function • Filter clogging prevention function • Check valve protection function • Large water quantity detection function • High-frequency operation detection function	
	Rotary operation	Inverters can be connected to each other using RTU communication (up to 3 units)	
	Wet bulb temperature estimation control	This function estimates the wet-bulb temperature in the fan control of the cooling tower and controls the fan so that the cooling water is linked with the outside air (wet-bulb) temperature to suppress unnecessary power consumption.	
	Scheduled Operation	By combining with the RTC built into the multifunctional keypad (TP-A2SW), it can run/stop the inverter and output external signals. • Can set 4 timers per week • Can set holidays (20 days per year) • Can correct for daylight saving time (DST)	
	Favorites function code	The function code can be registered in "Favorites" and displayed (Applicable to all function codes).	
	Data initialization	All function codes and limited function codes can be initialized.(Per motor, non-communication-related, customized logic only, Favorites only)	

* For details, refer to the FRENIC-MEGA (G2) User's Manual.

	Item		Explanation	Remarks
Control	Simulated operation mode		Sequence check is possible without inverter output.	
	Start check function		To ensure safety, the presence or absence of an operation command is checked at power-on, at alarm reset, and when switching operation command methods. An alarm is displayed if an operation command has been input.	
	Multifunction key		During the operation mode, the multifunction key “M/SHIFT” on LED keypads (TP-E2) can be used as an input method to activate the input terminal function like the X terminal.	
	Traceback		Data (user-selectable) such as frequency, voltage, current, etc., immediately before a trip can be saved and analyzed.	
Display	Running/stopping		Speed monitor (reference frequency, output frequency, motor speed, load shaft speed, line speed, and speed indication percentage), output current [A], output voltage [V], calculated torque [%], power consumption [kW], PID command value, PID feedback value, PID output, load factor [%], motor output [kW], torque current (%), magnetic flux command (%), analog input monitor, input watt hour	
	Inverter lifetime alarm		• It is judged that the life of main circuit capacitors, electrolytic capacitors on PCBs,IGBT or the cooling fan has been reached. • Life alarm information can be output externally. • Ambient temperature: 40 °C Load factor: Inverter rated current of 100% (HHD specification), 80% (HND, HD, ND specification)	
	Cumulative operating status		• The inverter cumulative running time, cumulative input watt hours, and motor cumulative running time/start count (for each motor) is displayed. • A warning is output if the maintenance time or startup count set beforehand is exceeded.	
	Trip		Displays the cause of a trip.	
	Light alarm warnings		The cause of light alarms is displayed.	
	During operation, when trip occurs		• Trip history: The cause (code) of the up to the last four trips is retained and displayed. • All kinds of running status data for up to the past 10 trips is retained and displayed. • Date and time can be displayed in the history by using the clock function (TP-A2SW)	
Protective functions	Overcurrent protection		Stops the inverter to protect it from overcurrent caused by an overload.	0C1 0C2 0C3
	Short circuit protection		Stops the inverter to protect it from overcurrent caused by shorting of the output circuit.	
	Ground fault protection		Detects the overcurrent caused by the ground fault of the output circuit and stops the inverter Protection may be disabled if the power is turned ON with the ground fault still occurring.	
			Detects output current zero-phase current, and stops the inverter to protect it from overcurrent caused by an output circuit ground fault. (5.5 kW or higher)	Ef
	Overvoltage protection		Stops the inverter if a DC intermediate circuit overvoltage (400V series: 800 VDC, 200V series: 400 VDC) is detected. The inverter cannot be protected if an excessively large voltage is applied by accident.	0U1 0U2 0U3
	Undervoltage protection		Stops the inverter if a drop in DC intermediate circuit voltage (400V series: 400 VDC, 200V series: 200 VDC) is detected. However, this is disabled based on the restart after momentary power failure setting. Furthermore, operation is possible (regenerative operation only) at a voltage level lower than that above when performing battery operation.	LU
	Input phase loss protection		Stops the inverter if input voltage phase loss or interphase unbalance factor is detected. If the load is light, or when a DC reactor is connected, input phase loss may not function.	Lin
	Output phase loss protection		Stops the inverter if inverter output phase loss is detected during operation. This protective function also functions during auto tuning and during magnetic pole position tuning. (Operation selection possible)	OPL
	Overheat protection		Stops the inverter if a cooling fan fault, or cooling fin overheating when an overload occurs is detected.	OH1
			Stops the inverter if inverter unit internal charging resistor overheating is detected.	OH3
			Stops the inverter if inverter unit internal charging resistor overheating is detected.	OH6
			By setting the braking resistor electronic thermal overload relay function, the inverter is stopped to protect the braking resistor from overheating.	dbH
	Inverter overload protection		Stops the inverter if overheating is detected by calculating the IGBT internal temperature from the output current and detected internal temperature.	OLU
	External alarm input		Stops the inverter and displays an error if a digital input signal (THR) is input.	OH2
	Fuse blown		Stops the inverter and displays an error if a fuse is blown inside the inverter. (75 kW or higher (type: 0346 to 0432 (200 V))) (90 kW or higher (type: 0261 to 1480 (400 V)))	FUS
	Charging circuit fault		Stops the inverter and displays an error if an inverter charging circuit error is detected. (Type: 0008 to 0432(200 V), Type: 0004 to 1480 (400 V))	PbF
	Braking transistor fault		Stops the inverter and displays an error if a braking transistor error is detected.(Type: 0003 to 0288(200 V), Type: 0002 to 0217(400 V))	dbA
	Motor protection	Electronic thermal overload relay	Stops the inverter if a motor overload is detected by setting the electronic thermal overload relay. Protects general-purpose motors and inverter motors in the entire frequency range. (The operation level and thermal time constant (0.5 to 75.0 minutes) can be set.)	OL1 to OL4
		PTC/NTC thermistor	The motor temperature is detected by the PTC/NTC thermistor, and the inverter is stopped if overheating is detected. To enable this function, connect the PTC/NTC thermistor between terminals [V2] and [11], and enable the switch on the control board.	OH4
		NTC thermistor wire break	The inverter is stopped and an error is displayed if a wire break is detected at the NTC thermistor connected between terminals [V2] and [11].	nrb
	Memory error		When the power is turned ON, a data check is performed when writing data, and an error is displayed if a memory error is detected.	Er1
	Keypad communication error		Stops the inverter and displays an error if a communication fault is detected at the keypad during operation.	Er2
	CPU error		Stops the inverter and displays an error if a CPU error is detected due to noise, etc.	Er3
	Option communication error		Stops the inverter and displays an error if a communication error with the inverter unit is detected when using an option.	Er4
	Option error		Stops the inverter and displays an error if an error is detected at the option side when using an option.	Er5
	Operation error	STOP key priority	Even when run commands are entered via the terminal block or communication, by pressing the keypad STOP button, the inverter forcibly decelerates and stops the motor, and an error is displayed after the motor has come to a stop.	Er6
		Start check	When the power is turned ON, an alarm is cleared, or when switching the run command method from link operation, the sudden starting of operation is suppressed if a run command has been entered, and an error is displayed to notify the operator.	
		Brake status error	Stops the inverter and displays an error if the brake signal (BRKS) output status and brake ON check signal (BRKE) input status do not match.	
	Tuning error		Stops the inverter and displays an error if tuning failure or interruption is detected during motor constant tuning, or if the tuning result is a defect.	Er7
	RS485 communication error (COM port 1)		Stops the inverter and displays an error if a communication error is detected when communicating via RS-485 COM port 1.	Er8

* For details, refer to the FRENIC-MEGA (G2) User’s Manual.

Common Specifications

	Item	Explanation	Remarks
Protective functions	RS485 communication error (COM port 2)	Stops the inverter and displays an error if a communication error is detected when communicating via RS-485 COM port 2.	ErP
	Data saving error during undervoltage	Stops the inverter and displays an error if unable to successfully save data when undervoltage protection is triggered.	ErF
	Position control error	Stops the inverter and displays an error if the positioning deviation is excessive when the servo lock is applied, or when performing master-follower operation.	Ero
	Hardware error	Stops the inverter and displays an error if an inverter internal hardware fault is detected.	ErH
	STOP input (EN1, EN2) terminal circuit error	Stops the inverter and displays an error if the inverter detects an EN1 or EN2 terminal circuit mismatch.	ECF
	PG wire break	Stops the inverter and displays an error if a pulse encoder wire break is detected. (This function is valid on some PG interface option cards.)	PG
	Excessive positioning deviation	Stops the inverter and displays an error if the position deviation is found to be excessive while performing position control.	dO
	Overspeed protection	Stops the inverter and displays an error if the following conditions are met. • If d35 = 999, the speed detection value is the maximum output frequency x (d32 or d33) x 120% or higher • If d35 ≠ 999, the speed detection value is the maximum output frequency x (d35) or higher • The detection value exceeds 599 Hz	OS
	Magnetic pole position detection error	Stops the inverter and displays an error if the signal from the magnetic pole position sensor mounted on the PM motor is abnormal.	ErC
	Step-out detection/ detection failure of magnetic pole position at startup	This occurs when a PM motor step-out is detected, or if magnetic pole position detection fails when starting.	Erd
	Speed inconsistency/ excessive speed deviation	Stops the inverter and displays an error if the state in which the speed deviation between the command speed and detected speed (ASR feedback) is too great continues for the specified time or longer.	ErE
	Password protection	Stops the inverter and displays an error if an attempt is made by a malicious third party to disable the password set by the user.	LoP
	Customizable logic error	Stops the inverter and displays an error if an attempt is made to make changes to customizable logic related settings while the inverter is running.	ECL
	Simulation failure	A simulation failure can be produced if the keypad STOP button and FUNC DATA button are held down for 5 seconds or longer. A simulation failure can be produced even if function code H45 is set to "4".	Err
	Current input terminal signal line break detection	Stops the inverter and displays an error if a line break is detected when current is less than 2 mA when using the current input terminal (terminal [C1] or [C2]) as current input 4 to 20 mA.	CoF
	Customizable logic alarm	An error is displayed if the alarm conditions defined by the user with customizable logic are met. (This is not an error at the inverter itself.)	CA1 to CA5
	EN (STO) terminal OFF	This is displayed if the run command turns ON when both terminal [EN1] and [EN2] are OFF, and the inverter is not ready to perform operation (STO status).	En.OFF
	Minor failure(Warnings)	Cooling fin overheating (OH1), external alarm (OH2), inverter internal overheating (OH3), charging resistor overheating (OH6), braking resistor overheating (dbH), thermistor (NTC) wire break (nrb), motor overload (OL1 to OL4), option communication error (Er4), option error (Er5), RS-485 communication error (COM port 1) (Er8), RS-485 communication error (COM port 2) (ErP), master-follower synchronization error (Ero), position control error (d0), speed does not reach (ErE)/excessive speed deviation (ErE), current input (terminal [C1]/[C2]) wire break detection (CoF), DC fan lock detection (FAL) , Excessive position deviation (d0), Low battery warning/Date and time information loss (Lob) , PID1 feedback error 1,2(PV1,PV2) , Feedback error (External PID)(PVA,PVb,PVC) , Dry-run protection(Pdr),Control of maximum starts per hour(roC), End of curve protection (PoL), Filter clogging error(FoL), Impeller anti-jam (rLo) , Userdefined alarm (CA1 to CA5)	
		Motor overload early warning	OL
		Cooling fin overheat early warning	OH
		Lifetime warning	L iF
		Reference command loss detected	rEF
		PID warning output	P id
		Low torque detection	uFL
		Overheat warning by PTC thermistor in motor	PrC
		Machine life (Cumulative motor running hours)	rFE
		Inverter life (Number of startups)	CnF
		PID control 1,2 warning output	PA1, PA2
		External PID control1,2,3 warning output	PAA, PAb, PAC
		Follower inverter alarm in mutual operation	SLA
		IGBT lifetime warning	iGb
		Reduced air flow warning	rAF
		Relay signals are output while the inverter is stopped due to an alarm. The alarm is cleared with digital input signal "RST". (Reset the alarm using the [PRG/RESET] key on the optional Multi-function keypad.)	
	Retry	The inverter can be automatically reset allowing it to be restarted when it stops due to a trip.(The number of retries and the latency between stop and reset can be specified.)	
	Overload prevention control	• Overload prevention control (Input phase loss): In case of input missing phase, the output frequency is reduced to reduce the load and operation is continued as long as possible. • Overload prevention control (Low voltage): When the output current increases due to a drop in power supply and an overload condition occurs, the output frequency is reduced to reduce the load and operation is continued as long as possible.	
	Surge protection	This function protects the inverter from a surge voltage between main circuit power lines and the ground.	
	Main circuit power cutoff detection	• Inverter operation is not possible when the inverter AC input power supply (main power supply) is not ON. • In such cases as when supplying power via a PWM converter or when using a DC bus bar connection, set main circuit power cutoff detection to "None".	
	Forced operation (Fire mode)	Alarms other than critical alarms are ignored, and a retry is performed forcibly.	
	Usage location	Indoors (environmental standard IEC60721-3-3:3C2); No corrosive gas, flammable gas, dust, oil mist (pollution level 2 (IEC60664-1)); No direct sunlight	

* For details, refer to the FRENIC-MEGA (G2) User's Manual.

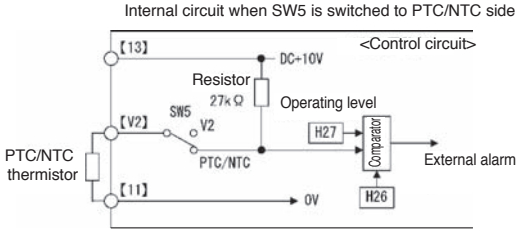
<table>
<tr><th colspan="2">Item</th><th>Explanation</th><th>Remarks</th></tr>
<tr><td rowspan="6">Environmental</td><td>Ambient temperature</td><td>HHD, HND: -10 to +55°C [14 to 131°F] (current derating necessary in +50 to +55°C [122 to 131°F] range)
HD, ND : -10 to +55°C [14 to 131°F] (current derating necessary in +40 to +55°C [104 to 131°F] range)</td><td></td></tr>
<tr><td>Ambient humidity</td><td>5 to 95% RH (avoid condensation)</td><td></td></tr>
<tr><td>Altitude</td><td>1000 m or less</td><td></td></tr>
<tr><td>Vibration</td><td colspan="2"><table>
<tr><th>Type (voltage series)</th><th>2 to less than 9 Hz</th><th>9 to less than 20 Hz</th><th>20 to less than 55 Hz</th><th>55 to 200 Hz</th></tr>
<tr><td>Type: 0115 or lower (200 V)
Type: 0060 or lower (400 V)</td><td rowspan="3">3 mm (max. amplitude)</td><td rowspan="2">9.8 m/s^2</td><td>5.9 m/s^2</td><td rowspan="3">1 m/s^2</td></tr>
<tr><td>Type: 0146 to 0288 (200 V)
Type: 0085 to 0217 (400 V)</td><td rowspan="2">2 m/s^2</td></tr>
<tr><td>Type: 0346 or higher (200 V)
Type: 0261 or higher (400 V)</td><td>2 m/s^2</td></tr>
</table></td><td></td></tr>
<tr><td>Storage temperature</td><td>• -25 to +70°C (during transport)
• -25 to +65°C (during temporary storage)</td><td></td></tr>
<tr><td>Relative humidity</td><td>5 to 95% RH (avoid condensation)</td><td></td></tr>
</table>

* For details, refer to the FRENIC-MEGA (G2) User's Manual.

Table 1.3-2 Output current derating factor relative to altitude

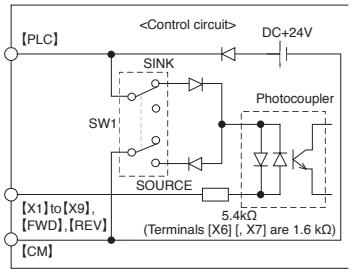
Altitude	Output current derating factor
1,000 m (3,300 ft) or less	1.00
1,000 to 1500 m (3,300 to 4,900 ft)	0.97
1,500 to 2,000 m (4,900 to 6,500 ft)	0.95
2,000 to 2,500 m (6,500 to 8,200 ft)	0.91
2,500 to 3,000 m (8,200 to 9,800 ft)	0.88

Terminal Specifications

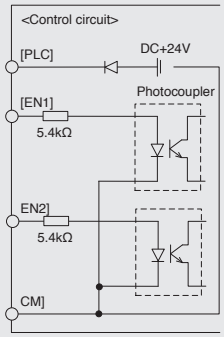
Class	Symbol	Terminal name	Explanation
Main circuit	L1/R,L2/S,L3/T	Main power supply input terminals	Connect a three-phase power supply.
	U,V,W	Inverter output	3-phase motor connection
	P(+),P1	For DC reactor connection	Connect a DC reactor (DCR) (option) for power-factor improvement.
	P(+),N(-)	For DC busbar connection	Use to connect to the DC intermediate circuit of other inverters, PWM converters, etc
	P(+),DB	For braking resistor connection	Connect terminal (+) of the braking resistor (DB) (optional) and the DB (wiring distance: 5 m or less)
	⏚G	For grounding the chassis (case) of the inverter	• This is the earth terminal of the inverter chassis (case) and motor. • Connect one terminal to the ground and the other terminal to the earth terminal of the motor (comes with two terminals).
	R0,T0	Auxiliary control power input	Connect to the power supply when you want to preserve the batch alarm signal during protective function activation (even when the main power of the inverter has been cut off), or when you want to continuously display the keypad (1.5 kW or higher Type: 0008 to 0432 (200 V) Type: 0004 to 1480 (400 V)).
Analog input	【13】	Power supply for variable resistor	• Use as a power supply (+10 V DC) for an external frequency setter (variable resistor: 1 to 5 kΩ). • Use a variable resistor of 1/2 W or more when connecting.
	【12】	Analog setting voltage input	(1) Set the frequency according to the external analog voltage input instruction value. • 0 to ±10 V DC/0 to ±100 (%) (normal action) • +10 to 0 V DC/0 to 100 (%) (reverse action) (2) It supports using analog inputs to assign to frequency settings, PID instructions, PID control feedback signals, auxiliary frequency settings, ratio settings, torque limiting settings, torque instruction values/torque current instruction values, speed limiting values, analog input monitors and other items. (3) Hardware specification * Input impedance: 22 (kΩ) * Can input up to ±15 V DC. However, it will be deemed to be ±10 V DC for any value that exceeds ±10 V DC. * Set function code C35 to "0" when inputting the analog setting voltage of both poles (0 to ±10 V DC) at terminal [12].
	【C1】	Analog setting current input (C1 function)	(1) Set the frequency according to the external analog current input instruction value. • 4 to 20 mA DC/0 to 100 (%), 0 to 20 mA DC/0 to 100 (%) (normal action) • 20 to 4 mA DC/0 to 100 (%), 20 to 0 mA DC/0 to 100 (%) (reverse action) (2) It supports using analog inputs to assign to frequency settings, PID instructions, PID control feedback signals, auxiliary frequency settings, ratio settings, torque limiting settings, torque instruction values/torque current instruction values, speed limiting values, analog input monitors and other items. (3) Hardware specifications * Input impedance: 250 (Ω) * Can input up to 30 mA DC. However, it will be deemed to be 20 mA DC for any value that exceeds 20 mA DC.
		Analog setting voltage input (V3 function)	(1) Set the frequency according to the external analog voltage input instruction value. • 0 to ±10 V DC/0 to ±100 (%) (normal action) • +10 to 0 V DC/0 to 100 (%) (reverse action) (2) It supports using analog inputs to assign to frequency settings, PID instructions, PID control feedback signals, auxiliary frequency settings, ratio settings, torque limiting settings, torque instruction values/torque current instruction values, speed limiting values, analog input monitors and other items. (3) Hardware specifications * Input impedance: 22 (kΩ) * Can input up to ±15 V DC. However, it will be deemed to be ±10 V DC for any value that exceeds ±10 V DC. * Set function code C78 to "0" when inputting the analog setting voltage of both poles (0 to ±10 V DC) at terminal [V3].
	【V2】	Analog setting voltage input (V2 function)	(1) Set the frequency according to the external analog voltage input instruction value. • 0 to ±10 V DC/0 to ±100 (%) (normal action) • +10 to 0 V DC/0 to 100 (%) (reverse action) (2) It supports using analog inputs to assign to frequency settings, PID instructions, PID control feedback signals, auxiliary frequency settings, ratio settings, torque limiting settings, torque instruction values/torque current instruction values, speed limiting values, analog input monitors and other items. (3) Hardware specifications * Input impedance: 22 (kΩ) * Can input up to ±15 V DC. However, it will be deemed to be ±10 V DC for any value that exceeds ±10 V DC. * Set function code C45 to "0" when inputting the analog setting voltage of both poles (0 to ±10 V DC) at terminal [V2].
		PTC/NTC thermistor input (PTC/NTC function)	(1) A PTC/NTC thermistor can be connected to protect the motor. (2) The PCB's SW5 switch needs to be switched to PTC/NTC side. • The figure below shows the internal circuit when SW5 (the switch for terminal [V2]) is switched to the PTC/NTC side. • When SW5 is switched to PTC/NTC side, function code H26 also needs to be changed. Internal circuit when SW5 is switched to PTC/NTC side 
	【11】	Analog common	• Common terminals for analog I/O signals (terminals [13], [12], [C1], [V2], [FM1], and [FM2]). • Insulated against terminals [CM] and [CMY].

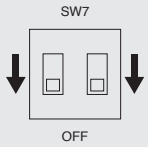
* For details, refer to the FRENIC-MEGA (G2) User's Manual.

<table>
<tr><th>Class</th><th>Symbol</th><th>Terminal name</th><th>Explanation</th></tr>
<tr><td rowspan="12">Analog input</td><td>【X1】</td><td>Digital input 1</td><td rowspan="11">(1) Various signals (coast to stop command, external alarms, multistep frequency selection, etc.) can be set for terminals [X1] to [X9], [FWD], and [REV].
(2) The input mode and SINK/SOURCE can be switched using SW1.
(3) The operating mode between each digital input terminal and terminal [CM] can be switched to "ON when shorted (active ON)" or "OFF when shorted (active OFF)".
(4) Digital input terminals [X6] and [X7] can be set up as pulse train input terminals by changing the function code.
• When connected to complementary output pulse generator: max. 100 Hz
• When connected to open collector output pulse generator: max. 30 Hz
(A pull-up resistor and pull-down resistor are required.)

<Digital input circuit specifications>
Digital input circuit
 

<table>
<tr><th colspan="2">Item</th><th>Min.</th><th>Max.</th></tr>
<tr><td rowspan="2">Operating voltage (SOURCE)</td><td>ON level</td><td>0V</td><td>2V</td></tr>
<tr><td>OFF level</td><td>20V</td><td>27V</td></tr>
<tr><td rowspan="2">Operating voltage (SINK)</td><td>ON level</td><td>20V</td><td>27V</td></tr>
<tr><td>OFF level</td><td>0V</td><td>2V</td></tr>
<tr><td colspan="2">Operating current when ON (when input voltage 27 V) (X6/X7 input terminals)</td><td>2.5mA (3mA)</td><td>5mA (16mA)</td></tr>
<tr><td colspan="2">Permissible leakage current when OFF</td><td>—</td><td>0.5mA</td></tr>
</table></td></tr>
<tr><td>【X2】</td><td>Digital input 2</td></tr>
<tr><td>【X3】</td><td>Digital input 3</td></tr>
<tr><td>【X4】</td><td>Digital input 4</td></tr>
<tr><td>【X5】</td><td>Digital input 5</td></tr>
<tr><td>【X6】</td><td>Digital input 6</td></tr>
<tr><td>【X7】</td><td>Digital input 7</td></tr>
<tr><td>【X8】</td><td>Digital input 8</td></tr>
<tr><td>【X9】</td><td>Digital input 9</td></tr>
<tr><td>【FWD】</td><td>Forward・rotation/stop command Input</td></tr>
<tr><td>【REV】</td><td>Reverse・rotation/stop command Input</td></tr>
<tr><td>【EN1】
【EN2】</td><td>Enable input</td><td>(1) When the terminal between [EN1] and [-PLC] or between [EN2] and [-PLC] is OFF, the operation of the inverter's output transistor will be stopped (Safe torque off: STO).
Always make sure to operate terminals [EN1] and [EN2] simultaneously.
If the terminals are not operated simultaneously, the eCf alarm will trigger and this will prevent the inverter from operating.
(2) The input mode of terminals [EN1] and [EN2] is fixed to the source and cannot be switched to the sink.
(3) SW7 can be used to enable or disable this function.
To use this function, set each SW7 switch to OFF.

<Enabling input circuit specifications>
 



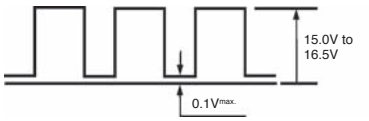
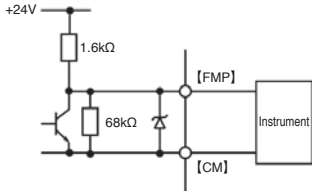
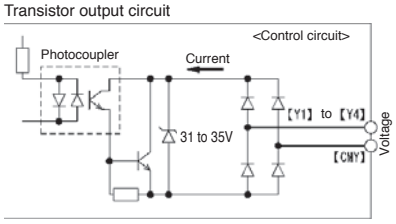
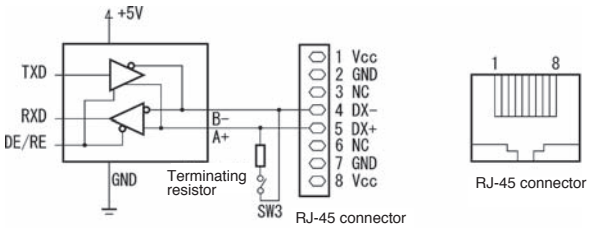
<table>
<tr><th colspan="2">Item</th><th>Min.</th><th>Max.</th></tr>
<tr><td rowspan="2">Operating voltage (SOURCE)</td><td>ON level</td><td>20V</td><td>27V</td></tr>
<tr><td>OFF level</td><td>0V</td><td>2V</td></tr>
<tr><td colspan="2">Operating current when ON (when input voltage 27 V)</td><td>2.5mA</td><td>10mA</td></tr>
<tr><td colspan="2">Permissible leakage current when OFF</td><td>—</td><td>0.5mA</td></tr>
</table></td></tr>
<tr><td>【PLC】</td><td>Programmable controller signal power supply</td><td>(1) Connect the output signal power supply for the programmable controller.
(Rated voltage +24 VDC (power supply voltage fluctuation range: +20.4 to +27 VDC), maximum 100 mA DC)
(2) The terminal can also be used as the power supply for loads connected to transistor outputs</td></tr>
<tr><td>【CM】</td><td>Digital common</td><td>This is a common terminal for digital input signals.
The terminal is insulated from terminals [11] and [CMY].</td></tr>
<tr><td rowspan="3">Analog output</td><td>【FM1】
【FM2】</td><td>Analog monitor
(FMA function)</td><td>This function outputs a monitor signal of analog DC voltage 0 to ±10 V DC, analog DC current 4 to 20 mA DC, or 0 to 20 mA DC.
The [FM1] output format (VO1/IO1) is switched by the PCB's SW4 switch and function code F29.
The content of the signal is selected from the following items based on the data setting of function code F31.
The [FM2] output format (VO2/IO2) is switched by the PCB's SW6 switch and function code F32.
The content of the signal is selected from the following items based on the data setting of function code F61.

Output frequency / Power consumption / Motor output
Output current / PID feedback amount / Analog output test
Output voltage / Speed detection（PG feedback value） / PID command
Output torque / Intermediate DC voltage / PID output
Load factor / Universal AO / Master-follower angle deviation and other items.

* Connectable impedance: Minimum of 5 kΩ (when outputting 0 to ±10 V DC) (up to two analog voltmeters (0 to 10 V DC, input impedance of 10 kΩ) can be connected.)
* Connectable impedance: Maximum of 500 Ω (at 4 m to 20 mA DC output)
* Gain adjustment range: 0 to 300%</td></tr>
<tr><td>【11】</td><td>Analog common</td><td>This is a common terminal for analog input/output signals.
This terminal is isolated from terminals [CM] and [CMY].</td></tr>
</table>

* For details, refer to the FRENIC-MEGA (G2) User's Manual.

Terminal Specifications

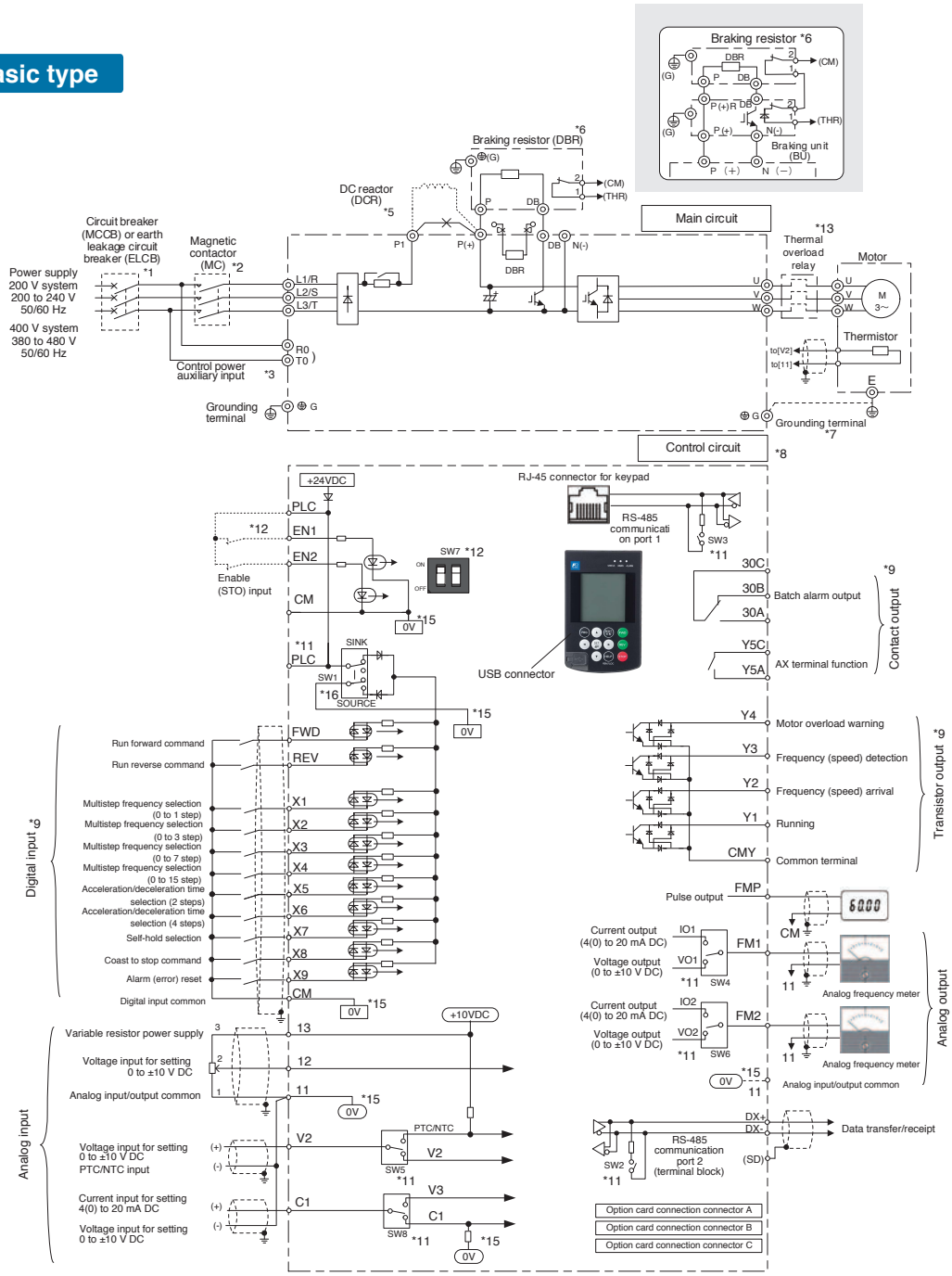
<table>
<tr><th>Class</th><th>Symbol</th><th>Terminal name</th><th>Explanation</th></tr>
<tr><td rowspan="2">Analog output</td><td>【FMP】</td><td>Pulse monitor
(FMP function)</td><td>This function outputs pulse signals. The content of the signal can be selected in the same way as the FM1/2 function by setting the function code F35.
* Connectable impedance: Minimum of 5 kΩ (up to two analog voltmeters (0 to 10 V DC, input impedance of 10 kΩ) can be connected.)
* Pulse duty: About 50%; Pulse rate: 25 to 6000 p/s (at full scale)
Pulse output waveform
 
FMP output circuit
  </td></tr>
<tr><td>【CM】</td><td>Digital common</td><td>This is a common terminal for digital input signals and terminal [FMP] output.
The terminal is insulated from terminals [11] and [CMY]. This is the same terminal as terminal [CM] for digital input.</td></tr>
<tr><td rowspan="5">Transistor output</td><td>【Y1】</td><td>Transistor output 1</td><td rowspan="4">(1) Various signals (running signals, frequency arrival signals, overload early warning signals, etc.) set with function codes E20 to E23 can be output.
(2) The operating mode between transistor output terminals [Y1] and [Y4] and terminal [CMY] can be switched to "ON when signal output (active ON)" or "OFF when signal output (active OFF)".
<Transistor output circuit specifications>
Transistor output circuit
 
<table><tr><th colspan="2">Item</th><th>Max.</th></tr><tr><td rowspan="2">Operating voltage</td><td>ON level</td><td>2V</td></tr><tr><td>OFF level</td><td>48V</td></tr><tr><td colspan="2">Operating current when ON</td><td>50mA</td></tr><tr><td colspan="2">Leakage current when OFF</td><td>0.1mA</td></tr></table></td></tr>
<tr><td>【Y2】</td><td>Transistor output 2</td></tr>
<tr><td>【Y3】</td><td>Transistor output 3</td></tr>
<tr><td>【Y4】</td><td>Transistor output 4</td></tr>
<tr><td>【CMY】</td><td>Transistor output common</td><td>This is a common terminal for transistor output signals.
This terminal is isolated from terminals [CM] and [11].</td></tr>
<tr><td rowspan="2">Analog output</td><td>【Y5A】
【Y5C】</td><td>General-purpose relay output</td><td>(1) The same signals as those of terminals [Y1] to [Y4] can be selected and output as multi-purpose relay outputs.
Contact capacity: 250 VAC 0.3 A cosϕ = 0.3, 48 VDC 0.5 A
(2) It is possible to switch between a "short circuit between terminals [Y5A] and [Y5C] when an ON signal is output (excitation: active ON)" or an "open circuit between terminals [Y5A] and [Y5C] when an ON signal is output (non-excitation: active OFF)".</td></tr>
<tr><td>【30A】
【30B】
【30C】</td><td>Integrated alarm output</td><td>(1) When the inverter stops with an alarm, an integrated alarm is output at the relay contact (1C).
Contact capacity: 250 VAC 0.3 A cosϕ = 0.3, 48 VDC 0.5 A
(2) The same signals as those of terminals [Y1] to [Y4] can be selected and output.
(3) It is possible to switch between a "short circuit between terminals [30A] and [30C] when an ON signal is output (excitation: active ON)" or an "open circuit between terminals [30A] and [30C] when an ON signal is output (non-excitation: active OFF)".</td></tr>
<tr><td rowspan="3">Communication</td><td>【DX+】
【DX-】
【SD】</td><td>RS-485 COM port 2
(terminal block)</td><td>• This is an input/output terminal used to connect a personal computer or programmable controller, etc. by RS-485 communication.
• Use the recommended stick terminal when making a daisy chain connection.</td></tr>
<tr><td>RJ-45 connector
Keypad</td><td>RS-485 COM port 1
(for keypad connection)</td><td>(1) This is used as a connector for connecting the keypad. The keypad power is supplied from the inverter via an extension cable for remote operation.
(2) This is used to connect a personal computer or programmable controller, etc. by RS-485 communication after disconnecting the keypad.
Connector pin assignment
 
• Pins 1, 2, 7, and 8 are assigned as the keypad's power source.
• Do not use these pins when connecting the RJ-45 connector to other devices.</td></tr>
<tr><td>USB connector</td><td>USB port (on keypad)</td><td>• This is a USB connector (mini B) for connecting to a personal computer.
• Use the inverter support loader (FRENIC loader) to edit, transfer, and verify function codes, perform test operations for the inverter, and monitor various statuses.</td></tr>
</table>

* For details, refer to the FRENIC-MEGA (G2) User's Manual.

Basic Wiring Diagram

Wiring of main circuit terminal and grounding terminal

Basic type



*1 Install the molded case circuit breaker (MCCB) or earth leakage circuit breaker (ELCB) (with overcurrent protection function) recommended for each inverter on the inverter input side (primary side) to protect wiring. Do not use a circuit breaker that exceeds the recommended rated current.

*2 An MCCB or ELCB is also used if isolating the inverter from the power supply, and therefore the magnetic contactor (MC) recommended for each inverter should be installed if required. Please note that if installing a coil such as an MC or solenoid near the inverter, connect a surge absorber in parallel.

*3 If wishing to retain the integrated alarm signal issued if the protective function is triggered even when the inverter main power supply is cut off, or to constantly display the keypad, connect these terminals to the power supply. (on FRN0008G2□-2G or higher /FRN0008G2□-4G or higher)
The inverter can be run even without inputting the power supply to these terminals.

*5 Remove the shorting bar between the inverter main circuit terminals P1 and P(+) before connecting the DC reactor (DCR) (option). Be sure to connect the DC reactor in the case of FRN0139G2□-4G ND / FRN0288G2□-2G HND / FRN0179G2□-4G HND, HD, ND specification and FRN0346G2□-2G or higher / FRN0217G2□-4G or higher inverters. Use a DC reactor (DCR) when the capacity of the power supply transformer is 500 kVA or more and is 10 times or more the inverter rated capacity, or when there are “thyristordriven” loads.

*6 FRN0288G2□-2G or lower / FRN0217G2□-4G or lower inverters are equipped with a built-in braking transistor, allowing direct connection of braking resistors between P(+) and DB.
If connecting a braking resistor (DB) (option) to FRN0346G2□-2G or higher / FRN0261G2□-4G or higher inverters, a braking unit (BU) (option) is necessary. A built-in braking resistor is connected between terminals P(+) and DB on FRN0046G2□-2G or lower /FRN0023G2□-4G or lower inverters. If connecting a braking resistor (DB), be sure to disconnect the built-in braking resistor.

*7 This terminal is used for grounding the motor. Connect if required.

*8 Use twisted wire or shielded wire for control signal lines.
Shielded wires are generally grounded, however, if subject to significant induction noise from outside, it may be possible to suppress the effect of the noise by connecting wires to [CM]. Isolate control signal lines from the main circuit wiring as best as possible, and do not run inside the same duct (a distance of 10 cm or greater is recommended.) If lines intersect, ensure that they do so almost perpendicularly to the main circuit wiring.

*9 Each of the functions described for terminals [FWD] and [REV], terminals [X1] to [X9] (digital input), terminals [Y1] to [Y4] (transistor output), terminal [Y5A/C], and terminal [30A/B/C] (contact output) indicate functions assigned by factory default.

*11 These are the switches on control PCBs, and are used to specify settings for inverter operation. Refer to the User’s Manual, “2.2.7 Switching switches” for details.

*12 Safety function terminals [EN1] and [EN2] are disabled with SW7 (2-pole switch) on the control PCB by factory default. If using this terminal function, be sure to change the respective SW7 switches to the OFF position and connect.

*13 The thermal overload relay is applicable as necessary. Make the circuit breakers (MCCB) or the magnetic contactors (MC) trip by the thermal relay auxiliary contacts (manual recovery).

*15 [0V] and (0V) are separated and insulated.

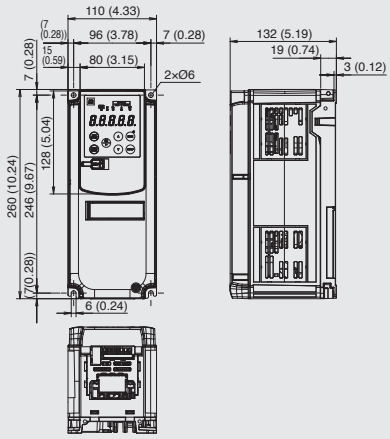
*16 The factory default setting for SW1 of FRN-G2E-4G is “SOURCE”.

External Dimensions

Basic type **EMC Filter Built-in Type**

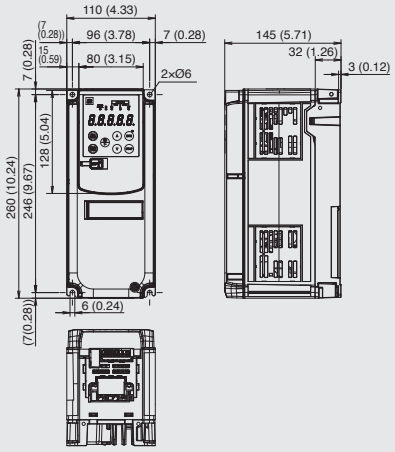
Type FRN0003G2□-2G, FRN0002G2□-4G

[Unit: mm (inch)]



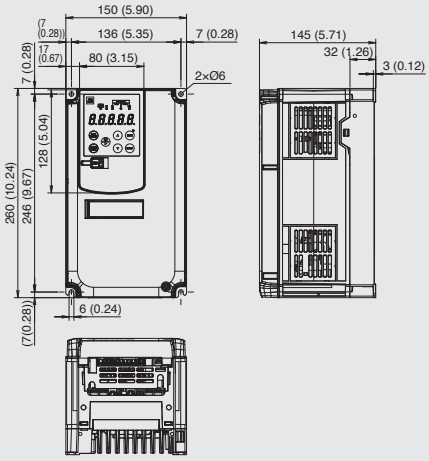
Type FRN0005G2□-2G, FRN0003G2□-4G

[Unit: mm (inch)]



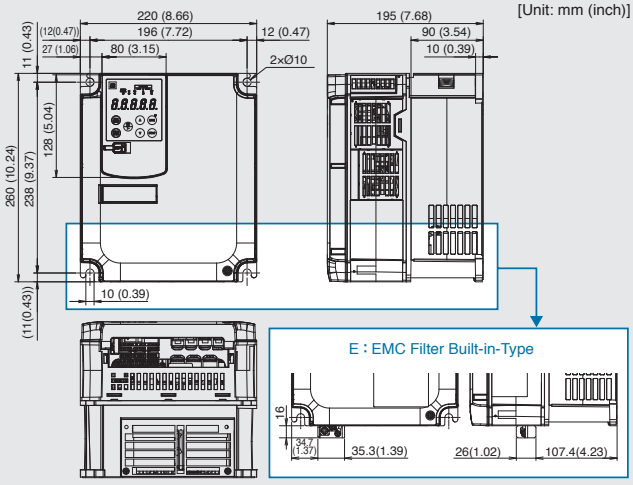
Type FRN0008G2□-2G to FRN0018G2□-2G, FRN0004G2□-4G to FRN0009G2□-4G

[Unit: mm (inch)]



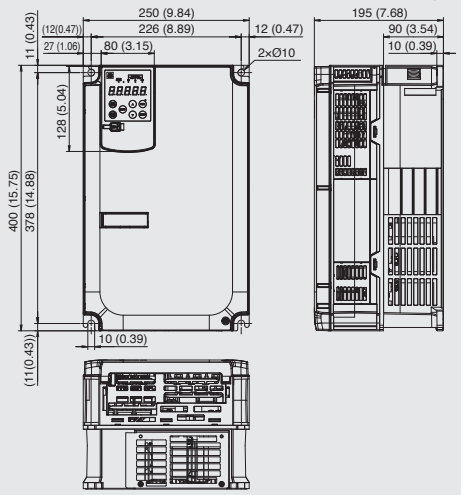
Type FRN0032G2□-2G to FRN0059G2□-2G, FRN0018G2□-4G to FRN0035G2□-4G

[Unit: mm (inch)]



Type FRN0075G2□-2G to FRN0115G2□-2G, FRN0041G2□-4G to FRN0060G2□-4G

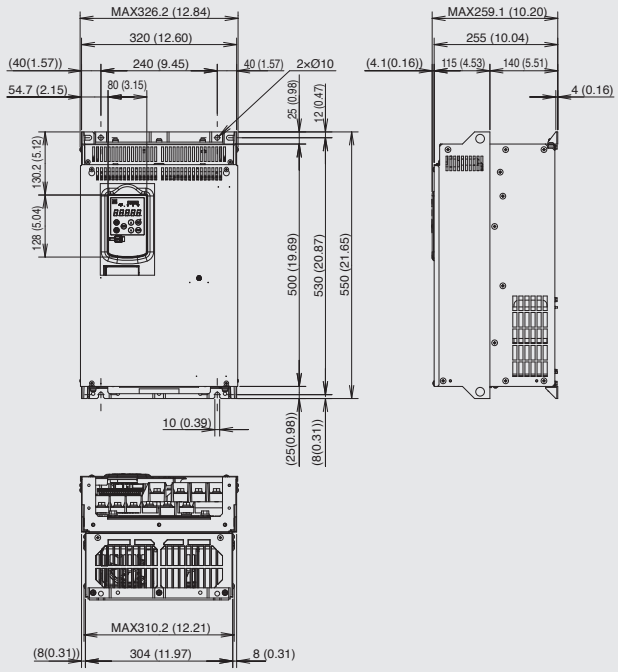
[Unit: mm (inch)]



Basic type

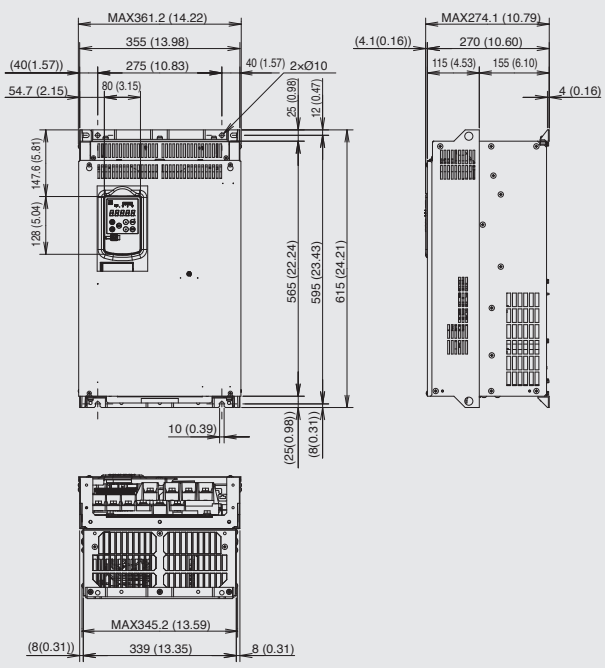
Type FRN0146G2□-2G, FRN0085G2□-4G, FRN0105G2□-4G

[Unit: mm (inch)]



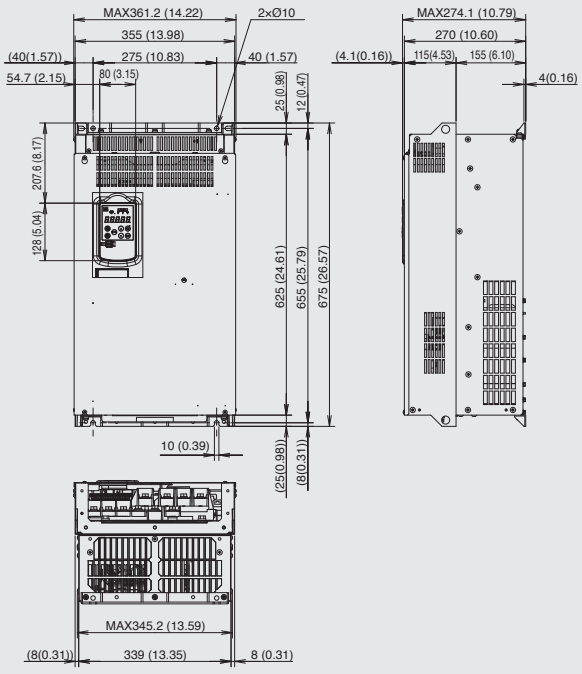
Type FRN0180G2□-2G, FRN0139G2□-4G

[Unit: mm (inch)]



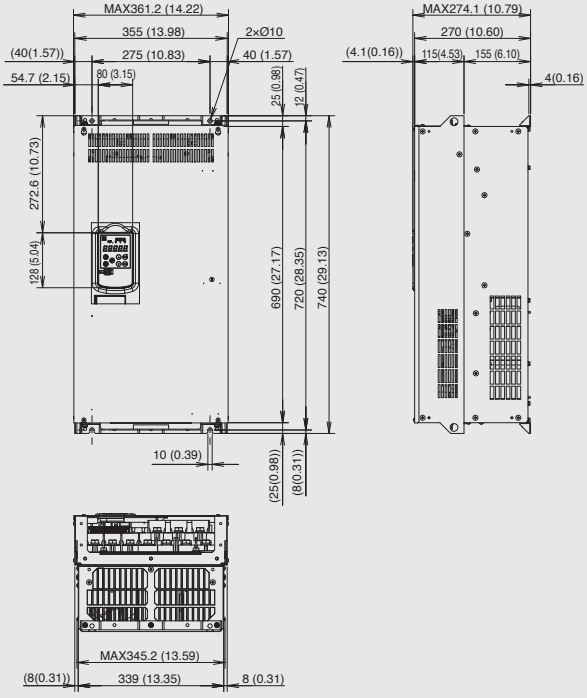
Type FRN0179G2□-4G

[Unit: mm (inch)]



Type FRN0215G2□-2G, FRN0288G2□-2G, FRN0217G2□-4G

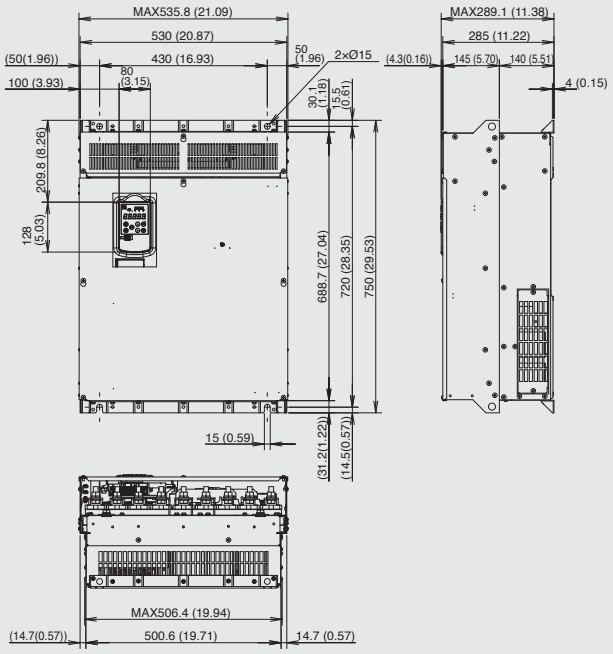
[Unit: mm (inch)]



Basic type

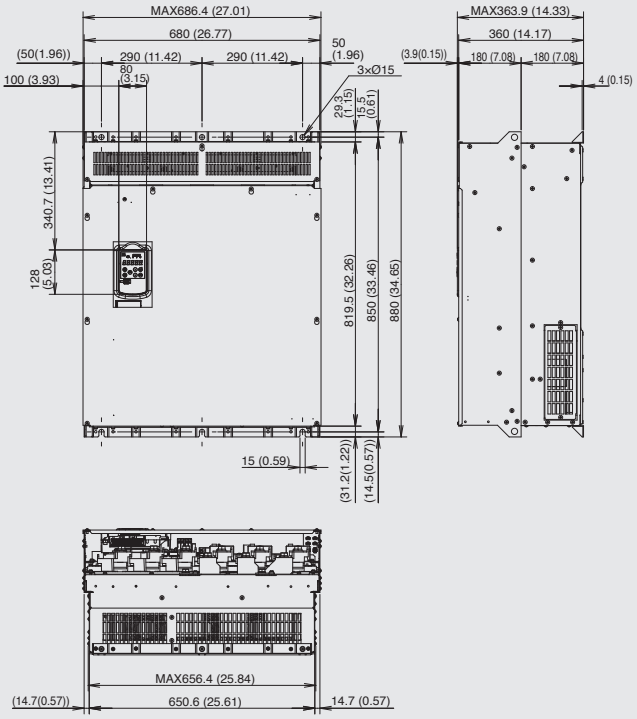
Type FRN0346G2□-2G

[Unit: mm (inch)]



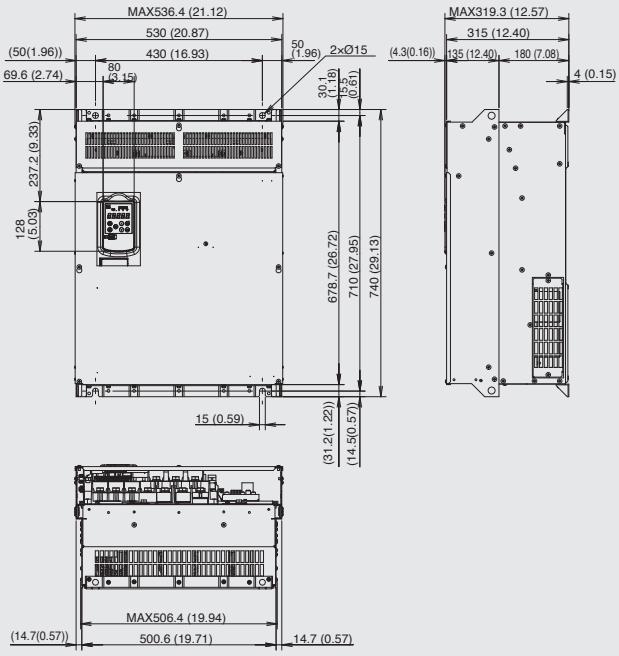
Type FRN0432G2□-2G

[Unit: mm (inch)]



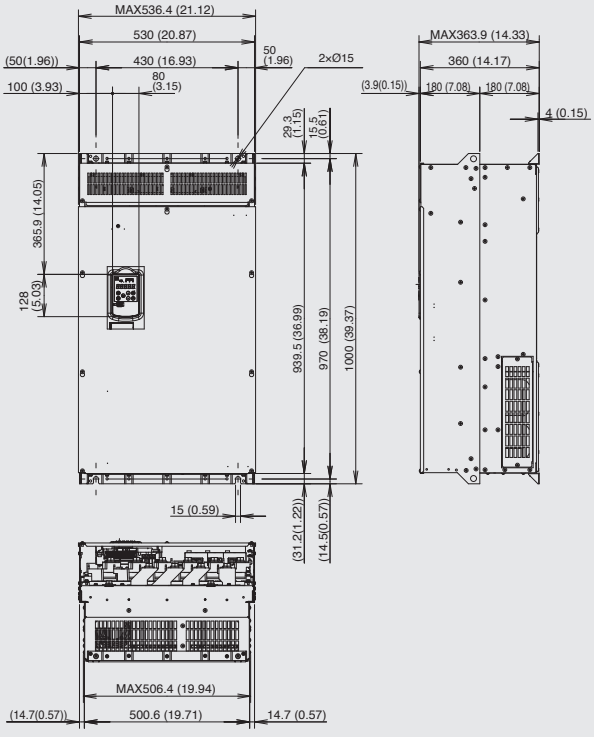
Type FRN0261G2□-4G, FRN0290G2□-4G

[Unit: mm (inch)]



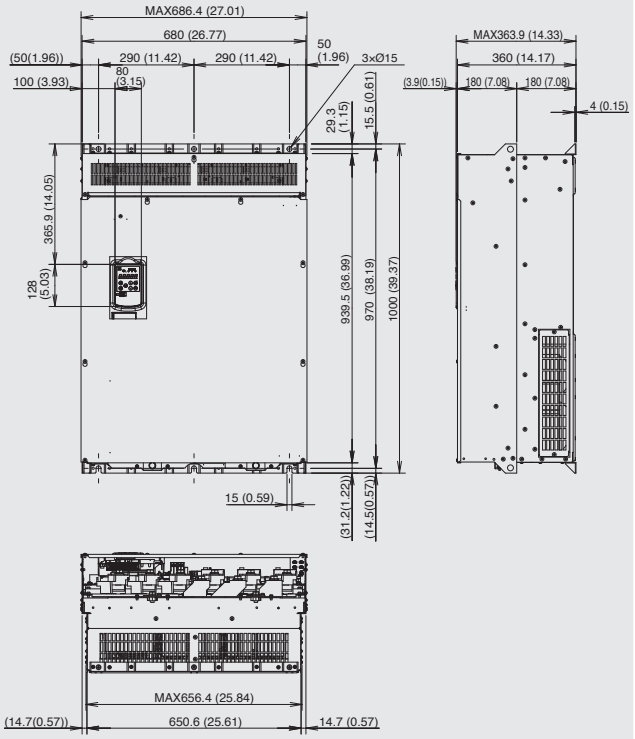
Type FRN0376G2□-4G, FRN0431G2□-4G

[Unit: mm (inch)]



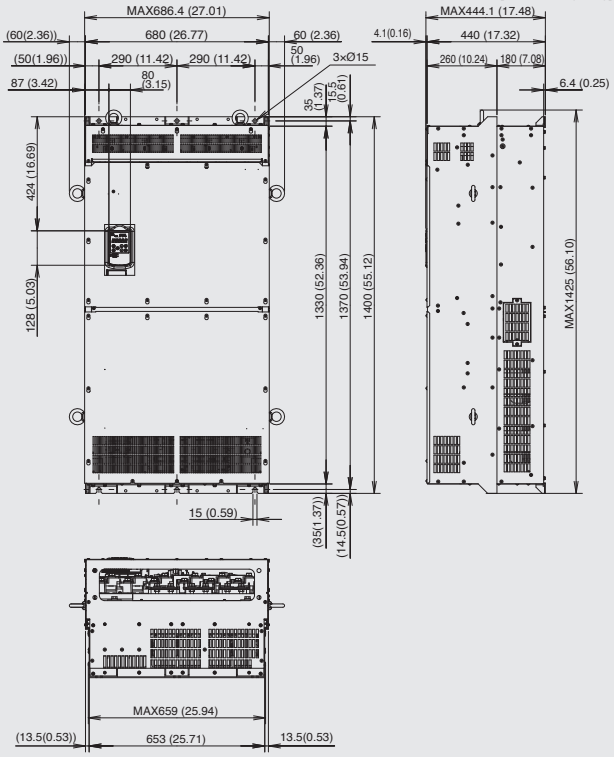
Type FRN0547G2□-4G, FRN0610G2□-4G

[Unit: mm (inch)]



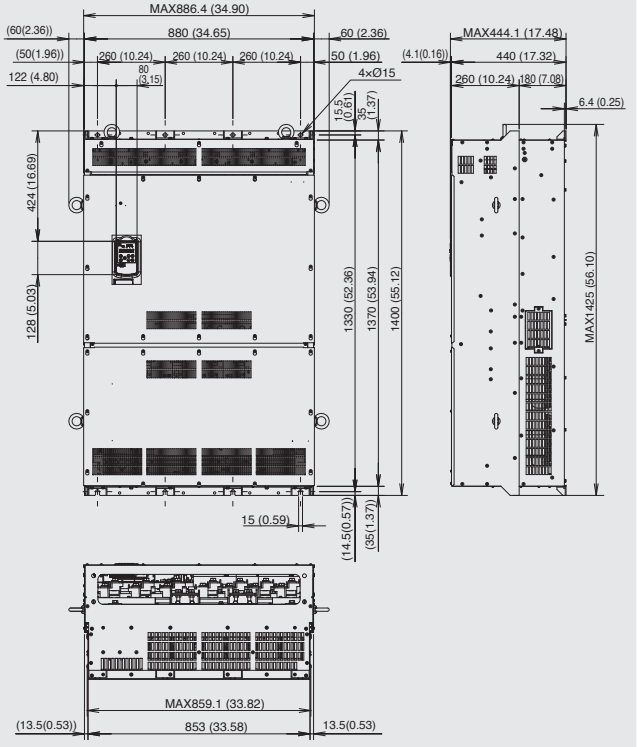
Type FRN0739G2□-4G, FRN0840G2□-4G

[Unit: mm (inch)]



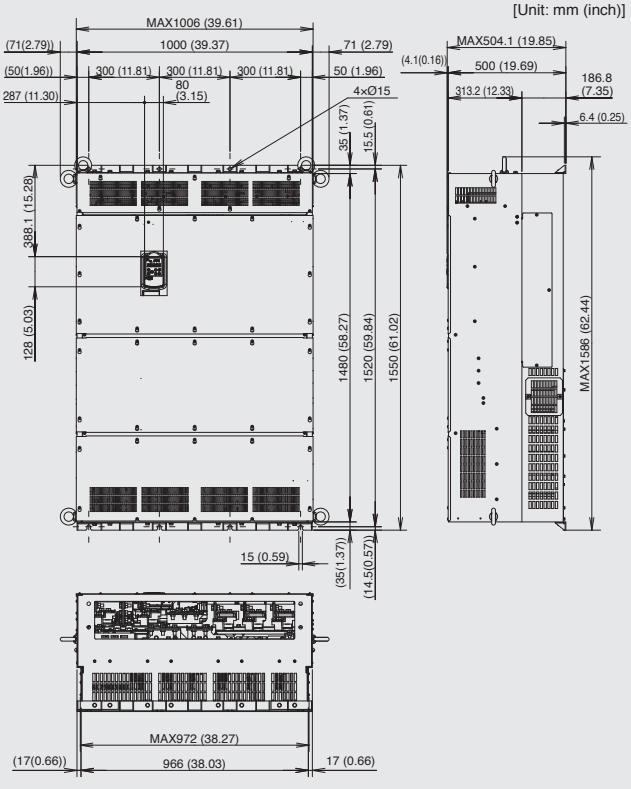
Type FRN1039G2□-4G, FRN1169G2□-4G

[Unit: mm (inch)]



Type FRN1385G2□-4G, FRN1480G2□-4G

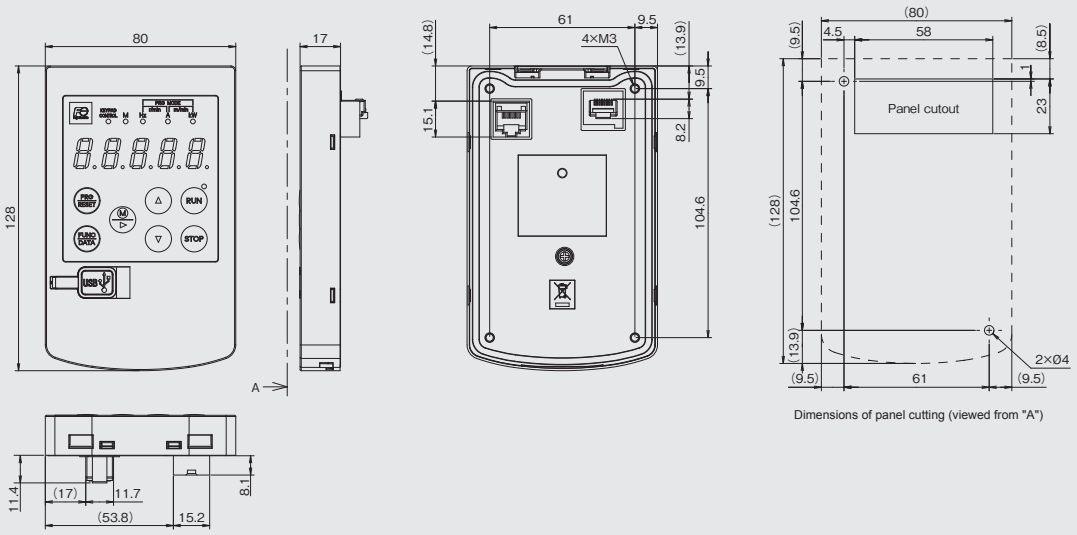
[Unit: mm (inch)]



Keypad

(USB connector model) Type : TP-E2 Option

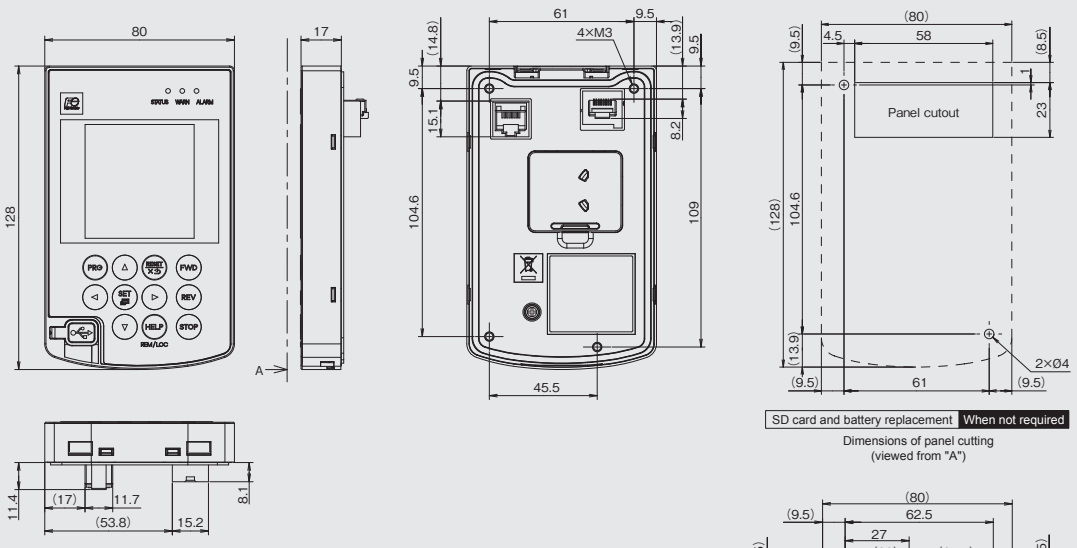
[Unit: mm]



Dimensions of panel cutting (viewed from "A")

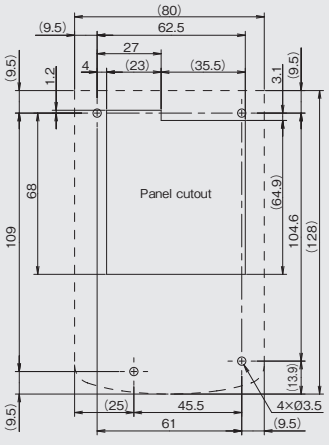
Multi-functional (USB connector model) Type : TP-A2SW Standard

[Unit: mm]



SD card and battery replacement | When not required

Dimensions of panel cutting (viewed from "A")



SD card and battery replacement | When required

Dimensions of panel cutting (viewed from "A")

Keypad Functions

Use the keypad to start and stop the inverter, display various data, set function code data, check I/O, and display maintenance and alarm information.

Table 3.2 Overview of Keypad/USB port Functions

Keys		Functions
Program key	PRG	This key switches the operation modes between Running mode/Alarm mode and Programming mode.
RESET key	RESET	Reset key which works as follows according to the operation modes. ■ In Running mode: This key cancels the screen transition. ■ In Programming mode: This key resets the alarm states and switches to Programming mode. ■ In Alarm mode: This key discards the settings being configured and cancels the screen transition.
UP/DOWN/ LEFT/RIGHT arrow key	▲ / ▼	UP/DOWN key which works as follows according to the operation modes. ■ In Running mode: These keys switch to the digital reference frequency and PID command modification screen (when commands from the keypad are enabled). ■ In Programming mode: These keys display multiple alarms and alarm history. ■ In Alarm mode: These keys select menu items, change data, and scroll the screen.
	◄ / ►	These keys move the cursor to the digit of data to be modified, shift the setting item, and switch the screen.
SET key	SET	Set key which works as follows according to the operation modes. ■ In Running mode: Pressing this key switches to the selection screen of the main monitor content. ■ In Programming mode: Pressing this key switches to the alarm detailed information screen. ■ In Alarm mode: Pressing this key established the selected items and data being changed.
HELP key	HELP REM/LOC	Pressing this key calls up the HELP screen according to the current display state. Holding it down for 2 seconds toggles between the remote and local modes.
Run key (forward)	FWD	Pressing this key starts running the motor in the forward rotation (when a run command from the keypad is enabled).
Run key (reverse)	REV	Pressing this key starts running the motor in the reverse rotation (when a run command from the keypad is enabled).
STOP key	STOP	Pressing this key stops the motor (when a run command from the keypad is enabled or the STOP key priority is selected).
USB port		The inverter and computer can be connected with a USB cable. The connector type at the inverter side is a miniB type.

Table 3.1 Indication of LED Indicators

LED Indicators	Indication	
STATUS (Green)	Shows the inverter running state.	
	Flashing	No run command input (Inverter stopped)
	ON	Run command input
WARN (Yellow)	Shows the warning state.	
	OFF	No warning has occurred.
	Flashing /ON	A warning has occurred.
ALARM (Red)	Shows the alarm state (alarm).	
	OFF	No alarm has occurred.
	Flashing	A alarm has occurred.

1. **LED indicators:**
   These indicators show the current running status of the inverter.
2. **LCD monitor:**
   This monitor shows the following various information about the inverter according to the operation modes.
3. **Keys/USB port**
   These keys are used to perform various inverter operations.

Function Codes

F codes :Fundamental functions

Function code	Name	Control method and Data setting range	Change when running	Data copying
F00	Data protection	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: No data protection, no digital setting protection 1: With data protection, no digital setting protection 2: No data protection, with digital setting protection 3: With data protection, with digital setting protection	Y	Y
F01	Frequency setting 1	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Keypad key operation (/ keys) 1: Analog voltage input (Terminal [12]) (from 0 to ±10 VDC) 2: Analog current input (Terminal [C1] (4 to 20 mA DC) 3: Analog voltage input (Terminal [12]) + analog current input (Terminal [C1]) 5: Analog voltage input (Terminal [V2]) (from 0 to ±10 VDC) 6: Analog voltage input (Terminal [V3]) (from 0 to ±10 VDC) 7: UP/DOWN control 8: Keypad key operation (/ keys) (with balanceless bumpless) 10: Pattern operation 11: Digital input interface card OPC-DI (option) 12: Pulse train input	N	Y
F02	Operation method	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Keypad operation (Rotation direction input: terminal block) 1: External signal (digital input) 2: Keypad operation (forward rotation) 3: Keypad operation (reverse rotation)	N	Y
F03	Maximum output frequency 1	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 5.0 to 599.0 Hz	N	Y
F04	Base frequency 1	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 5.0 to 599.0 Hz	N	Y
F05	Rated voltage at base frequency 1	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: AVR disable (output voltage proportional to power voltage) 80 to 240 V: AVR operation (200V series) 160 to 500 V: AVR operation (400 V series)	N	Y2
F06	Maximum output voltage 1	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 80 to 240 V: AVR operation (200V series) 160 to 500 V: AVR operation (400 V series)	N	Y2
F07	Acceleration time 1	V/f PGV/f SLV PGV PM SLV PM PGV TRQ	Y	Y
F08	Deceleration time 1	0.00 to 6000s * 0.00 is for acceleration and deceleration time cancel (when performing soft-start and stop externally)	Y	Y
F09	Torque boost 1	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.0 to 20.0% (% value against base frequency voltage 1)	Y	Y
F10	Electronic thermal overload protection for motor 1 (Select motor characteristics)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 1: Enable (for a general-purpose motor with self-cooling fan) 2: Enable (for an inverter-driven motor with separately powered cooling fan)	Y	Y
F11	(Operation level)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 A (disable), current value of 1 to 135% of inverter rated current set with A unit	Y	Y1 Y2
F12	(Thermal time constant)	0.5 to 75.0min	Y	Y
F14	Restart mode after momentary power failure (operation selection)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Trip immediately 1: Trip after a recovery from power failure 2: Trip after momentary deceleration is stopped 3: Continue to run (for heavy inertia load or general load) 4: Restart from frequency at power failure (for general load) 5: Restart from starting frequency	Y	Y
F15	Frequency limiter (upper limit)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.0 to 599.0Hz	Y	Y
F16	(Lower limit)			
F18	Bias (for frequency setting 1)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ -100.00 to 100.00%	Y*	Y
F20	DC braking 1 (starting frequency)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.0 to 60.0Hz	Y	Y
F21	DC braking 1 (Operation level)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0 to 100% (HHD specification), 0 to 80% (HND specification), 0 to 80% (HD specification), 0 to 60% (ND specification),	Y	Y
F22	(Braking time)	0.00 (disable): 0.01 to 30.00 s	Y	Y

*2 A standard value is set for each capacity. *3 The rated current of the motor is set. For details, refer to the FRENIC-MEGA (G2) User's Manual.
*10 6.00 s for 22 kW or less, and 20.00 s for 30 kW or more. *11 5.0 min. for 22 kW or less, and 10.0 min. for 30 kW or more.

F codes :Fundamental functions

Function code	Name	Control method and Data setting range	Change when running	Data copying
F23	Starting frequency 1	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.0 to 60.0 Hz If F42 = 5 or 15, 1.0 Hz is automatically set.	Y	Y
F24	(Holding time)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 to 10.00s	Y	Y
F25	Stop frequency	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.0 to 60.0Hz	Y	Y
F26	Motor sound (Carrier frequency)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ	Y	Y
F27	(Tone)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Level 0 (disable) 1: Level 1 2: Level 2 3: Level 3	Y	Y
F29	Terminal [FM1] (Operation selection)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Voltage output (0 to +10 VDC) 1: Current output (4 to 20 mA DC) 2: Current output (0 to 20 mA DC) 4: Voltage output (0 to +10 VDC)	Y	Y
F30	(Output gain)	0 to 300%	Y*	Y
F31	(Function selection)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ	Y	Y

	HHD specification		HND specification	
	FRN****G2S-2G	FRN****G2□-4G	FRN****G2S-2G	FRN****G2□-4G
0.75 to 16 kHz	0003 to 0288	0002 to 0179	0032 to 0088	0018 to 0045
0.75 to 10 kHz	0346 to 0432	0217 to 1480	0115 to 0288	0060 to 0179
0.75 to 6 kHz	-	-	0346 to 0432	0217 to 1480
	HD specification *102		ND specification *102	
	FRN****G2S-2G	FRN****G2□-4G	FRN****G2S-2G	FRN****G2□-4G
0.75 to 10 kHz	-	0085 to 0179	-	-
0.75 to 6 kHz	-	0217 to 1480	-	0085 to 1480

F31 (Function selection):

0: Output frequency 1 (before slip compensation)
1: Output frequency 2 (after slip compensation)
2: Output current
3: Output voltage when alarm occurred
4: Output torque
5: Load factor
6: Power consumption
7: PID feedback value
8: Actual speed/estimated speed
9: DC link bus voltage
10: Universal AO
11: Analog output test (-)
13: Motor output
14: Calibration (+)
15: PID command (SV)
16: PID output (MV)
17: Master-follower angle deviation
18: Inverter cooling fin temperature
21: PG feedback value
22: Torque current command
23: PID deviation
24: Line speed command
25: Winding diameter calculation value
26: Setting frequency (before acceleration/deceleration calculation)
50: PID control 1 feedback value (PV1) *101
51: PID control 1 command (SV1) *101
52: PID control 1 deviation (ERR1) *101
54: PID control 2 feedback value (PV2) *101
55: PID control 2 command (SV2) *101
56: PID control 2 deviation (ERR2) *101
60: External PID control 1 feedback value (EPID1-PV) *101
61: External PID control 1 command (EPID1-SV) *101
62: External PID control 1 deviation (EPID1-ERR) *101
63: External PID control 1 final deviation (EPID-ERR) *101
65: External PID control 1 final output (EPID1-OUT) *101
70: External PID control 2 feedback value (EPID2-PV) *101
71: External PID control 2 command (EPID2-SV) *101
72: External PID control 2 deviation (EPID2-ERR) *101
75: External PID control 2 final output (EPID2-OUT) *101
80: External PID control 3 feedback value (EPID3-PV) *101
81: External PID control 3 command (EPID3-SV) *101
82: External PID control 3 deviation (EPID3-ERR) *101
85: External PID control 3 final output (EPID3-OUT) *101
111 to 124: Customizable logic output signal 1 to 14 *101

*101 Compatible with software version ROM0500 or later.
*102 Compatible with software version ROM0600 or later

Function code	Name	Control method and Data setting range	Change when running	Data copying
F32	Terminal [FM2] (Operation selection)	Same as F29	Y	Y
F33	Terminal [FMP] (Pulse rate)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 25 to 6000 p/s (number of pulse at 100%)	Y*	Y
F34	(Output gain)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0,1 to 300% 0: Pulse output 1 to 300%	Y*	Y
F35	(Function selection)	Same as F31	Y	Y
F37	Load selection/ Auto torque boost/ Auto energy-saving operation 1	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Quadratic-torque load 1: Constant torque load 2: Auto torque boost 3: Auto energy-saving operation (quadratic-torque load) 4: Auto energy-saving operation (constant torque load) 5: Auto energy-saving operation with auto torque boost	N	Y
F38	Stop frequency (detection mode)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Speed detection value / estimated speed 1: Reference speed	N	Y
F39	(Holding time)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 to 10.00s	Y	Y
F40	Torque limiter 1-1	V/f PGV/f SLV PGV PM SLV PM PGV TRQ -300 to 0 to 300% ; 999 (Disable)	Y	Y
F41	Torque limiter 1-2		Y	Y
F42	Drive control selection 1	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: V/f control without slip compensation 1: Dynamic torque vector control 2: V/f control with slip compensation 3: V/f control with speed sensor 4: Dynamic torque vector control with sensor 5: Sensorless vector control 6: Vector control with speed sensor 15: Sensorless vector control (synchronous motors) 16: Vector control with sensor (synchronous motors)	N	Y
F43	Current limiter (mode selection)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Disable 1: Enable at constant speed (disable during ACC/DEC) 2: Enable during ACC/constant speed operation (disable during DEC)	Y	Y
F44	(Operation level)	20 to 200% (rated current of the inverter for 100%)	Y	Y
F50	Electronic thermal overload (for braking resistor protection) (discharging capacity)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0 (If using built-in breaking resistor) 1 to 9000 kWs OFF (cancel)	Y	Y1 Y2
F51	(Permissible average loss)	0.001 to 99.99kW	Y	Y1 Y2
F52	(Braking resistance value)	0.01 to 999Ω	Y	Y1 Y2
F58	Terminal [FM1] (Filter)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 to 5.00s	Y	Y
F59	(Bias)	-100.0 to 100.0%	Y*	Y
F60	Terminal [FM2] (Output gain)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0 to 300%	Y*	Y
F61	(Function selection)	Same as F31	Y	Y
F62	(Filter)	0.00 to 5.00s	Y	Y
F63	(Bias)	-100.0 to 100.0%	Y*	Y
F64	Terminal [FMP] (Filter)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 to 5.00s	Y	Y
F80	HHD/HND switching	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: HHD specification 1: HND specification 3: HD specification *102 4: ND specification *102	N	Y

*12 180% for 15 kW or less, and 160% for 22 kW or more.
*13 0 for 7.5 kW or less, and OFF for 11 kW or more.
*102 Compatible with software version ROM0600 or later

E codes :Extension Terminal Functions (terminal functions)

Function code	Name	Control method and Data setting range	Change when running	Data copying
E01	Terminal [X1] (Function selection)	Table 1 Refer to E01 to E09 in the control input terminal setting table.	N	Y
E02	Terminal [X2]		N	Y
E03	Terminal [X3]		N	Y
E04	Terminal [X4]		N	Y
E05	Terminal [X5]		N	Y
E06	Terminal [X6]		N	Y
E07	Terminal [X7]		N	Y
E08	Terminal [X8]		N	Y
E09	Terminal [X9]		N	Y

Table 1 Control input terminal setting table

Function code and Name				Control method and Data setting range	
E01 to E09	E70	E98,E99	o101 to o116		
Terminal [X1] to [X9]	Keypad M/shift key	Terminal [FWD][REV]	Terminal [I1] to [I16] (for OPC-DI)		
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0 (1000): Multistep frequency selection (0 to 1 steps)	『SS1』
				1 (1001): Select multistep frequency (0 to 3 steps)	『SS2』
				2 (1002): Select multistep frequency (0 to 7 steps)	『SS4』
				3 (1003): Select multistep frequency (0 to 15 steps)	『SS8』
Y	Y	Y	Y	4 (1004): Select ACC/DEC time (2 steps)	『RT1』
				5 (1005): Select ACC/DEC time (4 steps)	『RT2』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 6 (1006): Select 3-wire operation	『HLD』
Y	Y	Y	Y	7 (1007): Coast to a stop command	『BX』
Y	N	Y	Y	8 (1008): Reset alarm (Abnormal)	『RST』
Y	N	Y	Y	9 (1009): External alarm (9 = Active OFF/1009 = Active ON)	『THR』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 10 (1010): Ready for jogging	『JOG』
Y	Y	Y	Y	11 (1011): Select frequency setting 2/ frequency setting 1	『Hz2/Hz1』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 12 (1012): Select motor 2	『M2』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 13: DC braking command PM SLV is valid only when P30 = 0	『DCBRK』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 14 (1014): Select torque limit 2/ torque limit 1	『TL2/TL1』
Y	N	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 15: Switch to commercial power (50 Hz)	『SW50』
				16: Switch to commercial power (60 Hz)	『SW60』
Y	N	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 17 (1017): UP command	『UP』
				18 (1018): DOWN command	『DOWN』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 19 (1019): Allow function code editing (data change enabled)	『WE-KP』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 20 (1020): Cancel PID control	『Hz/PID』
Y	Y	Y	Y	21 (1021): Switch normal/ inverse operation	『IVS』
Y	N	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 22 (1022): Interlock	『IL』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 23 (1023): Cancel torque control	『Hz/TRQ』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 24 (1024): Select link operation (RS-485, BUS option)	『LE』
Y	N	Y	Y	25 (1025): Universal DI	『U-DI』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 26 (1026): Select auto search for idling motor speed at starting	『STM』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 30 (1030): Force to stop (30 = Active OFF/1030 = Active ON)	『STOP』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 32 (1032): Pre-excite	『EXITE』

Function code and Name				Control method and Data setting range		
E01 to E09	E70	E98,E99	o101 to o116			
Terminal [X1] to [X9]	Keypad M/shift key	Terminal [FWD][REV]	Terminal [I1] to [I16] (for OPC-DI)			
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 33 (1033): Reset PID integral and differential terms		『PID-RST』
				34 (1034): Hold PID integral term		『PID-HLD』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 35 (1035): Local (keypad) command selection		『LOC』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 36 (1036): Select motor 3		『M3』
				37 (1037): Select motor 4		『M4』
Y	Y	Y	Y	38 (1038): Drive permission	*100	『RE』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 39: Condensation prevention		『DWP』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 40: Switch to commercial power built-in sequence (50 Hz)		『ISW50』
				41: Switch to commercial power built-in sequence (60 Hz)		『ISW60』
Y	N	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 42 (1042): Activate the limit switch at start point		『LS』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 46 (1046): Overload stop enable command		『OLS』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 47 (1047): Servo lock command		『LOCK』
Y*1	N	N	N	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 48: Pulse train input * Terminal [X7] only (E06, E07)		『PIN』
Y*2	Y	Y	Y	49 (1049): Pulse train sign terminal * Other than terminal [X6] and [X7] (E01 to E05, E08, E09)		『SIGN』
Y	N	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 50 (1050): Drive motor fixed-time switching time clear command	*101	『MCLR』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 58(1058) :UP/DOWN frequency clear		『STZ』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 59 (1059): Battery operation selection		『BATRY』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 60 (1060): Select torque bias 1		『TB1』
				61 (1061): Select torque bias 2		『TB2』
				62 (1062): Hold torque bias		『H-TB』
Y	N	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 65 (1065): Check brake		『BRKE』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 70 (1070): Cancel line speed control		『Hz/LSC』
				71 (1071): Hold line speed control frequency in the memory		『LSC-HLD』
Y	N	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 72 (1072): Count the run time of commercial power-driven motor 1		『CRUN-M1』
				73 (1073): Count the run time of commercial power-driven motor 2		『CRUN-M2』
				74 (1074): Count the run time of commercial power-driven motor 3		『CRUN-M3』
				75 (1075): Count the run time of commercial power-driven motor 4		『CRUN-M4』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 76 (1076): Select droop control		『DROOP』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 77 (1077): Speed deviation error cancel		『PG-CCL』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 78 (1078): Speed control parameter selection 1		『MPRM1』
				79 (1079): Speed control parameter selection 2		『MPRM2』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 80 (1080): Cancel customizable logic		『CLC』
				81 (1081): Clear all customizable logic timers		『CLTC』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 82 (1082): Anti-regenerative control cancel		『AR-CCL』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 83 (1083): PG input switching		『PG-SEL』

*100 Compatible with software version ROM0300 or later.
*101 Compatible with software version ROM0500 or later.

E codes :Extension Terminal Functions (terminal functions)

Table 1 Control input terminal setting table

Function code and Name				Control method and Data setting range		
E01 to E09	E70	E98,E99	o101 to o116			
Terminal [X1] to [X9]	Keypad M/shift key	Terminal [FWD][REV]	Terminal [I1] to [I16] (for OPC-DI)			
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 84 (1084): Acceleration/deceleration cancel (bypass)		『BPS』
Y	N	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 87 (1087): Drive command 2/Drive command 1	*100	『FR2/FR1』
				88: Forward rotation and stop command 2	*100	『FWD2』
				89: Reverse rotation and stop command 2	*100	『REV2』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 94: Forward rotation JOG		『FJOG』
				95: Reverse rotation JOG		『RJOG』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 97 (1097): Direction command		『DIR』
N	N	Y	N	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 98: Forward rotation and stop command		『FWD』
				99: Reverse rotation and stop command		『REV』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 100: No assignment		『NONE』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 105 (1105): Light load automatic double speed judgment permission		『LAC-ENB』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 110 (1110): Servo lock gain selection		『SLG2』
Y	N	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 111 (1111): Forced stop (terminal block only) (111 = Active OFF/1111 = Active ON)		『STOP-T』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 116 (1116): AVR cancel		『AVR-CCL』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 119 (1119): Speed regulator P selection		『P-SEL』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 121 (1121) to 129(1129): Customizable logic input 1 to 9 “CLI1” to		『CLI1』～『CLI9』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 130 (1130): Boost command	*101	『BST』
				131 (1131): Flow switch	*101	『FS』
				132 (1132): Filter clogging reverse command	*101	『FRC』
				133 (1133): PID channel switching	*101	『PID2/1』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 134 (1134): Forced operation command		『FMS』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 135 (1135): Travel/absolute position switching		『INC/ABS』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 136 (1136): Orientation command		『ORT』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 137 (1137): Position control/speed control switching		『POS/Hz』
				138 (1138): Homing command		『ORG』
Y	N	Y	Y	139 (1139): + direction overtravel		『+OT』
				140 (1140): - direction overtravel		『-OT』
Y	Y	Y	Y	141 (1141): Position clear command		『P-CLR』
				142 (1142): Position preset command		『P-PRESET』
				143 (1143): Teaching command		『TEACH』
				144 (1144): Positioning data change command		『POS-SET』
				145 (1145): Positioning data selection		『POS-SEL1』
				146 (1146): Positioning data selection		『POS-SEL2』
				147 (1147): Positioning data selection 4		『POS-SEL4』
Y	N	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 149 (1149): Pump control switching command	*101	『PCHG』
				150 (1150): Rotary control master motor	*101	『MEN0』
				151 (1151): Pump control motor 1	*101	『MEN1』
				152 (1152): Pump control motor 2	*101	『MEN2』
				153 (1153): Pump control motor 3¥	*101	『MEN3』

*100 Compatible with software version ROM0300 or later.
*101 Compatible with software version ROM0500 or later.

Function code and Name				Control method and Data setting range		
E01 to E09	E70	E98,E99	o101 to o116			
Terminal [X1] to [X9]	Keypad M/shift key	Terminal [FWD][REV]	Terminal [I1] to [I16] (for OPC-DI)			
Y	N	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ		
				154 (1154): Pump control motor 4	*101	『MEN4』
				155 (1155): Pump control motor 5	*101	『MEN5』
				156 (1156): Pump control motor 6	*101	『MEN6』
				157 (1157): Pump control motor 7	*101	『MEN7』
				158 (1158): Pump control motor 8	*101	『MEN8』
				V/f PGV/f SLV PGV PM SLV PM PGV TRQ		
				159 (1159): For manufacturer adjustment	*101	『ICSW』
				160 (1160): For manufacturer adjustment	*101	『ICFB』
				161 (1161): For manufacturer adjustment	*101	『LCFB』
Y	N	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ		
				169 (1169): Initial diameter set command		『D-SET』
				170 (1170): Winding diameter calculation hold command		『D-HLD』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ		
				171 (1171): PID control multistage command 1		『PID-SS1』
				172 (1172): PID control multistage command		『PID-SS2』
Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ		
				181 (1181): External PID multi-stage command 1	*101	『EPID-SS1』
				182 (1182): External PID multi-stage command 2	*101	『EPID-SS2』
				190 (1190): Scheduled drive cancellation	*101	『TMC』
				191 (1191): Schedule 1 enabled	*101	『TM1』
				192 (1192): Schedule 2 enabled	*101	『TM2』
				193 (1193): Schedule 3 enabled	*101	『TM3』
				194 (1194): Schedule 4 enabled	*101	『TM4』
				201 (1201): External PID control 1 ON command	*101	『EPID1-ON』
				202 (1202): External PID control 1 cancellation	*101	『%/EPID1』
				203 (1203): External PID 1 positive/negative switching	*101	『EPID1-IVS』
				204 (1204): External PID 1 integral/differential reset	*101	『EPID1-RST』
				205 (1205): External PID 1 integral hold	*101	『EPID1-HLD』
				211 (1211): External PID control 2 ON command	*101	『EPID2-ON』
				212 (1212): External PID control 2 cancellation	*101	『%/EPID2』
				213 (1213): External PID 2 positive/negative switching	*101	『EPID2-IVS』
				214 (1214): External PID 2 integral/differential reset	*101	『EPID2-RST』
				215 (1215): External PID 2 integral hold	*101	『EPID2-HLD』
				221 (1221): External PID control 3 ON command	*101	『EPID3-ON』
				222 (1222): External PID control 3 cancellation	*101	『%/EPID3』
				223 (1223): External PID 3 positive/negative switching	*101	『EPID3-IVS』
				224 (1224): External PID 3 integral/differential reset	*101	『EPID3-RST』
				225 (1225): External PID 3 integral hold	*101	『EPID3-HLD』
Note) () indicates logical inversion. (Short circuit - OFF)						

*101 Compatible with software version ROM0500 or later.

E codes :Extension Terminal Functions (terminal functions)

Table 1 Control input terminal setting table

Function code	Name	Control method and Data setting range	Change when running	Data copying
E10	Acceleration time 2	V/f PGV/f SLV PGV PM SLV PM PGV TRQ	Y	Y
E11	Deceleration time 2	0.00 to 6000 s	Y	Y
E12	Acceleration time 3	* 0.00 is for acceleration and deceleration time cancel (when performing soft-start and stop externally)	Y	Y
E13	Deceleration time 3		Y	Y
E14	Acceleration time 4		Y	Y
E15	Deceleration time 4		Y	Y
E16	Torque limiter 2-1	V/f PGV/f SLV PGV PM SLV PM PGV TRQ	Y	Y
E17	Torque limiter 2-2	-300 to 0 to 300%; 999 (Disable)	Y	Y
E20	Terminal [Y1] (Function selection)	Table 2 Refer to E20 to E27 in the control input terminal setting table.	N	Y
E21	Terminal [Y2]		N	Y
E22	Terminal [Y3]		N	Y
E23	Terminal [Y4]		N	Y
E24	Terminal [Y5A/C] (Ry output)		N	Y
E27	Terminal [30A/B/C] (Ry output)		N	Y

*10 FRN0.4 to 22G2S/E/P-2J/4J is 6.00 s, and FRN30 to 630G2S/E/H/P-2J/4J is 20.00 s.

Table 2 Control input terminal setting table

Function code and Name					Control method and Data setting range
E20 to E24, E27	E71	o01 to o07 *101	o23 to o26	o121 to o128	
Terminal [Y1] to [Y4], [Y5A/C], [30A/B/C]	Keypad M-LED indicator	Terminal [Y6A/C] to [Y12A/C] (for OPC-RY2)	Terminal [Y1A/B/C] to [Y4A/B/C] (for OPC-RY)	Terminal [01] to [08] (for OPC-DO)	
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0 (1000): Inverter running 『RUN』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 1 (1001): Frequency (speed) arrival 『FAR』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 2 (1002): Frequency (speed) detected 『FDT』
Y	Y	Y	Y	Y	3 (1003): Under voltage detected (inverter stopped) 『LU』
Y	Y	Y	Y	Y	4 (1004): Detected torque polarity 『B/D』
Y	Y	Y	Y	Y	5 (1005): Inverter output limiting 『IOL』
Y	Y	Y	Y	Y	6 (1006): Auto-restarting after momentary power failure 『IPF』
Y	Y	Y	Y	Y	7 (1007): Motor overload early warning 『OL』
Y	Y	Y	Y	Y	8 (1008): Keypad operation 『KP』
Y	Y	Y	Y	Y	10 (1010): Inverter ready to run 『RDY』
Y	N	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 11: Commercial/inverter power supply switching 『SW88』 12: Commercial/inverter power supply switching 『SW52-2』 13: Commercial/inverter power supply switching 『SW52-1』
Y	N	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 15 (1015): Switch MC on the input power lines 『AX』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 16 (1016): Pattern operation stage transition 『TU』 17 (1017): Pattern operation cycle completed 『TO』 18 (1018): Pattern operation stage 1 『STG1』 19 (1019): Pattern operation stage 2 『STG2』 20 (1020): Pattern operation stage 4 『STG4』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 21 (1021): Frequency (speed) arrival 2 『FAR2』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 22 (1022): Inverter output limiting with delay 『IOL2』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 25 (1025): Cooling fan in operation 『FAN』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 26 (1026): Auto-resetting 『TRY』
Y	N	N	Y	N	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 27 (1027): Universal DO 『U-DO』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 28 (1028): Heat sink overheat early warning 『OH』

*101 Compatible with software version ROM0500 or later.

Function code and Name					Control method and Data setting range		
E20 to E24, E27	E71	o01 to o07 *101	o23 to o26	o121 to o128			
Terminal [Y1] to [Y4], [Y5A/C], [30A/B/C]	Keypad M-LED indicator	Terminal [Y6A/C] to [Y12A/C] (for OPC-RY2)	Terminal [Y1A/B/C] to [Y4A/B/C] (for OPC-RY)	Terminal [01] to [08] (for OPC-DO)			
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 29 (1029): Master-follower operation complete		『SY』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 30 (1030): Lifetime alarm		『LIFE』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 31 (1031): Frequency (speed) detected 2		『FDT2』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 33 (1033): Reference loss detected		『REF OFF』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 35 (1035): Inverter outputting		『RUN2』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 36 (1036): Overload prevention controlling		『OLP』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 37 (1037): Current detected		『ID』
					38 (1038): Current detected 2		『ID2』
					39 (1039): Current detected 3		『ID3』
					41 (1041): Low current detected		『IDL』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 42 (1042): PID alarm		『PID-ALM』
					43 (1043): Under PID control		『PID-CTL』
					44 (1044): Under sleep mode of PID control		『PID-STP』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 45 (1045): Low torque detected		『U-TL』
					46 (1046): Torque detected 1		『TD1』
					47 (1047): Torque detected 2		『TD2』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 48 (1048): Motor 1 selected		『SWM1』
					49 (1049): Motor 2 selected		『SWM2』
					50 (1050): Motor 3 selected		『SWM3』
					51 (1051): Motor 4 selected		『SWM4』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 52 (1052): Forward rotation		『FRUN』
					53 (1053): Reverse rotation		『RRUN』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 54 (1054): Under remote mode		『RMT』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 55 (1055): Drive command input available	*100	『AX2』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 56 (1056): Motor overheat detected by thermistor		『THM』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 57 (1057): Mechanical brake control		『BRKS』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 58 (1058): Frequency (speed) detected 3		『FDT3』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 59 (1059): Current input wire break detection (terminal [C1] and [C2])		『C1OFF』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 68 (1068): Fixed-time switching forecast signal	*101	『MCHG』
					69 (1069): Pump control output limit signal	*101	『MLIM』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 70 (1070): Speed valid		『DNZS』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 71 (1071): Speed agreement		『DSAG』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 72 (1072): Frequency (speed) arrival 3		『FAR3』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 76 (1076): Speed mismatch		『PG-ERR』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 77 (1077): Low DC link bus voltage detection		『U-EDC』

*100 Compatible with software version ROM0300 or later.
*101 Compatible with software version ROM0500 or later.

E codes :Extension Terminal Functions (terminal functions)

Table 2 Control input terminal setting table

Function code and Name					Control method and Data setting range		
E20 to E24, E27	E71	o01 to o07 *101	o23 to o26	o121 to o128			
Terminal [Y1] to [Y4], [Y5A/C], [30A/B/C]	Keypad M-LED indicator	Terminal [Y6A/C] to [Y12A/C] (for OPC-RY2)	Terminal [Y1A/B/C] to [Y4A/B/C] (for OPC-RY)	Terminal [01] to [08] (for OPC-DO)			
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 79 (1079): During decelerating at momentary power failure		『IPF2』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 82 (1082): Positioning complete		『PSET』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 84 (1084): Maintenance timer counted up		『MNT』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 87 (1087): Frequency arrival and detected		『FARFDT』
Y	N	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 88 (1088): Auxiliary motor drive signal	*101	『AUX_L』
Y	N	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 90 (1090): Alarm content 1		『AL1』
					91 (1091): Alarm content 2		『AL2』
					92 (1092): Alarm content 4		『AL4』
					93 (1093): Alarm content 8		『AL8』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 95 (1095): Forced operation		『FMRUN』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 98 (1098): Light alarm		『L-ALM』
					99 (1099): Alarm output		『ALM』
N	Y	Y	N	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 100: No assignment		『NONE』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 101 (1101): EN circuit failure detected		『DECF』
					102 (1102): EN terminal input OFF		『ENOFF』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 105 (1105): Braking transistor broken		『DBAL』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 111 (1111) to 124(1124): Customizable logic output signal 1 to 14		『CLO1』～『CLO14』
Y	N	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 125 (1125): Integral power pulse output		『POUT』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 131 (1131): Speed limiting		『S-LIM』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 132 (1132): Torque limit level		『T-LIM』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 133 (1133): Low current detection		『IDL2』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 135 (1135): Dancer upper limit position warning signal		『D-UPFL』
					136 (1136): Dancer lower limit position warning signal		『D-DNFL』
					137 (1137): Dancer position limit warning signal		『D-FL』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 151 (1151): Overtravel detection		『OT-OUT』
					152 (1152): Forced stop detection		『STOP-OUT』
					153 (1153): Pass point detection 1		『PPAS1』
					154 (1154): Pass point detection 2		『PPAS2』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 158 (1158): Overload detected		『LLIM』
					159 (1159): Performing light load automatic double speed operation		『LAC』
Y	N	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 160 (1160): Motor 1 inverter-driven	*101	『M1_I』
					161 (1161): Motor 1 commercial power-driven	*101	『M1_L』
					162 (1162): Motor 2 inverter-driven	*101	『M2_I』
					163 (1163): Motor 2 commercial power-driven	*101	『M2_L』
					164 (1164): Motor 3 inverter-driven	*101	『M3_I』
					165 (1165): Motor 3 commercial power-driven	*101	『M3_L』

*101 Compatible with software version ROM0500 or later.

Function code and Name					Control method and Data setting range		
E20 to E24, E27	E71	o01 to o07 *101	o23 to o26	o121 to o128			
Terminal [Y1] to [Y4], [Y5A/C], [30A/B/C]	Keypad M-LED indicator	Terminal [Y6A/C] to [Y12A/C] (for OPC-RY2)	Terminal [Y1A/B/C] to [Y4A/B/C] (for OPC-RY)	Terminal [01] to [08] (for OPC-DO)			
Y	N	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ		
					166 (1166): Motor 4 inverter-driven	*101	『M4_I』
					167 (1167): Motor 4 commercial power-driven	*101	『M4_L』
					169 (1169): Motor 5 commercial power-driven	*101	『M5_L』
					171 (1171): Motor 6 commercial power-driven	*101	『M6_L』
					173 (1173): Motor 7 commercial power-driven	*101	『M7_L』
					175 (1175): Motor 8 commercial power-driven	*101	『M8_L』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ		
					176 (1176): For manufacturer adjustment	*101	『COM_ABN』
					177 (1177): For manufacturer adjustment	*101	『COM_DO』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ		
					180 (1180): During rotary driving	*101	『M-RUN』
					181 (1181): During rotary driven alarm	*101	『M-ALM』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ		
					190 (1190): Scheduled driving	*101	『TMD』
					191 (1191): Schedule 1 in operation	*101	『TMD1』
					192 (1192): Schedule 2 in operation	*101	『TMD2』
					193 (1193): Schedule 3 in operation	*101	『TMD3』
					194 (1194): Schedule 4 in operation	*101	『TMD4』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ		
					200 (1200): PID 2 selected	*101	『PID2』
					201 (1201): PID 1 alarm	*101	『PV1-ALM』
					202 (1202): PID 1 feedback error	*101	『PV1-OFF』
					203 (1203): PID 2 alarm	*101	『PV2-ALM』
					204 (1204): PID 2 feedback error	*101	『PV2-OFF』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ		
					211 (1211): External PID 1 under control	*101	『EPID1-CTL』
					212 (1212): External PID 1 output	*101	『EPID1-OUT』
					213 (1213): External PID 1 during output	*101	『EPID1-RUN』
					214 (1214): External PID 1 alarm	*101	『EPV1-ALM』
					215 (1215): External PID 1 feedback error	*101	『EPV1-OFF』
					221 (1221): External PID 2 under control	*101	『EPID2-CTL』
					222 (1222): External PID 2 output	*101	『EPID2-OUT』
					223 (1223): External PID 2 during output	*101	『EPID2-RUN』
					224 (1224): External PID 2 alarm	*101	『EPV2-ALM』
					225 (1225): External PID 2 feedback error	*101	『EPV2-OFF』
					231 (1231): External PID 3 under control	*101	『EPID3-CTL』
					232 (1232): External PID 3 output	*101	『EPID3-OUT』
					233 (1233): External PID 3 during output	*101	『EPID3-RUN』
					234 (1234): External PID 3 alarm	*101	『EPV3-ALM』
					235 (1235): External PID 3 feedback error	*101	『EPV3-OFF』
Y	Y	Y	Y	Y	V/f PGV/f SLV PGV PM SLV PM PGV TRQ		
					251 (1251): M/Shift key ON/OFF state		『MTGL』
Note) () indicates logical inversion. (Short circuit - OFF)							

*101 Compatible with software version ROM0500 or later.

E codes :Extension Terminal Functions (terminal functions)

Function code	Name	Control method and Data setting range	Change when running	Data copying
E29	Frequency arrival delay timer (FAR2)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.01 to 10.00s	Y	Y
E30	Frequency arrival detection width (Detection width)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.0 to 10.0Hz	Y	Y
E31	Frequency (operation level)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ	Y	Y
E32	detection 1 (Hysteresis width)	0.0 to 599.0Hz	Y	Y
E34	Overload early warning/Current (Level)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 (Disable), 1 to 200% of inverter rated current(Inverter rated current dependent on F80)	Y	Y1 Y2
E35	detection (Timer)	0.01 to 600.00s	Y	Y
E36	Frequency detection 2 (Level)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.0 to 599.0Hz	Y	Y
E37	Current detection 2/ Low current (Level)	Same as E34	Y	Y1 Y2
E38	detection (Timer)	Same as E35	Y	Y
E39	Constant rate of feeding coefficient 1/ Speed display auxiliary coefficient 1	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.000 to 9999	Y	Y
E42	LED display filter	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.0 to 5.0s	Y	Y
E43	LED monitor (display selection)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Speed monitor (Selectable with E48) 3: Output current 4: Output voltage when alarm occurred 8: Calculated motor output torque when alarm occurred 9: Power consumption 10: PID process command 12: PID feedback value 13: Timer value 14: PID output 15: Load factor 16: Motor output 17: Analog signal input monitor 21: Current position 22: Positioning deviation 23: Torque current (%) 24: Magnetic flux command(%) 25: Input watt-hour 26: Winding diameter 27: Position control start position 28: Stop target position 29: PID deviation 30: Torque bias 31: Estimated inertia acceleration/deceleration time conversion value (coming soon) 32: Customizable logic output 50: PID command value (Final) *101 51: PID feedback value (Final) *101 52: PID output *101 53: PID control 1 command value *101 54: PID control 1 feedback value *101 55: PID control 2 command value *101 56: PID control 2 feedback value *101 60: External PID control 1 command value (Final) *101 61: External PID control 1 feedback value (Final) *101 62: External PID control 1 output (%) *101 63: External PID control 1 manual command value (%) *101 64: External PID control 1 command value *101 65: External PID control 1 feedback value *101 70: External PID control 2 command value *101 71: External PID control 2 feedback value *101 72: External PID control 2 output (%) *101 73: External PID control 2 manual command value (%) *101 80: External PID control 3 command value *101 81: External PID control 3 feedback value *101 82: External PID control 3 output (%) *101 83: External PID control 3 manual command value (%) *101	Y	Y
E44	(Display when stopped)	0: Specified value 1: Output value	Y	Y
E48	LED monitor details (Speed monitor selection)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Output frequency 1 (before slip compensation) 1: Output frequency 2 (after slip compensation) 2: Set frequency	Y	Y

*3 The rated current of the motor is set. For details, refer to the FRENIC-MEGA (G2) User's Manual.
*101 Compatible with software version ROM0500 or later.

Function code	Name	Control method and Data setting range	Change when running	Data copying
E48	LED monitor details (Speed monitor selection)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 3: Motor speed 4: Feed speed 5: Line speed 6: Constant feeding rate time 7: Speed (%) 8: Reference line speed 9: Line speed output value	Y	Y
E49	Torque Command Monitor (Polarity selection)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Torque polarity 1: Plus for driving, Minus for braking	Y	Y
E50	Display coefficient for speed monitor	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.01 to 600.00	Y	Y
E51	Display coefficient for "Input watt-hour data"	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.000 (Cancel/Reset), 0.001 to 9999	Y	Y
E52	Keypad menu selection	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Function code data setting mode (Menu 0, Menu 1, and Menu 7) 1: Function code data check mode (Menu 2 and Menu 7) 2: Full-menu mode	Y	Y
E54	Frequency detection 3 (Level)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.0 to 599.0Hz	Y	Y
E55	Current detection 3 (Level)	Same as E34	Y	Y1 Y2
E56	(Timer)	Same as E35	Y	Y
E57	Integral power pulse output unit	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Pulse output every 0.1 kWh 1: Pulse output every 1 kWh 2: Pulse output every 10 kWh 3: Pulse output every 100 kWh 4: Pulse output every 1000 kWh	Y	Y
E61	Terminal [12] (extended function)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: No extension function assignment 1: Auxiliary frequency setting 1 2: Auxiliary frequency setting 2 3: PID command 1 4: PID command 2 *101 5: PID Dfeedback value 6: Ratio setting 7: Analog torque limiter A 8: Analog torque limit value B 9: Torque bias 10: Torque command 11: Torque current command 12: Acceleration/deceleration time ratio setting 13: Upper limit frequency 14: Lower limit frequency 15: Auxiliary frequency setting 3 16: Auxiliary frequency setting 4 17: Speed limit for forward rotation (FWD) 18: Speed limit for reverse rotation (REV) 19: For manufacturer adjustment *101 20: Analog signal input monitor 30: PID feedback value 2 *101 31: PID process command auxiliary setting 1 *101 32: PID process command auxiliary setting 2 *101 33: Flow sensor *101 41: External PID process command 1 *101 42: External PID feedback value 1 *101 43: External PID manual command 1 *101 44: External PID process command 2 *101 45: External PID feedback value 2 *101 46: External PID manual command 2 *101 47: External PID process command 3 *101 48: External PID feedback value 3 *101 49: External PID manual command 3 *101	N	Y
E62	Terminal [C1] (C1 function) (extended function)		N	Y
E63	Terminal [V2] (extended function)		N	Y
E64	Saving of digital reference frequency	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Auto saving (main power is turned off) 1: Save by turning FUNC DATA key ON	Y	Y

*3 The rated current of the motor is set. For details, refer to the FRENIC-MEGA (G2) User's Manual.
*101 Compatible with software version ROM0500 or later.

E codes :Extension Terminal Functions (terminal functions)

Function code	Name	Control method and Data setting range	Change when running	Data copying
E65	Reference loss detection (Continuous running frequency)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Stop deceleration 20 to 120%, 999: Cancel	Y	Y
E66	Terminal [C1] (V3 function) (Extension function selection)	Same as E61	N	Y
E70	M/Shift key (Function selection)	Table 1 Refer to E70 in the control input terminal setting table.	N	Y
E71	M-LED indicator (Function selection)	Table 2 Refer to E71 in the control input terminal setting table.	N	Y
E76	DC link bus low-voltage detection level	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 200 to 400 V (200 V series) 400 to 800 V (400 V series)	Y	Y2
E78	Torque detection 1 (Level)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0 to 300%	Y	Y
E79	(Timer)	0.01 to 600.00s	Y	Y
E80	Torque detection 2/ low torque detection (Level)	Same as E78	Y	Y
E81	(Timer)	Same as E79	Y	Y
E82	Acceleration/deceleration time switching frequency *101	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.0 (Inherit): According to the F16 setting 0.1 to 599.0 Hz	Y	Y
E83	Acceleration time (At low speeds) *101	0.00 (Inherit): According to the acceleration time currently in effect 0.01 to 6000: Acceleration time between 0 Hz to E82	Y	Y
E84	Deceleration time (At low speeds) *101	0.00 (Inherit): According to the deceleration time currently in effect 0.01 to 6000: Deceleration time between E82 to 0 Hz	Y	Y
E85	Slow deceleration time switching frequency *101	0.0 (OFF): Inoperative 0.1 to 599.0 Hz	Y	Y
E86	Slow deceleration time (Check valve protection) *101	0.00 (Inherit): According to the deceleration time currently in effect 0.01 to 6000: Deceleration time between F16 to E85	Y	Y
E98	Terminal [FWD] (Function selection)	Table 1 Refer to E98 and E99 in the control input terminal setting table.	N	Y
E99	Terminal [REV] (Function selection)		N	Y

*101 Compatible with software version ROM0500 or later.

C codes :Control Functions of Frequency (Control function)

Function code	Name	Control method and Data setting range	Change when running	Data copying
C01	Jump frequency 1	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.0 to 599.0Hz	Y	Y
C02	2		Y	Y
C03	3		Y	Y
C04	(Skip width)	0.0 to 30.0Hz	Y	Y
C05	Multistep frequency 1	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 to 599.00Hz	Y	Y
C06	2		Y	Y
C07	3		Y	Y
C08	4		Y	Y
C09	5		Y	Y
C10	6		Y	Y
C11	7		Y	Y
C12	8		Y	Y
C13	9		Y	Y
C14	10		Y	Y
C15	11		Y	Y
C16	12		Y	Y
C17	13		Y	Y
C18	14		Y	Y
C19	15		Y	Y
C20	Jogging frequency	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 to 599.00Hz	Y	Y
C21	Pattern operation / timed operation (Operation selection)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: cycle operation 1: Repetition operation 2: Constant speed operation after 1 cycle operation 3: Timed operation	N	Y
C22	(Stage 1)	Special setting: Press the key 3 times. 1st: Set run time 0.0 to 6000 s and press the key. 2nd: Set rotational direction F (forward) or r (reverse) and press the key. 3rd: Set acceleration/deceleration time 1 to 4 and press the key.	Y	Y
C23	(Stage 2)		Y	Y
C24	(Stage 3)		Y	Y
C25	(Stage 4)		Y	Y
C26	(Stage 5)		Y	Y
C27	(Stage 6)		Y	Y
C28	(Stage 7)		Y	Y
C30	Frequency setting 2	Same as F01	N	Y
C31	Analog input adjustment (Terminal [12]) (Offset)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ -5.0 to 5.0%	Y*	Y
C32	(Gain)	0.00 to 400.00%	Y*	Y
C33	(Filter)	0.00 to 5.00s	Y	Y
C34	(Gain base point)	0.00 to 100.00%	Y*	Y
C35	(polarity selection)	0: Bipolar 1: Unipolar	N	Y
C36	Analog input adjustment (Terminal [C1]) (C1 function) (Offset)	Same as C31	Y*	Y
C37	(Gain)	Same as C32	Y*	Y
C38	(Filter)	Same as C33	Y	Y
C39	(Gain base point)	Same as C34	Y*	Y
C40	(polarity selection)	0: 4 to 20 mA Unipolar 1: 0 to 20 mA Unipolar 10: 4 to 20 mA Bipolar 11: 0 to 20 mA Bipolar	N	Y
C41	Analog input adjustment (Terminal [V2]) (Offset)	Same as C31	Y*	Y
C42	(Gain)	Same as C32	Y*	Y
C43	(Filter)	Same as C33	Y	Y
C44	(Gain base point)	Same as C34	Y*	Y
C45	(polarity selection)	Same as C35	N	Y
C50	Bias (for frequency setting 1) (Bias base point)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 to 100.00%	Y*	Y
C51	Bias (PID command 1) (bias value)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ -100.0 to 0.00～100.00%	Y*	Y
C52	(Bias base point)	0.00 to 100.00%	Y*	Y
C53	Selection of normal/ inverse operation (Frequency setting 1)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Normal 1: Inverse	Y	Y
C54	(Frequency setting 2)		Y	Y

C codes :Control Functions of Frequency (Control function)

Function code	Name	Control method and Data setting range	Change when running	Data copying
C55	Analog input adjustment (Terminal [12]) (Bias)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ -200.0 to 0.00 to 200.00%	Y*	Y
C56	(Bias base point)	0.00 to 100.00%	Y*	Y
C58	(Display unit)	1 to 92 1: No unit 2: % 4: r/min 7: kW 8: HP 10: mm/s 11: mm/m 12: mm/h 13: m/s 14: m/min 15: m/h 16: FPS 17: FPM 18: FPH 19: SPM (ROM0300 or later) [flow] 20: m3/s 21: m3/min 22: m3/h 23: L/s 24: L/min 25: L/h 26: GPS 27: GPM 28: GPH 29: CFS 30: CFM 31: CFH 32: kg/s 33: kg/m 34: kg/h 35: lb/s 36: lb/m 37: lb/h 38: AF/Y [Pressure] 40: Pa 41: kPa 42: MPa 43: mbar 44: bar 45: mmHg 46: PSI 47: mWG 48: inWG 49: inHg 50: WC 51: Ft WG 52: ATM (ROM0300 or later) [Temperature] 60: K 61: ℃ 62: °F [Distance] 65: Nm 66: lb Ft 70: mm 71: cm 72: m 73: km 74: in 75: Ft 76: Yd 77: mi [Concentration] 80: ppm [Others] 90 : m3 91 : L 92 : GAL 93 : OZ (ROM0300 or later)	Y	Y

Function code	Name	Control method and Data setting range	Change when running	Data copying
C59	Analog input adjustment (Terminal [12]) (maximum scale)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ -999.0 to 0.00 to 9990.0	N	Y
C60	(minimum scale)	-999.0 to 0.00 to 9990.0	N	Y
C61	Analog input adjustment (Terminal [C1] (C1 function)) (Bias)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ -200.0 to 0.00 to 200.00%	Y*	Y
C62	(Bias base point)	0.00 to 100.00%	Y*	Y
C64	(Display unit)	Same as C58	Y	Y
C65	(maximum scale)	-999.0 to 0.00 to 9990.0	N	Y
C66	(minimum scale)	-999.0 to 0.00 to 9990.0	N	Y
C67	Analog input adjustment (Terminal [V2]) (Bias)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ -200.0 to 0.00 to 200.00%	Y*	Y
C68	(Bias base point)	0.00 to 100.00%	Y*	Y
C70	(Display unit)	Same as C58	Y	Y
C71	(maximum scale)	-999.0 to 0.00 to 9990.0	N	Y
C72	(minimum scale)	-999.0 to 0.00 to 9990.0	N	Y
C74	Analog input adjustment (Terminal [C1]) (V3 function) (offset)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ -5.0 to 5.0%	Y*	Y
C75	(Gain)	0.00 to 400.00%	Y*	Y
C76	(Filter)	0.00 to 5.00s	Y	Y
C77	(Gain base point)	0.00 to 100.00%	Y*	Y
C78	(polarity selection)	0: Bipolar 1: Unipolar	N	Y
C82	(Bias)	-200.0 to 0.00 to 200.00%	Y*	Y
C83	(Bias base point)	0.00 to 100.00%	Y*	Y
C84	(Display unit)	Same as C58	Y	Y
C85	(maximum scale)	-999.0 to 0.00 to 9990.0	N	Y
C86	(minimum scale)		N	Y
C89	Frequency compensation 1 via communication (Numerator)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ -32768 to 32767 (Keypad display is 8000 to 7FFF (in hexadecimal)) (Interpreted as 1 when the value is set to 0)	Y	Y
C90	Frequency compensation 2 via communication (Denominator)		Y	Y
C94	Jump frequency 4	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.0 to 599.0Hz	Y	Y
C95	5		Y	Y
C96	6		Y	Y
C99	Digital setting frequency	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 to maximum output frequency (1 to 4)	Y*	Y

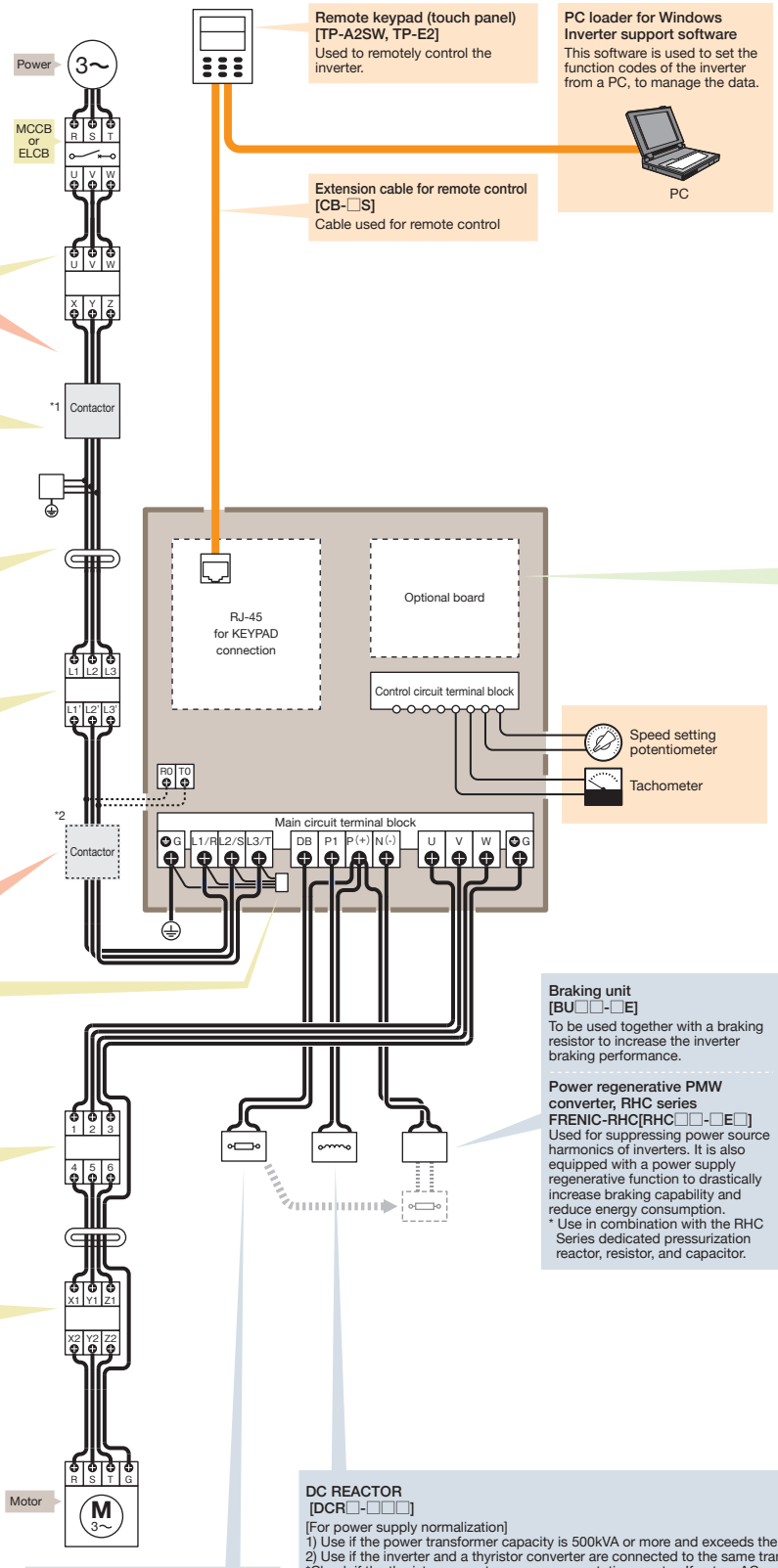
Options

Connection configuration

For main power input and inverter output

External operation, measurement, and communication

Built-in option card



Remote keypad (touch panel) [TP-A2SW, TP-E2]
Used to remotely control the inverter.

PC loader for Windows Inverter support software
This software is used to set the function codes of the inverter from a PC, to manage the data.

Extension cable for remote control [CB-□S]
Cable used for remote control

AC reactor [ACR□-□□□]
When using a power supply with unstable voltage.

*1 If not using an R0, T0 terminal, connect a connector at this location.

Arrester [CN5□□□] Consult our sales representatives
Suppresses induced lightning surges from the power source to protect entire equipment connected to the power source.

Ferrite ring for reducing radio noise [ACL-40C, ACL-74C, F200160]
Used to reduce radio noise. Suppressive effect to the frequency band is available by approximately 1MHz or more. This is appropriate as a simple measure against noise since it affects broad range in the frequency band.

EMC compliance filter [EFL-□□□, FS□□, FN□□]
Dedicated filter to comply with the European EMC Directive (Emission). Install the filter while referring to the details in the installation manual.

Power filter for output circuit [RNF□□□□-□□] Consult our sales representatives
This will become more effective in noise reduction if used together with the power filter for input circuit.

*2 If using an R0, T0 terminal, connect a connector at this location.

Filter capacitor for reducing radio noise [NFM□□M315KPD□] Consult our sales representatives
Used to reduce radio noise. This is effective for the AM radio frequency band.
*Do not use it on the inverter output side.
[Made by Nippon Chemi-con]

Power filter for input circuit [RNF□□□□-□□] Consult our sales representatives
This filter can be used for the same purpose as the EMC compliance filter, but is not an EMC compliance.

Output circuit filter [OFL-□□□-4A]
Connected to the output of an inverter to:
- Suppress fluctuations of motor terminal voltage.
- Prevent damages to the motor insulation due to surge voltage in 400V series inverter.

*This filter is not limited by carrier frequency. Also, motor can be tuned while this option is installed.

Braking unit [BU□□-□E]
To be used together with a braking resistor to increase the inverter braking performance.

Power regenerative PMW converter, RHC series FRENIC-RHC[RHC□□-□E□]
Used for suppressing power source harmonics of inverters. It is also equipped with a power supply regenerative function to drastically increase braking capability and reduce energy consumption.
* Use in combination with the RHC Series dedicated pressurization reactor, resistor, and capacitor.

Braking resistor [DB□□-□, DB□□-□C]
Increases braking capability for highly frequent stopping and large moment of inertia. When used together with a braking unit, connect this to the connection terminal of the braking unit.

DC REACTOR [DCR□-□□□]
[For power supply normalization]
1) Use if the power transformer capacity is 500kVA or more and exceeds the inverter rated capacity by 10 times.
2) Use if the inverter and a thyristor converter are connected to the same transformer.
*Check if the thyristor converter uses a commutation reactor. If not,an AC reactor must be connected to the power supply side.
3) Connect to prevent trips when trip occurs due to opening/closing of the phase-advancing capacitor for the power supply lines.
4) Use if the voltage unbalance exceeds 2%.
[For improving the input power-factor and reducing harmonics]
•Used to reduce the input harmonic current (correcting power-factor)
* For the drop effect, refer to the guideline appendix.

■Control option cards

- **Relay output interface card [OPC-RY] [OPC-RY2]**
  Converts inverter transistor output to relay output signal
- **Digital interface cards [OPC-DI], [OPC-DO]**
  Frequency setting by binary and BCD digital signals
- **Analog interface card [OPC-AIO] [OPC-AO]**
  Torque control by external analog signal
- **PG interface card [OPC-PG□]**
  Performs PG vector control via feedback signals from the encoder
- **[OPC-PMPG2]**
  Enables sensor-equipped synchronous motor operation

■Communication option cards

- **SX bus card [OPC-SX]**
- **T-Link communication card [OPC-TL]**
  Data link between PLC (MICREX-F) and inverter

●**Open bus cards**
Data link between various open buses and inverters

- **Multi-protocol Ethernet communications card [OPC-ETM]**
- **PROFIBUS-DP communication card [OPC-PDP2]**
- **DeviceNet communication card [OPC-DEV]**
- **CANopen communication card [OPC-COP2]**
- **CC-Link communication card [OPC-CCL]**
- **Resistance temperature sensor input card [OPC-PT]**

Filter unit [IFL-□□U-□]
Effectively reduces harmonics and noise when used in combination with an inverter.
Comes with a built-in DC reactor, zero-phase reactor, and capacitive filter that effectively reduces noise.

IP40 compatible attachment [P40ST-F□1]
This attachment makes the inverter's protective structure totally enclosed (IP40).

Compatibility attachment [MA-■-□□]
This attachment makes mounting compatible with our older models.

External cooling attachment [PB-F1-□□]
This attachment is used to move the inverter's cooling fins to a position that is outside the board.

Peripheral and structure options

Multifunctional keypad
[TP-A2SW]

- Equipped with a highly visible LCD.
- Supports a total of 19 languages, including Japanese hiragana, katakana and kanji.
- Parameter changes and mantenance can be perfpromed remotely using a mobile device built-in bluetooth.

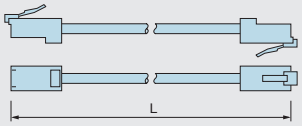
Item	Specification	Remarks
Supported languages	Supports a total of 19 languages, including Japanese, English and Chinese.	
Copy function	Three sets can be stored.	
USB port	Type.mini B	FRENIC Loader for Windows OS
Wireless communi-cation network	Bluetooth Ver.5.0	FRENIC Mobile Loader for Android OS
micro SD card*	SDHC standards (max 32GB)	
Battery*	CR2032	Trace back function
Extension cable	ANSI/TIA/EIA568A Category 5 (10BASE-T/100BASE-TX)	Real-time clock function
Connector for keypad	RJ-45	Option type: CB-□S
Enclosure	Outside cabinet：IP55, inverter back side: IP20	
Approx.weight	135 g	

*SD card not included.

Extension cable for remote control
[CB-□S]

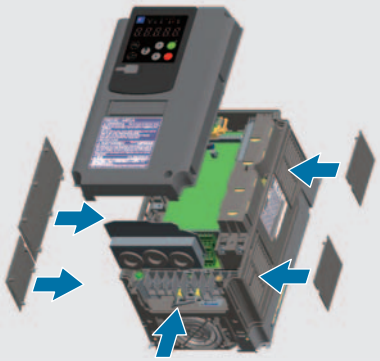
This straight cable is used to connect the RJ-45 connector of the inverter body to the keypad, USB-RS485 converter, etc.
Available in three lengths (1, 3, 5m).

- Cable



Type	CB-5S	CB-3S	CB-1S
Length [m]	5	3	1

IP40 compatible attachment
[P40ST-F□1]



By mounting this product to the body of the standard type (basic type), the protective structure can be changed from IP20 (standard enclosed type) to IP40 (totally enclosed type).

■Applicable list table

Item	Specification										
Type	P40ST-FA1		P40ST-FB1			P40ST-FC1			P40ST-FD1		
Applicable inverter type FRN□□□□G2S-4G	0002	0003	0004	0006	0009	0018	0023	0031	0038	0045	0060
FRN□□□□G2S-2G	0003	0005	0008	0011	0018	0032	0046	0059	0075	0088	0115
Approx. weight [kg]	0.1		0.2			0.3			0.4		

■Configuration kit

Type	Remarks
P40ST-FA1	Closing plate (small side) x 3 pcs. / Closing plate (large side) x 1 pc. / Wiring cover x 1 pc.
P40ST-FB1	Closing plate (small side) x 3 pcs. / Closing plate (large side) x 1 pc. / Wiring cover x 1 pc.
P40ST-FC1	Closing plate (large side) / Closing plate (right corner) x 1 pc. (left corner) x 1 pc. / Wiring cover x 1 pc. / Cross-recessed pan head screw with built-in washer × 2 pcs. (M5 × 10)
	Closing plate (large side) / Closing plate (right corner) x 1 pc. (left corner) x 1 pc. / Wiring cover x 1 pc. / Cross-recessed pan head screw with built-in washer × 2 pcs. (M5 × 10)

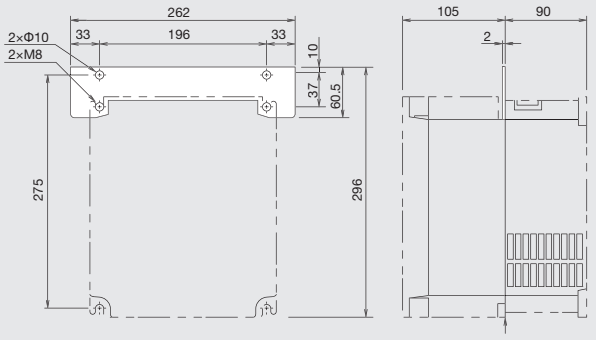
Note 1 Can be mounted only on the standard type (basic type).
Note 2 Ambient temperature: -10 to +40°C
Note 3 When attaching the IP40 option, only one optional card can be mounted (two OPC-RY cards can be mounted).
Note 4 After attaching the IP40 option, change the setting with bit 7 (IP20 / IP40 switching) of the function code H98 (protection / operation

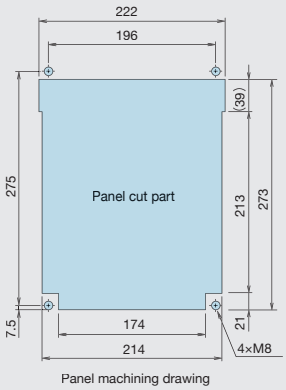
External cooling attachment
[PB-F1-□□]

This attachment is used to move the inverter's cooling fins to a position that is outside the board.

■PB-F1-15

(unit: mm)

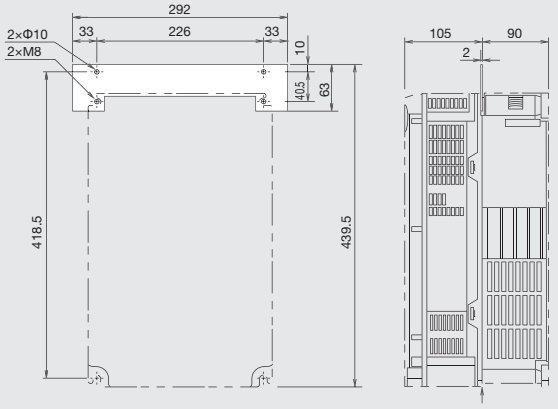


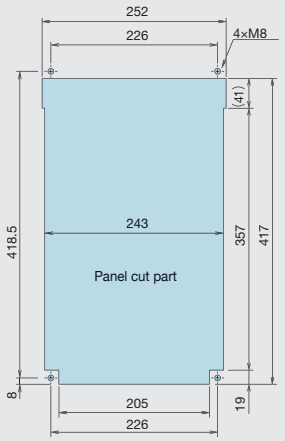


Applicable inverter type
FRN0018G2■-4GU
FRN0023G2■-4GU
FRN0031G2■-4GU
FRN0032G2S-2GU
FRN0046G2S-2GU
FRN0059G2S-2GU

■PB-F1-30

(unit: mm)





Applicable inverter type
FRN0038G2■-4GU
FRN0045G2■-4GU
FRN0060G2■-4GU
FRN0075G2S-2GU
FRN0088G2S-2GU
FRN0115G2S-2GU

Control terminal block

A round terminal blocks can be connected. Compatible with the conventional FRENIC-MEGA_G1 series.

■Specification of the screw and the torque and recommended wire size

Common terminal	Specification of the screw		Recommended wire size (mm^2)
	Screw size	Tightening torque (N·m)	
Control circuit terminal	M3	0.7	0.75 *
fixation screw	M3	0.7	—

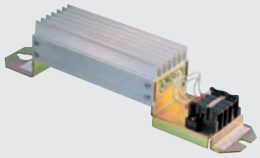
* When attaching the terminal block, can not to used the function of the terminal【X6】,【EN1】,【EN2】and【FM2】.
If using the terminal【X6】in FRENIC-MEGA_G1 series, assign it to other than terminal【X6】.

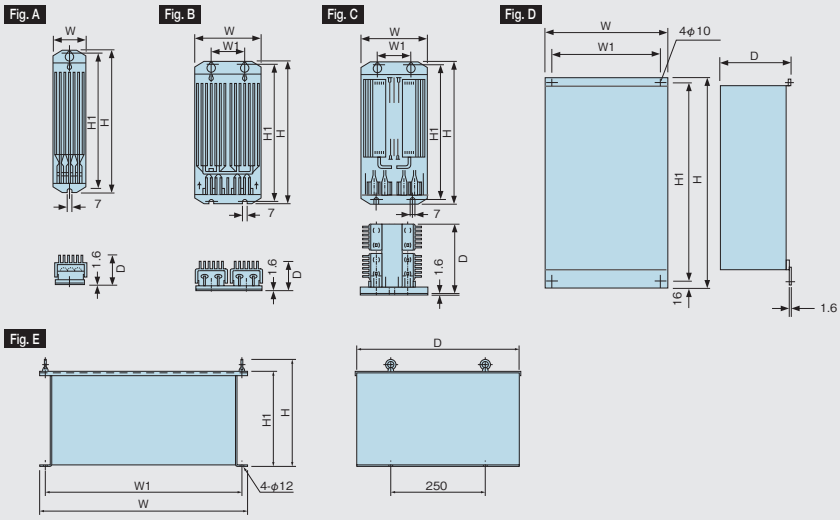
Built-in option card

Item	Type	Specification
PG interface card	OPC-PG	Comes with a two-system pulse input circuit, enabling speed control, position control, and synchronous operation. • Applications: Speed control (vector control with sensor) pulse train input • Specifications: 20 to 3000 P/R A, B, Z phase (incremental) Open collector/complimentary system • PG power supply +12 Vdc ±10% / 120 mA or less or +15 Vdc ±10% / 120 mA or less
PG interface (5 V line driver) card	OPC-PG2	Comes with a single-system pulse input circuit, enabling speed control (vector control with sensor) with PG-based feedback signals. • Applications: Speed control (vector control with sensor) • Specifications: 20 to 3000 P/R 5 V line driver system (single system) • PG power supply: +5 VDC ±10% / 200 mA or less
PG interface (5 V line driver x 2 systems) card	OPC-PG22	Comes with two 5 V line driver pulse input circuits, enabling synchronous operation, positioning control and vibration control of two PG-equipped motors using PG-based feedback signals, as well as frequency command using pulse train input. • Applications: Speed control (vector control with sensor, V/f control with sensor, dynamic torque vector control with sensor), pulse train input, synchronous operation, positioning control • Specifications: 20 to 3000 P/R, 5 V line driver system (two systems) • PG power supply: +5 VDC ±10% / 300 mA or less
PG interface card for synchronous motor drive	OPC-PMPG2	Comes with a 5 V line driver single-system pulse input circuit, enabling synchronous motor operation (vector control with synchronous motor sensor) with PG-based feedback signals. • Applications: Synchronous motor operation (vector control with sensor) • Specifications: 20 to 3000 P/R 5 V line driver system • PG power supply: +5 VDC ±10% / 300 mA or less
Relay output interface card	OPC-RY	This is an option card for converting the transistor outputs of terminals Y1 to Y4 of the inverter into relay outputs (1C contact). Comes with 2 relay outputs, but supports 4 relay outputs when 2 interface cards are installed. • Relay output: 2 circuits built-in • Signal type: 1 contact • Contact capacity: 250 VAC 0.3 A cosϕ = 0.3, 48 VDC, 0.5 A (resistive load)
	OPC-RY2	Any output signal (up to 7 types) set by a function code can be output via relay output (1a contact). • Relay output: Up to 7 circuits • Signal type: 1a contact • Contact capacity: 250 V AC 0.3 A, cos ϕ = 0.3, 48 V DC 0.5 A (Resistance load)
Resistance temperature sensor input card	OPC-PT	Enables conversion of temperature values to digital values. Enables connection of two resistance temperature detectors (RTDs). There are five types of connectible resistance temperature detectors (RTDs): "JPt100", "Pt100", "Ni100", "Pt1000", and "Ni1000".
Digital interface card	OPC-DI	16 digital input terminals (sink/source switchable) Enables frequency setting by binary code (8, 12, 15, or 16 bits) and BCD code, and expansion of general-purpose input terminals.
	OPC-DO	8 digital output terminals (sink/source switchable) Enables monitoring by binary code (8 bits) and expansion of general-purpose output terminals.
Analog interface card	OPC-AIO	Enables torque limit value, frequency setting, and ratio tuning setting via analog input. Enables monitoring of inverter output frequency, current, torque, etc. in analog quantities. • Analog input Analog voltage input: 1 (0 to ±10 V) Analog current input: 1 (4 to 20 mA or 0 to 20 mA) • Analog output Analog voltage output: 1 (0 to ±10 V) Analog current output: 1 (4 to 20 mA)
Analog current output (2 ch) interface card	OPC-AO	Enables monitoring of inverter output frequency, current, torque, etc. in analog units. 2 analog current outputs (4 to 20 mA)
Multi-protocol Ethernet communication card	OPC-ETM	Connects to the master device via Ethernet communication (EtherNet/IP, PROFINET), enabling setting of operation commands and frequency commands, and setting and checking of function codes. • Connector type: RJ-45 shielded • Ethernet cable: CAT-5e or higher UTP or STP cable • Physical layer type: IEEE 802.3 • No. of ports: 2-port (with built-in switch function) • Communication speed: 10 Mbps/100 Mbps (auto detection)
DeviceNet communication card	OPC-DEV	Operation and frequency commands can be set from DeviceNet master, enabling monitoring of operation status and changing/checking of all function codes • No. of connected nodes: Up to 64 (including master) • MAC ID: 0 to 63 • Insulation: 500 VDC (photocoupler insulation) • Communication speed: 500 kbps/250 kbps/125 kbps • Network power consumption: Up to 80 mA 24 VDC
PROFIBUS-DP communication card	OPC-PDP2	Operation and frequency commands can be set from PROFIBUS-DP master, enabling monitoring of operation status and changing/checking of all function codes. • Communication speed: 9.6 kbps to 12 Mbps • Transmission distance: Up to 1,200 m • Connection connector: 2 x 6-pole terminal block
CC-Link communication card	OPC-CCL	When connecting to a CC-Link master unit, it supports a communication speed of up to 10 Mbps and a total length of up to 1,200 m. • No. of connected units: 42 • Communication method: CC-Link Ver1.10 and Ver2.0 • Communication speed: 156 kbps or faster
T-Link communication card	OPC-TL	This is an option to connect our PLCs (MICREX-SX, MICREX-F) and inverters via T-link (I/O transmission). Allows for the following: • No. of transmission words occupied: 8 words • No. of connected inverters: Up to 12 • Maximum transmission speed: 500 kbps • Setting of operating frequency • Setting of operation commands (FWD, REV, RST, etc.) • Operation status monitor • Set/read data code for each function code
CANopen communication card	OPC-COP2	Operation and frequency commands can be set from CANopen master (PC, PLC, etc.), as well as setting/checking of all function codes. • No. of connected nodes: Up to 127 • Communication speed: 20 kbps, 50 kbps, 125 kbps, 250 kbps, 500 kbps, 800 kbps, 1 Mbps • Transmission distance: Up to 2,500 m

Dynamic Braking Resistor

[Standard specifications]
[DB□□ -□]





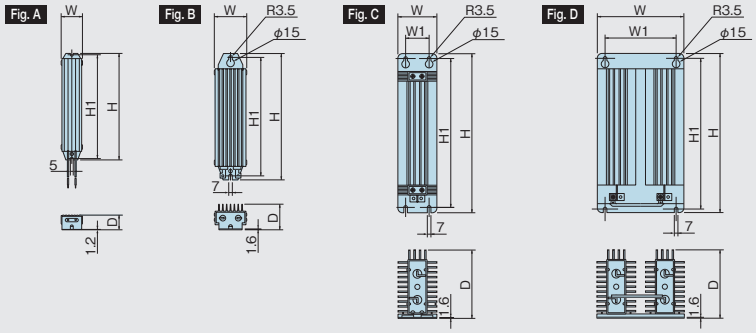
Voltage	Type	Fig	Dimensions [mm]					Approx. weight [kg]
			W	W1	H	H1	D	
3-phase 230V	DB0.75-2C	A	68	–	310	295	67	1.3
	DB2.2-2C		80		345	332	94	2
	DB3.7-2C		80		345	332	94	2
	DB5.5-2C	B	146	90	450	430	67.5	4.5
	DB7.5-2C		160	90	390	370	90	5
	DB11-2C	C	142	74	430	415	160	6.9
	DB15-2C		142	74	430	415	160	6.9
	DB22-2C		142	74	510	495	160	8.7
	DB30-2C	D	400	368	660	628	140	10
	DB37-2C						240	13
	DB45-2C							18
	DB55-2C		405		750	718		22
	DB75-2C	E	450	420	283	240	440	35
	DB110-2C		550	520				32

Voltage	Type	Fig	Dimensions [mm]					Approx. weight [kg]
			W	W1	H	H1	D	
3-phase 480V	DB0.75-4C	A	68	–	310	295	67	1.3
	DB2.2-4C		68		470	455	67	2
	DB3.7-4C		68		470	455	67	1.7
	DB5.5-4C	B	146	74	470	455	67	4.5
	DB7.5-4C		146	74	510	495	67	5
	DB11-4C	C	142	74	430	415	160	6.9
	DB15-4C		142	74	430	415	160	6.9
	DB22-4C		142	74	510	495	160	8.7
	DB30-4C	D	420	388	660	628	140	11
	DB37-4C						240	14
	DB45-4C							19
	DB55-4C		425		750	718		21
	DB75-4C	E	550	520	283	240	440	26
	DB110-4C							30
	DB160-4C		750	720				57
	DB200-4C							43
	DB220-4C*		600	570				74

* DB220-4C is a set of two with the above dimensions.

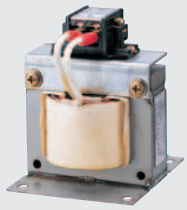
Dynamic Braking Resistor

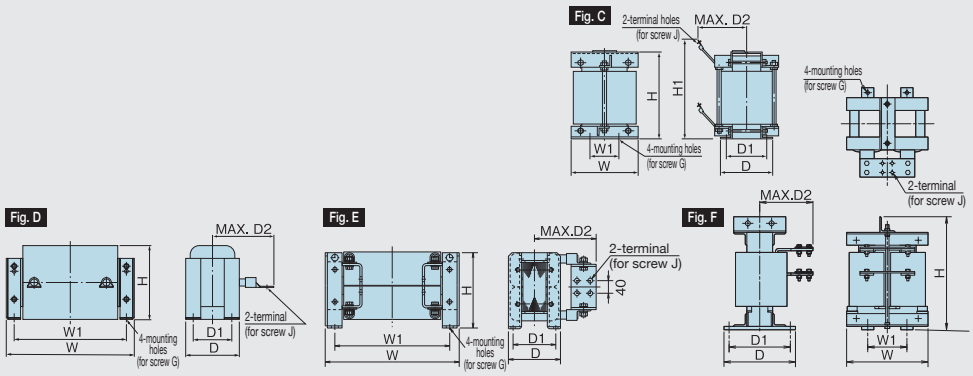
[10%EDSpec.]
[DB□□ -□C]



Voltage	Type	Dimensions [mm]				
		W	W1	H	H1	D
DB0.75-2C/4C	A	43	–	221	215	30.5
DB2.2-2C/4C	B	67	–	188	172	55
DB3.7-2C/4C		67	–	328	312	55
DB5.5-2C/4C		80	–	378	362	78
DB7.5-2C/4C		80	–	418	402	78
DB11-2C/4C	C	80	50	460	440	140
DB15-2C/4C		80	50	580	560	140
DB22-2C/4C	D	180	144	400	383	145

DC Reactor
[DCR□-□□□]



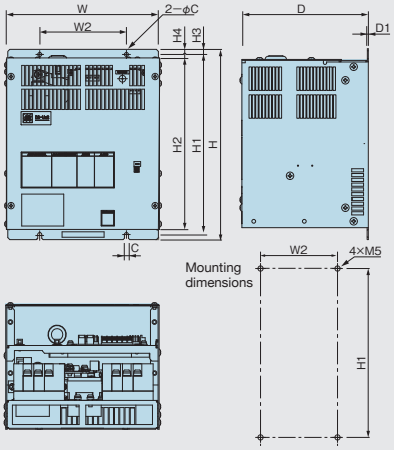


Voltage	Type	Fig	Dimensions [mm]									Approx. weight [kg]
			W	W1	D	D1	D2	G	H	H1	J	
3-phase 200V	DCR2-75C	D	255	225	106	86	145	M6(7×13)	145	–	M12	12
	DCR2-90C		255	225	116	96	155	M6(7×13)	145	–	M12	14
	DCR2-110C		300	265	116	90	185	M8(10×18)	160	–	M12	17
3-phase 400V	DCR4-75C	C	255	225	106	86	125	M6(7×13)	145	–	M10	13
	DCR4-90C		255	225	116	96	140	M6(7×13)	145	–	M12	15
	DCR4-110C		300	265	116	90	175	M8(10×18)	155	–	M12	19
	DCR4-132C		300	265	126	100	180	M8(10×18)	160	–	M12	22
	DCR4-160C		350	310	131	103	180	M10(12×22)	190	–	M12	26
	DCR4-200C		350	310	141	113	185	M10(12×22)	190	–	M12	30
	DCR4-220C		350	310	146	118	200	M10(12×22)	190	–	M12	33
	DCR4-250C		350	310	161	133	210	M10(12×22)	190	–	M12	35
	DCR4-280C		350	310	161	133	210	M10(12×22)	190	–	M16	37
	DCR4-315C		400	345	146	118	200	M10(12×22)	225	–	M16	40
	DCR4-355C	E	400	345	156	128	200	M10(12×22)	225	–	4×M12	49
	DCR4-400C		445	385	145	117	213	M10(12×22)	245	–	4×M12	52
	DCR4-450C		440	385	150	122	215	M10(12×22)	245	–	4×M12	62
	DCR4-500C		445	390	165	137	220	M10(12×22)	245	–	4×M12	72
	DCR4-560C	F	270	145	203	170	195	M12(14×20)	485	–	2×M12	70
	DCR4-630C		285	145	203	170	195	M12(14×20)	480	–	2×M12	75
	DCR4-710C		340	160	295	255	225	M12(Φ15)	480	–	4×M12	95
	DCR4-800B		340	160	295	255	225	M12(Φ15)	480	–	4×M12	95

* The DCR2/4-□□B type is also prepared for motors with 75 kW or larger, which are applicable as standard. Contact us for ordering product separately.
* If using motors with output of 75 kW or higher, be sure to use a DC reactor (option).

DC Reactor Type	Remarks
Input power factor of DCR2/4-□□/□□A/□□B: approx. 90 to 95%	The symbol at the end of the type code varies depending on the capacity.
Input power factor of the DCR2/4-□□C: about 86 to 90%	This can be selected with the inverter of 37kW or more.

Braking unit
[BU□□-□E]



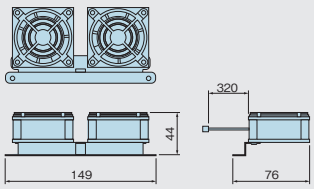
Voltage	Type	Dimensions [mm]											Approx. weight [kg]
		W	W1	W2	W3	H	H1	H2	H3	H4	D	D1	
3-phase 200V	BU90-2E	250	–	150	–	370	355	340	7.5	15	160	2.4	9
3-phase 400V	BU90-4E	230	–	130	–	280	265	250	7.5	15	160	1.2	5.5
	BU132-4E	250	–	150	–	370	355	340				2.4	9
	BU220-4E					450	435	420					13

Fan unit for braking unit

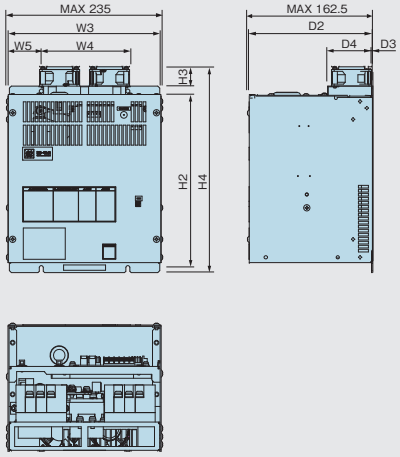
The duty cycle [%ED] of the model with an external braking unit is increased from 10% ED to 30% ED byusing this option.

Fan unit

●BU-F



Braking unit + Fan unit



Voltage	Type	Dimensions [mm]								
		W3	W4	W5	H2	H3	H4	D2	D3	D4
3-phase 200V	BU90-2EF	250	135	57.5	370	30	400	160	1.2	64
3-phase 400V	BU90-4EF	230	135	47.5	280	30	310	160	1.2	64
	BU132-4EF	250		57.5	370		400			
	BU220-4EF	250		57.5	450		480			

Product Warranty

To all our customers who purchase Fuji Electric products included in this catalog:

Please take the following items into consideration when placing your order.

When requesting an estimate and placing your orders for the products included in these materials, please be aware that any items such as specifications which are not specifically mentioned in the contract, catalog, specifications or other materials will be as mentioned below.
In addition, the products included in these materials are limited in the use they are put to and the place where they can be used, etc., and may require periodic inspection. Please confirm these points with your sales representative or directly with this company.
Furthermore, regarding purchased products and delivered products, we request that you take adequate consideration of the necessity of rapid receiving inspections and of product management and maintenance even before receiving your products.

1. Free of Charge Warranty Period and Warranty Range

1-1 Free of charge warranty period

(1) The product warranty period is "1 year from the date of purchase" or 24 months from the manufacturing date imprinted on the name place, whichever date is earlier.
(2) However, in cases where the operating environment, conditions of use, use frequency and times used, etc., have an effect on product life, this warranty period may not apply.
(3) Furthermore, the warranty period for parts restored by Fuji Electric's Service Department is "6 months from the date that repairs are completed."

1-2 Warranty range

(1) In the event that breakdown occurs during the product's warranty period which is the responsibility of Fuji Electric, Fuji Electric will replace or repair the part of the product that has broken down free of charge at the place where the product was purchased or where it was delivered. However, if the following cases are applicable, the terms of this warranty may not apply.

1) The breakdown was caused by inappropriate conditions, environment, handling or use methods, etc. which are not specified in the catalog, operation manual, specifications or other relevant documents.
2) The breakdown was caused by the product other than the purchased or delivered Fuji's product.
3) The breakdown was caused by the product other than Fuji's product, such as the customer's equipment or software design, etc.
4) Concerning the Fuji's programmable products, the breakdown was caused by a program other than a program supplied by this company, or the results from using such a program.
5) The breakdown was caused by modifications or repairs affected by a party other than Fuji Electric.
6) The breakdown was caused by improper maintenance or replacement using consumables, etc. specified in the operation manual or catalog, etc.
7) The breakdown was caused by a chemical or technical problem that was not foreseen when making practical application of the product at the time it was purchased or delivered.
8) The product was not used in the manner the product was originally intended to be used.
9) The breakdown was caused by a reason which is not this company's responsibility, such as lightning or other disaster.

(2) Furthermore, the warranty specified herein shall be limited to the purchased or delivered product alone.
(3) The upper limit for the warranty range shall be as specified in item (1) above and any damages (damage to or loss of machinery or equipment, or lost profits from the same, etc.) consequent to or resulting from breakdown of the purchased or delivered product shall be excluded from coverage by this warranty.

1-3. Trouble diagnosis

As a rule, the customer is requested to carry out a preliminary trouble diagnosis. However, at the customer's request, this company or its service network can perform the trouble diagnosis on a chargeable basis. In this case, the customer is asked to assume the burden for charges levied in accordance with this company's fee schedule.

2. Exclusion of Liability for Loss of Opportunity, etc.

Regardless of whether a breakdown occurs during or after the free of charge warranty period, this company shall not be liable for any loss of opportunity, loss of profits, or damages arising from special circumstances, secondary damages, accident compensation to another company, or damages to products other than this company's products, whether foreseen or not by this company, which this company is not be responsible for causing.

3. Repair Period after Production Stop, Spare Parts Supply Period (Holding Period)

Concerning models (products) which have gone out of production, this company will perform repairs for a period of 7 years after production stop, counting from the month and year when the production stop occurs. In addition, we will continue to supply the spare parts required for repairs for a period of 7 years, counting from the month and year when the production stop occurs. However, it is estimated that the life cycle of certain electronic and other parts is short and it will be difficult to procure or produce those parts, so there may be cases where it is difficult to provide repairs or supply spare parts even within this 7-year period. For details, please confirm at our company's business office or our service office.

4. Transfer Rights

In the case of standard products which do not include settings or adjustments in an application program, the products shall be transported to and transferred to the customer and this company shall not be responsible for local adjustments or trial operation.

5. Service Contents

The cost of purchased and delivered products does not include the cost of dispatching engineers or service costs. Depending on the request, these can be discussed separately.

6. Applicable Scope of Service

Above contents shall be assumed to apply to transactions and use of the country where you purchased the products. Consult the local supplier or Fuji for the detail separately.

NOTES

When running general-purpose motors

- **Driving a 400V general-purpose motor**
  When driving a 400V general-purpose motor with an inverter using extremely long cables, damage to the insulation of the motor may occur. Use an output circuit filter (OFL) if necessary after checking with the motor manufacturer. Fuji's motors do not require the use of output circuit filters because of their reinforced insulation.
- **Torque characteristics and temperature rise**
  When the inverter is used to run a general-purpose motor, the temperature of the motor becomes higher than when it is operated using a commercial power supply. In the low-speed range, the cooling effect will be weakened, so decrease the output torque of the motor. If constant torque is required in the low-speed range, use a Fuji inverter motor or a motor equipped with an externally powered ventilating fan.
- **Vibration**
  When the motor is mounted to a machine, resonance may be caused by the natural frequencies, including that of the machine. Operation of a 2-pole motor at 60Hz or more may cause abnormal vibration.
  * Study use of tier coupling or dampening rubber.
  * It is also recommended to use the inverter jump frequency control to avoid resonance points.
- **Noise**
  When an inverter is used with a general-purpose motor, the motor noise level is higher than that with a commercial power supply. To reduce noise, raise carrier frequency of the inverter. High-speed operation at 60Hz or more can also result in more noise.

When running special motors

- **High-speed motors**
  When driving a high-speed motor while setting the frequency higher than 120Hz, test the combination with another motor to confirm the safety of high-speed motors.
- **Explosion-proof motors**
  When driving an explosion-proof motor with an inverter, use a combination of a motor and an inverter that has been approved in advance.
- **Submersible motors and pumps**
  These motors have a larger rated current than general-purpose motors. Select an inverter whose rated output current is greater than that of the motor.
  These motors differ from general-purpose motors in thermal characteristics. Set a low value in the thermal time constant of the motor when setting the electronic thermal function.
- **Brake motors**
  For motors equipped with parallel-connected brakes, their braking power must be supplied from the primary circuit (commercial power supply). If the brake power is connected to the inverter power output circuit (secondary circuit) by mistake, problems may occur.
  Do not use inverters for driving motors equipped with series-connected brakes.
- **Geared motors**
  If the power transmission mechanism uses an oil-lubricated gearbox or speed changer/reducer, then continuous motor operation at low speed may cause poor lubrication. Avoid such operation.
- **Synchronous motors**
  It is necessary to use software suitable for this motor type. Contact Fuji for details.
- **Single-phase motors**
  Single-phase motors are not suitable for inverter-driven variable speed operation. Use three-phase motors.
  * Even if a single-phase power supply is available, use a three-phase motor as the inverter provides three-phase output.

Environmental conditions

- **Installation location**
  Use the inverter in a location with an ambient temperature range of -10 to 50˚C.
  The inverter and braking resistor surfaces become hot under certain operating conditions. Install the inverter on nonflammable material such as metal.
  Ensure that the installation location meets the environmental conditions specified in "Environment" in inverter specifications.

Combination with peripheral devices

- **Installing a molded case circuit breaker (MCCB)**
  Install a recommended molded case circuit breaker (MCCB) or an earth leakage circuit breaker (ELCB) in the primary circuit of each inverter to protect the wiring. Ensure that the circuit breaker capacity is equivalent to or lower than the recommended capacity.
- **Installing a magnetic contactor (MC) in the output (secondary) circuit**
  If a magnetic contactor (MC) is mounted in the inverter's secondary circuit for switching the motor to commercial power or for any other purpose, ensure that both the inverter and the motor are fully stopped before you turn the MC on or off. Remove the surge killer integrated with the MC.
- **Installing a magnetic contactor (MC) in the input (primary) circuit**
  Do not turn the magnetic contactor (MC) in the primary circuit on or off more than once an hour as an inverter fault may result. If frequent starts or stops are required during motor operation, use FWD/REV signals.
- **Protecting the motor**
  The electronic thermal function of the inverter can protect the motor. The operation level and the motor type (general-purpose motor, inverter motor) should be set. For high-speed motors or water-cooled motors, set a small value for the thermal time constant to protect the motor.
  If you connect the motor thermal relay to the motor with a long cable, a high-frequency current may flow into the wiring stray capacitance. This may cause the relay to trip at a current lower than the set value for the thermal relay. If this happens, lower the carrier frequency or use the output circuit filter (OFL).
- **Regarding power-factor correcting capacitor**
  Do not mount power factor correcting capacitors in the inverter (primary) circuit. Use the DC REACTOR to improve the inverter power factor. Do not use power factor correcting capacitors in the inverter output circuit (secondary). An overcurrent trip will occur, disabling motor operation.
- **Discontinuance of surge killer**
  Do not mount surge killers in the inverter output (secondary) circuit.
- **Reducing noise**
  Use of a filter and shielded wires are typical measures against noise to ensure that EMC Directives are met.
- **Measures against surge currents**
  If an overvoltage trip occurs while the inverter is stopped or operated under a light load, it is assumed that the surge current is generated by open/close of the phase-advancing capacitor in the power system.
  We recommend connecting a DC REACTOR to the inverter.
- **Megger test**
  When checking the insulation resistance of the inverter, use a 500V megger and follow the instructions contained in the Instruction Manual.

Wiring

- **Wiring distance of control circuit**
  When performing remote operation, use twisted shield wire and limit the distance between the inverter and the control box to 20m.
- **Wiring length between inverter and motor**
  If long wiring is used between the inverter and the motor, the inverter will overheat or trip as a result of overcurrent (high-frequency current flowing into the stray capacitance) in the wires connected to the phases. Ensure that the wiring is shorter than 50m. If this length must be exceeded, lower the carrier frequency or mount an output circuit filter (OFL).
- **Wiring size**
  Select cables with a sufficient capacity by referring to the current value or recommended wire size.
- **Wiring type**
  Do not use multicore cables that are normally used for connecting several inverters and motors.
- **Grounding**
  Securely ground the inverter using the grounding terminal.

Selecting inverter capacity

- **Driving general-purpose motor**
  Select an inverter according to the applicable motor ratings listed in the standard specifications table for the inverter. When high starting torque is required or quick acceleration or deceleration is required, select an inverter with a capacity one size greater than the standard.
- **Driving special motors**
  Select an inverter that meets the following condition: Inverter rated current > Motor rated current.

Transportation and storage

When transporting or storing inverters, follow the procedures and select locations that meet the environmental conditions that agree with the inverter specifications.

Fuji Electric

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